Research Article

# Approximate Fixed Point Theorems for the Class of Almost S- $KKM_C$ Mappings in Abstract Convex Uniform Spaces

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We use a concept of abstract convexity to define the almost S- $KKM_C$  property, al-S- $KKM_C(X, Y)$  family, and almost  $\Phi$ -spaces. We get some new approximate fixed point theorems and fixed point theorems in almost  $\Phi$ -spaces. Our results extend some results of other authors.

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### **1. Introduction and Preliminaries**

In 1929, Knaster et al. [1] proved the well-known *KKM* theorem for an *n*-simplex. Ky Fan's generalization of the *KKM* theorem to infinite dimensional topological vector spaces in 1961 [2] proved to be a very versatile tool in modern nonlinear analysis with many far-reaching applications.

Chang and Yen [3] undertook a systematic study of the *KKM* property, and Chang et al. [4] generalized this property as well as the notion of a KKM(X, Y) family of [4] to the wider concepts of the *S*-*KKM* property and its related *S*-*KKM*(*X*, *Y*, *Z*) family.

Among the many contributions in the study of the *KKM* property and related topics, we mention the work by Amini et al. [5] where the classes of *KKM* and *S-KKM* mappings have been introduced in the framework of abstract convex spaces. The authors of [5] also define a concept of convexity that contains a number of other concepts of abstract convexities and obtain fixed point theorems for multifunctions verifying the *S-KKM* property on  $\Phi$ -spaces that extend results of Ben-El-Mechaiekh et al. [6] and Horvath [7], motivated by the works of Ky Fan [2] and Browder [8]. We refer for the study of these notions to Ben-El-Mechaiekh et al. [9], and more recently, to Park [10], and Kim and Park [11].

In this paper, we use a concept of abstract convexity to define the almost S- $KKM_C$  property, the corresponding notion of almost S- $KKM_C(X, Y)$  family as well as the concept of almost  $\Phi$ -spaces.

Let X and Y be two sets, and let  $T : X \to 2^{Y}$  be a set-valued mapping. We will use the following notations in the sequel;

- (i)  $T(x) = \{y \in Y : y \in T(x)\},\$
- (ii)  $T(A) = \bigcup_{x \in A} T(x)$ ,
- (iii)  $T^{-1}(y) = \{x \in X : y \in T(x)\},\$
- (iv)  $T^{-1}(B) = \{x \in X : T(x) \cap B \neq \phi\}$ , and
- (v) if *D* is a nonempty subset of *X*, then  $\langle D \rangle$  denotes the class of all nonempty finite subsets of *D*.

For the case where *X* and *Y* are two topological spaces, a set-valued map  $T : X \to 2^Y$  is said to be closed if its graph  $\mathcal{G}_T = \{(x, y) \in X \times Y : y \in T(x)\}$  is closed. *T* is said to be compact if the image T(X) of *X* under *T* is contained in a compact subset of *Y*.

*Definition 1.1.* An abstract convex space (E, C) consists of a nonempty topological space E, and a family C of subsets of E such that E and  $\emptyset$  belong to C and C is closed under arbitrary intersection. This kind of abstract convexity was widely studied; see [5, 9, 12, 13].

Suppose that *A* is a nonempty subset of an abstract convex space (E, C). Then

(i) a natural definition of *C*-convex hull of *A* is

$$co_{\mathcal{C}}(A) = \cap \{B \in \mathcal{C} : A \subset B\}, \text{and}$$

$$(1.1)$$

(ii) we say that *A* is *C*-convex if for each  $B \in \langle A \rangle$ ,  $co_{\mathcal{C}}(B) \subset A$ .

*Remark* 1.2. It is clear that if  $A \in C$ , then A is C-convex. That is, each member of C is C-convex.

*Definition 1.3.* We list some properties of a uniform space. A uniformity [14] for a set *E* is a nonempty family  $\mathcal{U}$  of subsets of  $E \times E$  such that

- (i) each member of  $\mathcal{U}$  contains the diagonal  $\Delta$  where the diagonal  $\Delta$  denotes the set of all pairs (*x*, *x*) for *x* in *E*;
- (ii) if  $U \in \mathcal{U}$ , then  $U^{-1} \in \mathcal{U}$ ;
- (iii) if  $U \in \mathcal{U}$ , then  $V \circ V \subset U$  for some  $V \in \mathcal{U}$ ;
- (iv) if  $U, V \in \mathcal{U}$ , then  $U \cap V \in \mathcal{U}$ ;
- (v) if  $U \in \mathcal{U}$  and  $U \subset V \subset E \times E$ , then  $V \in \mathcal{U}$ .

