

## Research Article

# Existence Principle for Advanced Integral Equations on Semiline

Adela Chiş

Received 18 May 2007; Accepted 16 July 2007

Recommended by Andrzej Szulkin

The continuation principle for generalized contractions in gauge spaces is used to discuss nonlinear integral equations with advanced argument.

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## 1. Introduction

This paper deals with an integral equation with advanced argument. The advanced argument makes necessary the use of two pseudometrics in the contraction condition. For this reason we will apply the continuation principle established in Chiş and Precup [1] involving contractions in Gheorghiu's sense, with respect to a family of pseudometrics rather than the existence principle from Frigon [2, 3].

In what follows we recall some notions and results from papers Chiş and Precup [1] and Chiş [4].

First recall the notion of a contraction on a gauge space introduced by Gheorghiu [5].

*Definition 1.1* (Gheorghiu [5]). Let  $(X, \mathcal{P})$  be a gauge space with the family of pseudometrics  $\mathcal{P} = \{p_\alpha\}_{\alpha \in A}$ , where  $A$  is a set of indices. A map  $F : D \subset X \rightarrow X$  is a *contraction* if there exists a function  $\varphi : A \rightarrow A$  and  $a \in \mathbb{R}_+^A, a = \{a_\alpha\}_{\alpha \in A}$  such that

$$\begin{aligned} p_\alpha(F(x), F(y)) &\leq a_\alpha p_{\varphi(\alpha)}(x, y), \quad \forall \alpha \in A, x, y \in D, \\ \sum_{n=1}^{\infty} a_\alpha a_{\varphi(\alpha)} a_{\varphi^2(\alpha)} \cdots a_{\varphi^{n-1}(\alpha)} p_{\varphi^n(\alpha)}(x, y) &< \infty, \end{aligned} \tag{1.1}$$

for every  $\alpha \in A$  and  $x, y \in D$ . Here,  $\varphi^n$  is the  $n$ th iteration of  $\varphi$ .

## 2 Fixed Point Theory and Applications

**THEOREM 1.2** (Chiş [4]). *Let  $X$  be a set endowed with two separating gauge structures:  $\mathcal{P} = \{p_\alpha\}_{\alpha \in A}$  and  $\mathcal{Q} = \{q_\beta\}_{\beta \in B}$ , let  $D_0$  and  $D$  be two subsets of  $X$  with  $D_0 \subset D$ , and let  $F : D \rightarrow X$  be a map. Assume that  $F(D_0) \subset D_0$  and  $D$  is  $\mathcal{P}$ -closed. In addition, assume that the following conditions are satisfied:*

(i) *there is a function  $\psi : A \rightarrow B$  and  $c \in (0, \infty)^A$ ,  $c = \{c_\alpha\}_{\alpha \in A}$  such that*

$$p_\alpha(x, y) \leq c_\alpha q_{\psi(\alpha)}(x, y), \quad \forall \alpha \in A, x, y \in X; \quad (1.2)$$

(ii)  *$(X, \mathcal{P})$  is a sequentially complete gauge space;*

(iii) *if  $x_0 \in D$ ,  $x_n = F(x_{n-1})$ , for  $n = 1, 2, \dots$ , and  $\mathcal{P} - \lim_{n \rightarrow \infty} x_n = x$  for some  $x \in D$ , then  $F(x) = x$ ;*

(iv)  *$F$  is a  $\mathcal{Q}$ -contraction on  $D_0$ .*

*Then  $F$  has at least one fixed point which can be obtained by successive approximations starting from any element of  $D_0$ .*

For a map  $H : D \times [0, 1] \rightarrow X$ , where  $D \subset X$ , we will use the following notations:

$$\begin{aligned} \Sigma &= \{(x, \lambda) \in D \times [0, 1] : H(x, \lambda) = x\}, \\ S &= \{x \in D : H(x, \lambda) = x, \text{ for some } \lambda \in [0, 1]\}, \\ \Lambda &= \{\lambda \in [0, 1] : H(x, \lambda) = x, \text{ for some } x \in D\}. \end{aligned} \quad (1.3)$$

**THEOREM 1.3** (Chiş and Precup [1]). *Let  $X$  be a set endowed with the separating gauge structures  $\mathcal{P} = \{p_\alpha\}_{\alpha \in A}$  and  $\mathcal{Q}^\lambda = \{q_\beta^\lambda\}_{\beta \in B}$ , for  $\lambda \in [0, 1]$ . Let  $D \subset X$  be  $\mathcal{P}$ -sequentially closed,  $H : D \times [0, 1] \rightarrow X$  a map, and assume that the following conditions are satisfied:*

