

Research Article

Hybrid Proximal-Type Algorithms for Generalized Equilibrium Problems, Maximal Monotone Operators, and Relatively Nonexpansive Mappings

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The purpose of this paper is to introduce and consider new hybrid proximal-type algorithms for finding a common element of the set EP of solutions of a generalized equilibrium problem, the set $F(S)$ of fixed points of a relatively nonexpansive mapping S , and the set $T^{-1}0$ of zeros of a maximal monotone operator T in a uniformly smooth and uniformly convex Banach space. Strong convergence theorems for these hybrid proximal-type algorithms are established; that is, under appropriate conditions, the sequences generated by these various algorithms converge strongly to the same point in $EP \cap F(S) \cap T^{-1}0$. These new results represent the improvement, generalization, and development of the previously known ones in the literature.

1. Introduction

Let E be a real Banach space with the dual E^* and C be a nonempty closed convex subset of E . We denote by \mathcal{N} and \mathcal{R} the sets of positive integers and real numbers, respectively. Also, we denote by J the normalized duality mapping from E to 2^{E^*} defined by

$$Jx = \{x^* \in E^* : \langle x, x^* \rangle = \|x\|^2 = \|x^*\|^2\}, \quad \forall x \in E, \quad (1.1)$$

where $\langle \cdot, \cdot \rangle$ denotes the generalized duality pairing. Recall that if E is smooth, then J is single valued and if E is uniformly smooth, then J is uniformly norm-to-norm continuous on bounded subsets of E . We will still denote by J the single valued duality mapping. Let

$f : C \times C \rightarrow \mathcal{R}$ be a bifunction and $A : C \rightarrow E^*$ be a nonlinear mapping. We consider the following generalized equilibrium problem:

$$\text{find } u \in C \text{ such that } f(u, y) + \langle Au, y - u \rangle \geq 0, \quad \forall y \in C. \quad (1.2)$$

The set of such $u \in C$ is denoted by EP, that is,

$$\text{EP} = \{u \in C : f(u, y) + \langle Au, y - u \rangle \geq 0, \quad \forall y \in C\}. \quad (1.3)$$

Whenever $E = H$ a Hilbert space, problem (1.2) was introduced and studied by S. Takahashi and W. Takahashi [1]. Similar problems have been studied extensively recently. See, for example, [2–11]. In the case of $A \equiv 0$, EP is denoted by $\text{EP}(f)$. In the case of $f \equiv 0$, EP is also denoted by $\text{VI}(C, A)$. The problem (1.2) is very general in the sense that it includes, as special cases, optimization problems, variational inequalities, minimax problems, the Nash equilibrium problem in noncooperative games and others; see, for example, [12–14]. A mapping $S : C \rightarrow E$ is called nonexpansive if $\|Sx - Sy\| \leq \|x - y\|$ for all $x, y \in C$. Denote by $F(S)$ the set of fixed points of S , that is, $F(S) = \{x \in C : Sx = x\}$. A mapping $A : C \rightarrow E^*$ is called α -inverse-strongly monotone, if there exists an $\alpha > 0$ such that

$$\langle Ax - Ay, x - y \rangle \geq \alpha \|Ax - Ay\|^2, \quad \forall x, y \in C. \quad (1.4)$$

It is easy to see that if $A : C \rightarrow E^*$ is an α -inverse-strongly monotone mapping, then it is $1/\alpha$ -Lipschitzian.

Let E be a real Banach space with the dual E^* . A multivalued operator $T : E \rightarrow 2^{E^*}$ with domain $D(T) = \{z \in E : Tz \neq \emptyset\}$ is called monotone if $\langle x_1 - x_2, y_1 - y_2 \rangle \geq 0$ for each $x_i \in D(T)$ and $y_i \in Tx_i$, $i = 1, 2$. A monotone operator T is called maximal if its graph $G(T) = \{(x, y) : y \in Tx\}$ is not properly contained in the graph of any other monotone operator. A method for solving the inclusion $0 \in Tx$ is the proximal point algorithm. Denote by I the identity operator on $E = H$ a Hilbert space. The proximal point algorithm generates, for any initial point $x_0 = x \in H$, a sequence $\{x_n\}$ in H , by the iterative scheme

$$x_{n+1} = (I + r_n T)^{-1} x_n, \quad n = 0, 1, 2, \dots, \quad (1.5)$$

where $\{r_n\}$ is a sequence in the interval $(0, \infty)$. Note that this iteration is equivalent to

$$0 \in Tx_{n+1} + \frac{1}{r_n}(x_{n+1} - x_n), \quad n = 0, 1, 2, \dots \quad (1.6)$$

This algorithm was first introduced by Martinet [12] and generally studied by Rockafellar [15] in the framework of a Hilbert space. Later many authors studied its convergence in a Hilbert space or a Banach space. See, for instance, [16–21] and the references therein.