The pair (E, C) is called a uniform space. Every member V in  $\mathcal{U}$  is called an entourage. An entourage is said to be symmetric if  $(x, y) \in V$  whenever  $(y, x) \in V$ .

*Definition* 1.4. If (E, C) is an abstract convex space with a uniformity  $\mathcal{U}$ , then we say that (E, C) is an abstract convex uniform space.

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*Definition* 1.5. Let *A* be a nonempty subset of an abstract convex uniform space (E, C) which has a uniformity  $\mathcal{U}$ , and  $\mathcal{U}$  has a symmetric basis  $\mathcal{N}$ . Then *A* is called almost *C*-convex if, for any  $K \in \langle A \rangle$  and for any  $V \in \mathcal{N}$ , there exists a mapping  $h_{K,V} : K \to A$  such that  $h_{K,V}(x) \in V[x]$  for all  $x \in K$  and  $co_{\mathcal{C}}(h_{K,V}(K)) \subset A$ . Moreover, we call the mapping  $h_{K,V} : K \to A$  a *C*-convex-inducing mapping.

*Remark* 1.6. It is clear that every *C*-convex set must be almost *C*-convex, but the converse is not true. And in general, the *C*-convex-inducing mapping is not unique. If  $U, V \in \mathcal{N}$  and  $U \subset V$ , then  $h_{A,U} : A \to X$  can be regarded as  $h_{A,V} : A \to X$ . If  $A \subset B$ , then  $h_{A,U} : A \to X$  can be regarded as  $h_{B,U} : B \to X$ .

Recently, Amini et al. [5] introduced the class of multifunctions with the  $S - KKM_C$  property in abstract convex spaces.

*Definition 1.7* (see [5]). Let *Z* be a nonempty set, (X, C) an abstract convex space, and *Y* a topological space. If  $S : Z \to 2^X$ ,  $T : X \to 2^Y$  and  $F : Z \to 2^Y$  are three multifunctions satisfying

$$T(co_{\mathcal{C}}(S(A))) \subset \bigcup_{x \in A} F(x), \quad \text{for each } A \in \langle Z \rangle, \tag{1.2}$$

then *F* is called a *S*-*K*K*M*<sub>*C*</sub> mapping with respect to *T*. If the multifunction  $T : X \to 2^Y$  satisfies the requirement that for any *S*-*K*K*M*<sub>*C*</sub> mapping *F* with respect to *T*, the family  $\{\overline{F(x)} : x \in Z\}$  has the finite intersection property where  $\overline{F(x)}$  denotes the closure of F(x), then *T* is said to have the *S*-*K*K*M*<sub>*C*</sub> property with respect to *C*. We define

$$S - KKM_{\mathcal{C}}(Z, X, Y) := \left\{ T : W \to 2^{Y} \mid T \text{ has the } S - KKM_{\mathcal{C}} \text{ property with respect to } \mathcal{C} \right\}.$$
(1.3)

We extended the  $S - KKM_{C}$  property to the almost  $S - KKM_{C}$  property, as follows.

*Definition 1.8.* Let *Z* be a nonempty set, let *X* be an almost *C*-convex subset of an abstract convex uniform space (E, C) which has a uniformity  $\mathcal{U}$  and  $\mathcal{U}$  has a symmetric basis  $\mathcal{N}$ , and let *Y* be a topological space. If  $S : Z \to 2^X$ ,  $T : X \to 2^Y$  and  $F : Z \to 2^Y$  are three multifunctions satisfying for each  $A \in \langle Z \rangle$ , each  $B \in \langle S(A) \rangle$ , and each  $U \in \mathcal{N}$ , there exists a *C*-convex-inducing mapping  $h_{B,U} : B \to W$  such that