(i) *for each  $\lambda \in [0, 1]$ , there exists a function  $\varphi_\lambda : B \rightarrow B$  and  $a^\lambda \in [0, 1]^B$ ,  $a^\lambda = \{a_\beta^\lambda\}_{\beta \in B}$  such that*

$$\begin{aligned} q_\beta^\lambda(H(x, \lambda), H(y, \lambda)) &\leq a_\beta^\lambda q_{\varphi_\lambda(\beta)}^\lambda(x, y), \\ \sum_{n=1}^{\infty} a_\beta^\lambda a_{\varphi_\lambda(\beta)}^\lambda a_{\varphi_\lambda^2(\beta)}^\lambda \cdots a_{\varphi_\lambda^{n-1}(\beta)}^\lambda &< \infty, \end{aligned} \quad (1.4)$$

*for every  $\beta \in B$  and  $x, y \in D$ ;*

(ii) *there exists  $\rho > 0$  such that for each  $(x, \lambda) \in \Sigma$ , there is a  $\beta \in B$  with*

$$\inf \{q_\beta^\lambda(x, y) : y \in X \setminus D\} > \rho; \quad (1.5)$$

(iii) *for each  $\lambda \in [0, 1]$ , there is a function  $\psi : A \rightarrow B$  and  $c \in (0, \infty)^A$ ,  $c = \{c_\alpha\}_{\alpha \in A}$  such that*

$$p_\alpha(x, y) \leq c_\alpha q_{\psi(\alpha)}^\lambda(x, y), \quad \forall \alpha \in A, x, y \in X; \quad (1.6)$$

(iv)  *$(X, \mathcal{P})$  is a sequentially complete gauge space;*

(v) *if  $\lambda \in [0, 1]$ ,  $x_0 \in D$ ,  $x_n = H(x_{n-1}, \lambda)$ , for  $n = 1, 2, \dots$ , and  $\mathcal{P} - \lim_{n \rightarrow \infty} x_n = x$ , then  $H(x, \lambda) = x$ ;*

(vi) for every  $\varepsilon > 0$ , there exists  $\delta = \delta(\varepsilon) > 0$  with

$$q_{\varphi_n^r(\beta)}^\lambda(x, H(x, \lambda)) \leq (1 - a_{\varphi_n^r(\beta)}^\lambda) \varepsilon, \quad (1.7)$$

for  $(x, \mu) \in \Sigma$ ,  $|\lambda - \mu| \leq \delta$ , all  $\beta \in B$ , and  $n \in \mathbb{N}$ .

In addition, assume that  $H_0 := H(\cdot, 0)$  has a fixed point. Then, for each  $\lambda \in [0, 1]$ , the map  $H_\lambda := H(\cdot, \lambda)$  has at least a fixed point.

## 2. The main result

We consider the integral equation inspired from biomathematics (see O'Regan and Precup [6]):

$$x(t) = \int_{t-1}^t f(s, x(s+2)), \quad t \in [0, \infty). \quad (2.1)$$

Let  $I = [-1, \infty)$  and for a function  $u \in L^1(a, b)$  we denote by  $\|u\|_{L^1(a,b)}$  the norm in  $L^1(a, b)$ . We have the following existence principle for (2.1).

**THEOREM 2.1.** *Let  $(E, \|\cdot\|)$  be a Banach space, and let  $f : I \times E \rightarrow E$  be a continuous function. Assume that the following conditions hold:*

(a) *there exists  $k : I \rightarrow (0, \infty)$ ,  $k \in L^1_{\text{loc}}(I)$  with  $\|k\|_{L^1_{\text{loc}}(I)} < 1$  such that*

$$\|f(t, x) - f(t, y)\| \leq k(t)|x - y| \quad (2.2)$$

*for all  $x, y \in E$ , and  $t \in I$ ;*

(b) *for each  $n \in \mathbb{N}$  there exists  $r_n > 0$  such that, any continuous solution  $x$  of the equation*

$$x(t) = \lambda \left( \int_{t-1}^t f(s, x(s+1)) ds \right), \quad t \in [0, \infty) \quad (2.3)$$

*with  $\lambda \in [0, 1]$ , satisfies  $\|x(t)\| \leq r_n$  for any  $t \in [n, 2n+1]$ ;*