Let E be a reflexive, strictly convex, and smooth Banach space with the dual E^* and C be a nonempty closed convex subset of E . Let $T : E \rightarrow 2^{E^*}$ be a maximal monotone operator with domain $D(T) = C$ and $S : C \rightarrow C$ be a relatively nonexpansive mapping. Let $A : C \rightarrow E^*$ be an α -inverse-strongly monotone mapping and $f : C \times C \rightarrow \mathcal{R}$ be a bifunction satisfying

(A1)–(A4): (A1) $f(x, x) = 0, \forall x \in C$; (A2) f is monotone, that is, $f(x, y) + f(y, x) \leq 0, \forall x, y \in C$; (A3) $\limsup_{t \downarrow 0} f(x + t(z - x), y) \leq f(x, y), \forall x, y, z \in C$; (A4) the function $y \mapsto f(x, y)$ is convex and lower semicontinuous. The purpose of this paper is to introduce and investigate two new hybrid proximal-type Algorithms 1.1 and 1.2 for finding an element of $EP \cap F(S) \cap T^{-1}0$.

Algorithm 1.1.

$$\begin{aligned}
& x_0 \in C \text{ arbitrarily chosen,} \\
& 0 = v_n + \frac{1}{r_n}(J\tilde{x}_n - Jx_n), \quad v_n \in T\tilde{x}_n, \\
& z_n = J^{-1}(\beta_n J\tilde{x}_n + (1 - \beta_n)JS\tilde{x}_n), \\
& y_n = J^{-1}(\alpha_n J\tilde{x}_n + (1 - \alpha_n)JSz_n), \\
& u_n \in C \text{ such that} \tag{1.7} \\
& f(u_n, y) + \langle Au_n, y - u_n \rangle + \frac{1}{r_n} \langle y - u_n, Ju_n - Jy_n \rangle \geq 0, \quad \forall y \in C, \\
& H_n = \{v \in C : \phi(v, u_n) \leq \alpha_n \phi(v, \tilde{x}_n) + (1 - \alpha_n) \phi(v, z_n), \langle v - \tilde{x}_n, v_n \rangle \leq 0\}, \\
& W_n = \{v \in C : \langle v - x_n, Jx_0 - Jx_n \rangle \leq 0\}, \\
& x_{n+1} = \Pi_{H_n \cap W_n} x_0, \quad n = 0, 1, 2, \dots,
\end{aligned}$$

where $\{r_n\}_{n=0}^{\infty}$ is a sequence in $(0, \infty)$ and $\{\alpha_n\}_{n=0}^{\infty}, \{\beta_n\}_{n=0}^{\infty}$ are sequences in $[0, 1]$.

Algorithm 1.2.

$$\begin{aligned}
& x_0 \in C \text{ arbitrarily chosen,} \\
& 0 = v_n + \frac{1}{r_n}(J\tilde{x}_n - Jx_n), \quad v_n \in T\tilde{x}_n, \\
& y_n = J^{-1}(\alpha_n Jx_0 + (1 - \alpha_n)JS\tilde{x}_n), \\
& u_n \in C \text{ such that} \tag{1.8} \\
& f(u_n, y) + \langle Au_n, y - u_n \rangle + \frac{1}{r_n} \langle y - u_n, Ju_n - Jy_n \rangle \geq 0, \quad \forall y \in C, \\
& H_n = \{v \in C : \phi(v, u_n) \leq \alpha_n \phi(v, x_0) + (1 - \alpha_n) \phi(v, \tilde{x}_n), \langle v - \tilde{x}_n, v_n \rangle \leq 0\}, \\
& W_n = \{v \in C : \langle v - x_n, Jx_0 - Jx_n \rangle \leq 0\}, \\
& x_{n+1} = \Pi_{H_n \cap W_n} x_0, \quad n = 0, 1, 2, \dots,
\end{aligned}$$

where $\{r_n\}_{n=0}^{\infty}$ is a sequence in $(0, \infty)$ and $\{\alpha_n\}_{n=0}^{\infty}$ is a sequence in $[0, 1]$.

In this paper, strong convergence results on these two hybrid proximal-type algorithms are established; that is, under appropriate conditions, the sequence $\{x_n\}$ generated by Algorithm 1.1 and the sequence $\{x_n\}$ generated by Algorithm 1.2, converge strongly to the same point $\Pi_{EP \cap F(S) \cap T^{-1}0}x_0$. These new results represent the improvement, generalization and development of the previously known ones in the literature including Solodov and Svaiter [22], Kamimura and Takahashi [23], Qin and Su [24], and Ceng et al. [25].