$$T(co_{\mathcal{C}}(h_{B,U}(B))) \subset F(A), \tag{1.4}$$

then *F* is called an almost *S*-*KKM*<sub>*C*</sub> mapping with respect to *T*. If the multifunction  $T : X \rightarrow 2^{Y}$  satisfies the requirement that for any almost *S*-*KKM*<sub>*C*</sub> mapping *F* with respect to *T*, the family { $\overline{F(x)} : x \in Z$ } has the finite intersection property, then *T* is said to have the almost *S*-*KKM*<sub>*C*</sub> property with respect to *C*. We define

$$al - S - KKM_{\mathcal{C}}(Z, X, Y)$$
  
:=  $\{T : W \to 2^{Y} | T \text{ has the almost } S - KKM_{\mathcal{C}} \text{ property with respect to } \mathcal{C}\}.$  (1.5)

From the above definitions, we have the following proposition of the  $al - S - KKM_{\mathcal{C}}(Z, X, Y)$  family.

**Proposition 1.9.** Let X be a nonempty set, let Y be an almost C-convex subset of an abstract convex uniform space (E, C), let Z and W be two topological spaces, and let  $S : X \to 2^Y$  be a multifunction. If  $T \in al-S-KKM_C(X, Y, Z)$  and if  $f : Z \to W$  is continuous, then  $fT \in al-S-KKM_C(X, Y, W)$ .

The  $\Phi$ -mappings and the  $\Phi$ -spaces, in an abstract convex space setting, were also introduced by Amini et al. [5].

*Definition 1.10* (see [5]). Let (X, C) be an abstract convex space, and Y a topological space. A map  $T: Y \to 2^X$  is called a  $\Phi$ -mapping if there exists a multifunction  $F: Y \to 2^X$  such that

- (i) for each  $y \in Y$ ,  $A \in \langle F(y) \rangle$  implies  $co_{\mathcal{C}}(A) \subset T(y)$ , and
- (ii)  $\Upsilon = \bigcup_{x \in X} \operatorname{int} F^{-1}(x)$ .

The mapping *F* is called a companion mapping of *T*.

Furthermore, if the abstract convex space (X, C) which has a uniformity  $\mathcal{U}$  and  $\mathcal{U}$  has a symmetric basis  $\mathcal{N}$ , then X is called a  $\Phi$ -space if for each entourage  $V \in \mathcal{N}$ , there exists a  $\Phi$ -mapping  $T : X \to 2^X$  such that  $\mathcal{C}_T \subset V$ .

*Remark 1.11.* (i) If  $T : Y \to 2^X$  is a  $\Phi$ -mapping, then for each nonempty subset  $Y_1$  of Y,  $T|_{Y_1} : Y_1 \to X$  is also a  $\Phi$ -mapping.

(ii) It is easy to see that if  $X_1 \subset X$  and  $C_1 = \{C \cap X_1 : C \in C\}$ , then  $(X_1, C_1)$  is also a  $\Phi$ -space.

In order to establish the main result of this paper for the multifunctions with the almost  $S - KKM_{C}$  property, we need the following definitions concerning the almost  $\Phi$ -mappings and the almost  $\Phi$ -spaces.

*Definition* 1.12. Let *X* be an almost *C*-convex subset of an abstract convex uniform space (E, C) which has a uniformity  $\mathcal{U}$  and  $\mathcal{U}$  has a symmetric base family  $\mathcal{N}$ , and Y a topological space. A map  $T : Y \to 2^X$  is called an almost  $\Phi$ -mapping if there exists a multifunction  $F : Y \to 2^X$  such that

- (i) for each  $y \in Y$ ,  $A \in \langle F(y) \rangle$  and  $U \in \mathcal{N}$ , there exists a *C*-convex-inducing  $h_{A,U}$ :  $A \to X$  such that  $co_{\mathcal{C}}(h_{A,U}(A)) \subset U[T(y)]$ , and
- (ii)  $\Upsilon = \bigcup_{x \in X} \operatorname{int} F^{-1}(x)$ .

The mapping *F* is called an almost companion mapping of *T*.

Furthermore, *X* is called an almost  $\Phi$ -space, if, for each entourage  $V \in \mathcal{N}$ , there exists an almost  $\Phi$ -mapping  $T : X \to 2^X$  such that  $\mathcal{G}_T \subset V$ .

*Definition 1.13.* Let *X* be an almost  $\Phi$ -space, and let  $T : X \to 2^X$ . We say that *T* has the approximate fixed point property if, for each  $U \in \mathcal{N}$ , there exists  $x \in X$  such that  $U[x] \cap T(x) \neq \phi$ .