(c) *there exists  $\alpha \in L^1_{\text{loc}}(I)$  şi  $\beta : [0, \infty) \rightarrow (0, \infty)$  nondecreasing such that*

$$\|f(t, x)\| \leq \alpha(t)\beta(\|x\|) \quad (2.4)$$

*for all  $t \in I$  and  $x \in E$ ;*

(d) *there exists  $C > 0$  such that  $\beta(r_{k+1})/(1 - L_k) \leq C$  for any  $k \in \mathbb{N}$ , where  $L_n = \int_{n-1}^{2n+1} k(s) ds$ .*

*Then there exists at least one solution  $x \in C(\mathbb{R}_+, E)$  of the integral equation (2.1).*

*Proof.* For the proof we use Theorem 1.3. Let  $X = C(\mathbb{R}_+, E)$ . For each  $n \in \mathbb{N}$  we define the map  $|\cdot|_n : X \rightarrow \mathbb{R}_+$  by  $|x|_n = \max_{t \in [n, 2n+1]} \|x(t)\|$ . This map is a seminorm on  $X$ , and let  $d_n : X \times X \rightarrow \mathbb{R}_+$  be given by

$$d_n(x, y) = |x - y|_n = \max_{t \in [n, 2n+1]} \|x(t) - y(t)\|. \quad (2.5)$$

#### 4 Fixed Point Theory and Applications

It is easy to show that  $d_n$  is a pseudometric on  $X$  and the family  $\{d_n\}_{n \in \mathbb{N}}$  defines on  $X$  a gauge structure, separated and complete by sequences.

Here  $\mathcal{P} = \mathcal{Q}^\lambda = \{d_n\}_{n \in \mathbb{N}}$  for each  $\lambda \in [0, 1]$ . Let  $D$  be the closure in  $X$  of the set

$$\{x \in X : \text{there exists } n \in \mathbb{N} \text{ such that } d_n(x, 0) \leq r_n + \delta\}, \quad (2.6)$$

where  $\delta > 0$  is a fixed number. We define  $H : D \times [0, 1] \rightarrow X$  by  $H(x, \lambda) = \lambda A(x)$ , where

$$A(x)(t) = \int_{t-1}^t f(s, x(s+2)) ds. \quad (2.7)$$

First, we verify condition (i) from Theorem 1.3.

Let  $t \in [n, 2n+1]$ , where  $n \geq 0$ . We have

$$\begin{aligned} \|H(x, \lambda)(t) - H(y, \lambda)(t)\| &\leq \lambda \int_{t-1}^t \|f(s, x(s+2)) - f(s, y(s+2))\| ds \\ &\leq \int_{n-1}^{2n+1} k(s) \|x(s+2) - y(s+2)\| ds \\ &\leq \max_{s \in [n-1, 2n+1]} \|x(s+2) - y(s+2)\| \int_{n-1}^{2n+1} k(s) ds \\ &\leq \max_{\tau \in [n+1, 2n+3]} \|x(\tau) - y(\tau)\| \int_{n-1}^{2n+1} k(s) ds \\ &= L_n d_{n+1}(x, y). \end{aligned} \quad (2.8)$$

If we take the maximum with respect to  $t$ , we obtain

$$d_n(H(x, \lambda), H(y, \lambda)) \leq L_n d_{n+1}(x, y) \quad (2.9)$$

for all  $x, y \in D$  and all  $n \in \mathbb{N}$ . Hence, condition (i) in Theorem 1.3 holds with  $\varphi_\lambda = \varphi$  where  $\varphi : \mathbb{N} \rightarrow \mathbb{N}$  is defined by  $\varphi(n) = n+1$ . In addition, the series  $\sum_{n=1}^{\infty} L_n L_{n+1} \cdots L_{2n}$  is finite since from assumption (a) we know that  $|k|_{L^1_{\text{loc}}(I)} < 1$  so  $L_n \leq |k|_{L^1_{\text{loc}}(I)} < 1$ .

Condition (ii) in our case becomes: there exists  $\rho > 0$  such that for any solution  $(x, \lambda) \in D \times [0, 1]$ , to  $x = H(x, \lambda)$ , there exists  $n \in \mathbb{N}$  with

$$\inf \{d_n(x, y) : y \in X \setminus D\} > \rho. \quad (2.10)$$

If  $y \in X \setminus D$ , we have that  $d_n(y, 0) > r_n + \delta$  for each  $n \in \mathbb{N}$ . So there exists at least one  $t \in [n, 2n+1]$  with

$$\|x(t) - y(t)\| \geq \|y(t)\| - \|x(t)\| > r_n + \delta - r_n = \delta. \quad (2.11)$$

Hence  $d_n(x, y) > \delta$  and (2.10) holds for any  $\rho \in (0, \delta)$ .