Throughout this paper the symbol \rightharpoonup stands for weak convergence and \rightarrow stands for strong convergence.

2. Preliminaries

Let E be a real Banach space with the dual E^* . We denote by J the normalized duality mapping from E to 2^{E^*} defined by

$$Jx = \left\{ x^* \in E^* : \langle x, x^* \rangle = \|x\|^2 = \|x^*\|^2 \right\}, \quad \forall x \in X, \quad (2.1)$$

where $\langle \cdot, \cdot \rangle$ denotes the generalized duality pairing. A Banach space E is called strictly convex if $\|(x + y)/2\| < 1$ for all $x, y \in E$ with $\|x\| = \|y\| = 1$ and $x \neq y$. It is said to be uniformly convex if $x_n - y_n \rightarrow 0$ for any two sequences $\{x_n\}, \{y_n\} \subset E$ such that $\|x_n\| = \|y_n\| = 1$ and $\lim_{n \rightarrow \infty} \|(x_n + y_n)/2\| = 1$. Let $U = \{x \in E : \|x\| = 1\}$ be a unit sphere of E , then the Banach space E is called smooth if

$$\lim_{t \rightarrow 0} \frac{\|x + ty\| - \|x\|}{t} \quad (2.2)$$

exists for each $x, y \in U$. If E is smooth, then J is single valued. We still denote the single valued duality mapping by J .

It is also said to be uniformly smooth if the limit is attained uniformly for $x, y \in U$. Recall also that if E is uniformly smooth, then J is uniformly norm-to-norm continuous on bounded subsets of E . A Banach space E is said to have the Kadec-Klee property if for any sequence $\{x_n\} \subset E$, whenever $x_n \rightharpoonup x \in E$ and $\|x_n\| \rightarrow \|x\|$, we have $x_n \rightarrow x$. It is known that if E is uniformly convex, then E has the Kadec-Klee property; see [26, 27] for more details.

Let C be a nonempty closed convex subset of a real Hilbert space H and $P_C : H \rightarrow C$ be the metric projection of H onto C , then P_C is nonexpansive. This fact actually characterizes Hilbert spaces and hence, it is not available in more general Banach spaces. Nevertheless, Alber [28] recently introduced a generalized projection operator Π_C in a Banach space E which is an analogue of the metric projection in Hilbert spaces.

Next, we assume that E is a smooth Banach space. Consider the functional defined as in [28, 29] by

$$\phi(x, y) = \|x\|^2 - 2\langle x, Jy \rangle + \|y\|^2, \quad \forall x, y \in E. \quad (2.3)$$

It is clear that in a Hilbert space H , (2.3) reduces to $\phi(x, y) = \|x - y\|^2$, for all $x, y \in H$.

The generalized projection $\Pi_C : E \rightarrow C$ is a mapping that assigns to an arbitrary point $x \in E$ the minimum point of the functional $\phi(y, x)$; that is, $\Pi_C x = \bar{x}$, where \bar{x} is the solution to the minimization problem

$$\phi(\bar{x}, x) = \min_{y \in C} \phi(y, x). \quad (2.4)$$

The existence and uniqueness of the operator Π_C follows from the properties of the functional $\phi(x, y)$ and strict monotonicity of the mapping J (see, e.g., [30]). In a Hilbert space H , $\Pi_C = P_C$. From [28], in uniformly smooth and uniformly convex Banach spaces, we have

$$(\|x\| - \|y\|)^2 \leq \phi(x, y) \leq (\|x\| + \|y\|)^2, \quad \forall x, y \in E. \quad (2.5)$$

Let C be a nonempty closed convex subset of E , and let S be a mapping from C into itself. A point $p \in C$ is called an asymptotically fixed point of S [31] if C contains a sequence $\{x_n\}$ which converges weakly to p such that $Sx_n - x_n \rightarrow 0$. The set of asymptotical fixed points of S will be denoted by $\hat{F}(S)$. A mapping S from C into itself is called relatively nonexpansive [32–34] if $\hat{F}(S) = F(S)$ and $\phi(p, Sx) \leq \phi(p, x)$ for all $x \in C$ and $p \in F(S)$.

We remark that if E is a reflexive, strictly convex and smooth Banach space, then for any $x, y \in E$, $\phi(x, y) = 0$ if and only if $x = y$. It is sufficient to show that if $\phi(x, y) = 0$ then $x = y$. From (2.5), we have $\|x\| = \|y\|$. This implies that $\langle x, Jy \rangle = \|x\|^2 = \|y\|^2$. From the definition of J , we have $Jx = Jy$. Therefore, we have $x = y$; see [26, 27] for more details.