#### 2. Main Results

Using the above introduced concepts and definitions, we now state our main theorem.

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**Theorem 2.1.** Let X be an almost  $\Phi$ -space, and let  $s : X \to X$  be a surjective single-valued function. If  $T \in al - s - KKM_{\mathcal{C}}(X, X, X)$  is compact, then T has the approximate fixed point property.

*Proof.* Let  $\mathcal{N}$  be a symmetric basis of the uniform structure, and let  $U \in \mathcal{N}$ . Take  $V \in \mathcal{N}$  such that  $V \circ V \subset U$ . Then, by the definition of the almost  $\Phi$ -space, there exists an almost  $\Phi$ -mapping  $F : X \to 2^X$  such that  $\mathcal{G}_F \subset V$ . Since F is an almost  $\Phi$ -mapping, there exists an almost companion mapping  $G : X \to 2^X$  such that  $X = \bigcup_{x \in X} \operatorname{int} G^{-1}(x)$ .

Let  $K = \overline{T(X)}$ . Then K is compact, since T is compact. Hence there exists  $A \in \langle X \rangle$  such that  $K \subset \bigcup_{x \in A}$  int  $G^{-1}(x)$ . Since s is surjective, there exists a finite subset B of X such that  $K \subset \bigcup_{z \in B}$  int  $G^{-1}(s(z))$ .

Now, we define  $P: X \to 2^X$  by

$$P(z) = K \setminus \inf G^{-1}(s(z)), \text{ for each } z \in X.$$

$$(2.1)$$

By the definition of P, we obtain that P is not an almost  $s - KKM_C$  mapping with respect to T. Hence, there exist  $N = \{z_1, z_2, ..., z_k\} \subset X$  and  $D \in \langle s(N) \rangle$  such that for any C-convex-inducing  $h_{D,V} : D \to W_{\infty}$ , we have

$$T(co_{\mathcal{C}}(h_{D,V}(D))) \not\subseteq \bigcup_{i=1}^{k} P(z_i).$$

$$(2.2)$$

So, for any *C*-convex-inducing  $h_{D,V} : D \to X$ , there exist  $x_U \in co_C(h_{D,V}(D))$  and  $y_U \in T(x_U)$  such that  $y_U \notin \bigcup_{i=1}^k P(z_i)$ . Consequently,  $y_U \in \bigcap_{i=1}^k \text{int } G^{-1}(s(z_i))$ , and so  $s(z_i) \in G(y_U)$  for all i = 1, 2, ..., k. Since *F* is an almost  $\Phi$ -mapping, there exists a *C*-convex-inducing  $h_{D,V}^* : D \to X$  such that  $co_C(h_{D,V}^*(D)) \subset V[F(y_U)]$ . So  $x_U \in ad_C(h_{D,V}^*(D))$  and  $x_U \in V[F(y_U)]$ . Thus, there exists  $z_U \in F(y_U)$  such that  $x_U \in V[z_U]$ . Since *X* is an almost  $\Phi$ -space, we have  $(y_U, z_U) \in \mathcal{G}_F \subset V$ , and so  $(y_U, x_U) = (y_U, z_U) \circ (z_U, x_U) \in V \circ V \subset U$ , that is,  $y_U \in U[x_U]$ . Therefore,  $y_U \in U[x_U] \cap T(x_U)$ . The proof is finished.

*Remark* 2.2. In the case, if X is a  $\Phi$ -space and  $T \in s - KKM_C(X, X, X)$ , then the above theorem reduces to Amini et al. [5, Theorem 2.5]

From Theorem 2.1 above, we obtain immediately the following fixed point theorem.

**Theorem 2.3.** Suppose that all of the assumptions of Theorem 2.1 hold. If T is closed, then T has a fixed point in X.

*Proof.* By Theorem 2.1, for each  $U \in \mathcal{N}$ , there exist  $x_U, y_U \in X$  such that  $y_U \in U[x_U] \cap T(x_U)$ . Since *T* is compact, without loss of generality, we may assume that  $y_U$  converges to some  $\overline{y}$  in *X*; then  $x_U$  also converges to  $\overline{y}$  since *X* is a Hausdorff uniform space and  $(x_U, y_U) \in U$  for each  $U \in \mathcal{N}$ . By the closedness of *T*, we have that  $\overline{y} \in T(\overline{y})$ .