Condition (iii) in Theorem 1.3 is trivial since  $\mathcal{P} = \mathcal{Q}^\lambda$  for any  $\lambda \in [0, 1]$ .

Condition (iv) in Theorem 1.3 becomes:  $(X, \{d_n\}_{n \in \mathbb{N}})$  is a gauge space sequentially complete because  $E$  is a Banach space.

Condition (v): Let  $\lambda \in [0, 1]$ ,  $x_0 \in D$ ,  $x_n = H(x_{n-1}, \lambda)$  for  $n = 1, 2, \dots$ , and assume  $\mathcal{P} - \lim_{n \rightarrow \infty} x_n = x$ . We will prove that  $H(x, \lambda) = x$ .

Let  $m \in \mathbb{N}$  and  $t \in [m, 2m + 1]$ . We have

$$\begin{aligned}
\|H(x, \lambda)(t) - x(t)\| &= \|H(x, \lambda)(t) - x_n(t) + x_n(t) - x(t)\| \\
&\leq \|H(x, \lambda)(t) - x_n(t)\| + \|x_n(t) - x(t)\| \\
&= \|H(x, \lambda)(t) - H(x_{n-1}, \lambda)(t)\| + \|x_n(t) - x(t)\| \\
&\leq \int_{t-1}^t k(s) \|x(s+2) - x_{n-1}(s+2)\| ds + \max_{t \in [m, 2m+1]} \|x_n(t) - x(t)\| \\
&\leq L_m \max_{s \in [m-1, 2m+1]} \|x(s+2) - x_{n-1}(s+2)\| + d_m(x_n, x) \\
&= L_m \max_{\tau \in [m+1, 2m+3]} \|x(\tau) - x_{n-1}(\tau)\| + d_m(x_n, x) \\
&= L_m d_{m+1}(x, x_{n-1}) + d_m(x_n, x).
\end{aligned} \tag{2.12}$$

Consequently, passing to maximum after  $t \in [m, 2m + 1]$  we have

$$d_m(H(x, \lambda), x) \leq L_m d_{m+1}(x, x_{n-1}) + d_m(x_n, x) \tag{2.13}$$

for all  $m \in \mathbb{N}$ . Letting  $n \rightarrow \infty$ , we deduce that  $d_m(H(x, \lambda), x) = 0$  for each  $m \in \mathbb{N}$  and since the family  $\{d_m\}_{m \in \mathbb{N}}$  is separated, we have  $H(x, \lambda) = x$ .

Condition (vi) becomes: for each  $\varepsilon > 0$ , there exists  $\delta = \delta(\varepsilon) > 0$  such that

$$d_{\varphi^n(m)}(x, H(x, \lambda)) \leq (1 - L_{\varphi^n(m)}) \varepsilon \tag{2.14}$$

for each  $(x, \mu) \in D \times [0, 1]$ ,  $H(x, \mu) = x$ ,  $|\lambda - \mu| \leq \delta$ , and  $n, m \in \mathbb{N}$ .

We have  $\varphi^n(m) = n + m$ . Let  $t \in [n + m, 2(n + m) + 1]$ , and using conditions (c) and (d) we obtain

$$\begin{aligned}
\|x(t) - H(x, \lambda)(t)\| &= \|H(x, \mu)(t) - H(x, \lambda)(t)\| \\
&= |\mu - \lambda| \left\| \int_{t-1}^t f(s, x(s+2)) ds \right\| \\
&\leq |\mu - \lambda| \int_{t-1}^t \alpha(s) \beta(\|x(s+2)\|) ds \\
&\leq |\mu - \lambda| \beta(r_{m+n+1}) \int_{n+m-1}^{2(n+m)+1} \alpha(s) ds \\
&\leq |\mu - \lambda| |\alpha|_{L^1_{loc}(I)} C (1 - L_{m+n}).
\end{aligned} \tag{2.15}$$

So condition (vi) is true with  $\delta(\varepsilon) = \varepsilon/C |\alpha|_{L^1_{loc}(I)}$ .

In addition,  $H(\cdot, 0) = 0$ . So  $H(\cdot, 0)$  has a fixed point.

Therefore, all the assumptions of Theorem 1.3 are satisfied. Now the conclusion follows from Theorem 1.3.  $\square$

Other existence results for integral and differential equations established by the continuation method (see O'Regan and Precup [6]) are given in Chiş [4, 7].

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Adela Chiş: Department of Mathematics, Technical University of Cluj-Napoca,  
400020 Cluj-Napoca, Romania  
Email address: adela.chis@math.utcluj.ro