**Corollary 2.4.** Let X be an almost  $\Phi$ -space, and let  $s : X \to X$  be a surjective single-valued function. Suppose  $T \in al-s-KKM_C(X, X, X)$  such that  $\overline{T(X)}$  is totally bounded. Then T has the approximate fixed point property.

**Corollary 2.5.** *Suppose that all of the assumptions of the above Corollary 2.5 hold. If T is closed, then T has a fixed point in X.* 

In case *X* is an almost convex subset of Hausdorff topological vector spaces and for each  $A \subset X$ , we have

(i) 
$$co_{\mathcal{C}}(A) = co(A)$$
, and

(ii) 
$$al - s - KKM_{\mathcal{C}}(X, X, X) = al - s - KKM(X, X, X).$$

This allows us to state the following results.

**Theorem 2.6.** Let *E* be a Hausdorff locally convex space, let *X* be an almost convex subset of *E*, and let  $s : X \to X$  be a surjective function. Assume that  $T \in al - s - KKM(X, X, X)$  is compact and closed, then *T* has a fixed point in *X*.

*Proof.* Let C be the family of all convex subsets of E, and let  $\mathcal{B}_0 = \{\overline{V}_\alpha : \alpha \in \Lambda\}$  be a local basis of E such that each  $\overline{V}_\alpha \in \mathcal{B}_0$  is symmetric and convex for each  $\alpha \in \Lambda$ . For each  $x \in X$ , we set  $V_\alpha[x] = x + \overline{V}_\alpha$ . Noting that  $x \in V_\alpha[x]$ . Set

$$\mathcal{M} = \{ V_{\alpha} \mid V_{\alpha} = \bigcup_{x \in X} \{ (x, y) : y \in V_{\alpha}[x] \}, \ \alpha \in \Lambda \}.$$

$$(2.3)$$

Then  $\mathcal{N}$  is a basis of a uniformity of E. For each  $V_{\beta} \in \mathcal{N}$ ,  $\beta \in \Lambda$ , we define the two set-valued mappings  $G, F : X \to 2^X$  by  $G(x) = F(x) = V_{\beta}[x]$  for each  $x \in X$ . Then we have

(i) for each 
$$x \in X$$
,  $co(G(x)) = co(V_{\beta}[x]) \subset V_{\beta}[V_{\beta}[x]] = V_{\beta}[F(x)]$ , and

(ii) 
$$X = \bigcup_{x \in X} \inf G^{-1}(x)$$
.

So, *G* is an almost companion mapping of *F*. This implies that *F* is an almost  $\Phi$ -mapping such that  $\mathcal{G}_F \subset V_\beta$ . Therefore, *X* is an almost  $\Phi$ -space.

All conditions of Theorems 2.1 and 2.3 are therefore fulfilled; the result follows from an argument similar to those in the proofs of Theorems 2.1 and 2.3.  $\hfill \Box$ 

**Theorem 2.7.** Let *E* be a topological vector space, let *X* be an almost convex subset of *E*, and let  $s : X \to X$  be a surjective function. Suppose that  $T \in al - s - KKM(X, X, X)$  is compact, then for any symmetric convex neighborhood  $\overline{V}$  of 0 in *E*, there is  $x_V \in X$  such that  $(x_V + \overline{V}) \cap T(x_V) \neq \phi$ .

*Proof.* Let C be the family of all convex subsets of E, and let  $\mathcal{B}_0 = \{a\overline{V} : a > 0\}$  be a new local basis of E. We will use  $\mathcal{B}_0$  to construct a weaker topology on E such that E becomes a new topological vector space. For each  $x \in X$ , we set  $V_a[x] = x + a\overline{V}$ . Noting that  $x \in V_a[x]$ . Set

$$\mathcal{N} = \{ V_a \mid V_a = \bigcup_{x \in X} \{ (x, y) : y \in V_a[x] \}, \ a > 0 \}.$$
(2.4)

Then  $\mathcal{N}$  is a basis of a uniformity of *E*. In vein of the reasonings similar to those of Theorems 2.1 and 2.6, we complete the proof.

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