We need the following lemmas for the proof of our main results.

Lemma 2.1 (see [23]). *Let E be a smooth and uniformly convex Banach space and let $\{x_n\}$ and $\{y_n\}$ be two sequences of E . If $\phi(x_n, y_n) \rightarrow 0$ and either $\{x_n\}$ or $\{y_n\}$ is bounded, then $x_n - y_n \rightarrow 0$.*

Lemma 2.2 (see [23, 28]). *Let C be a nonempty closed convex subset of a smooth, strictly convex and reflexive Banach space E , let $x \in E$ and let $z \in C$, then*

$$z = \Pi_C x \iff \langle y - z, Jx - Jz \rangle \leq 0, \quad \forall y \in C. \quad (2.6)$$

Lemma 2.3 (see [23, 28]). *Let C be a nonempty closed convex subset of a smooth, strictly convex and reflexive Banach space E , then*

$$\phi(x, \Pi_C y) + \phi(\Pi_C y, y) \leq \phi(x, y), \quad \forall x \in C, y \in E. \quad (2.7)$$

Lemma 2.4 (see [35]). *Let C be a nonempty closed convex subset of a reflexive, strictly convex and smooth Banach space E , and let $S : C \rightarrow C$ be a relatively nonexpansive mapping, then $F(S)$ is closed and convex.*

The following result is according to Blum and Oettli [36].

Lemma 2.5 (see [36]). *Let C be a nonempty closed convex subset of a smooth, strictly convex and reflexive Banach space E , let f be a bifunction from $C \times C$ to \mathcal{R} satisfying (A1)–(A4), and let $r > 0$ and $x \in E$, then, there exists $z \in C$ such that*

$$f(z, y) + \frac{1}{r} \langle y - z, Jz - Jx \rangle \geq 0, \quad \forall y \in C. \quad (2.8)$$

Motivated by Combettes and Hirstoaga [37] in a Hilbert space, Takahashi and Zembayashi [38] established the following lemma.

Lemma 2.6 (see [38]). *Let C be a nonempty closed convex subset of a uniformly smooth, strictly convex and reflexive Banach space E , and let f be a bifunction from $C \times C$ to \mathcal{R} satisfying (A1)–(A4). For $r > 0$ and $x \in E$, define a mapping $T_r : E \rightarrow C$ as follows:*

$$T_r(x) = \left\{ z \in C : f(z, y) + \frac{1}{r} \langle y - z, Jz - Jx \rangle \geq 0, \forall y \in C \right\} \quad (2.9)$$

for all $x \in E$, then, the following hold:

- (i) T_r is single valued;
- (ii) T_r is a firmly nonexpansive-type mapping, that is, for all $x, y \in E$,

$$\langle T_r x - T_r y, J T_r x - J T_r y \rangle \leq \langle T_r x - T_r y, Jx - Jy \rangle; \quad (2.10)$$

- (iii) $F(T_r) = \widehat{F}(T_r) = \text{EP}(f)$;
- (iv) $\text{EP}(f)$ is closed and convex.

Using Lemma 2.6, one has the following result.

Lemma 2.7 (see [38]). *Let C be a nonempty closed convex subset of a smooth, strictly convex and reflexive Banach space E , let f be a bifunction from $C \times C$ to \mathcal{R} satisfying (A1)–(A4), and let $r > 0$, then, for $x \in E$ and $q \in F(T_r)$,*

$$\phi(q, T_r x) + \phi(T_r x, x) \leq \phi(q, x). \quad (2.11)$$

Utilizing Lemmas 2.5, 2.6 and 2.7 as above, Chang [39] derived the following result.

Proposition 2.8 (see [39, Lemma 2.5]). *Let E be a smooth, strictly convex and reflexive Banach space and C be a nonempty closed convex subset of E . Let $A : C \rightarrow E^*$ be an α -inverse-strongly monotone mapping, let f be a bifunction from $C \times C$ to \mathcal{R} satisfying (A1)–(A4), and let $r > 0$, then there hold the following:*

(I) for $x \in E$, there exists $u \in C$ such that

$$f(u, y) + \langle Au, y - u \rangle + \frac{1}{r} \langle y - u, Ju - Jx \rangle \geq 0, \quad \forall y \in C; \quad (2.12)$$

(II) if E is additionally uniformly smooth and $K_r : E \rightarrow C$ is defined as

$$K_r(x) = \left\{ u \in C : f(u, y) + \langle Au, y - u \rangle + \frac{1}{r} \langle y - u, Ju - Jx \rangle \geq 0, \forall y \in C \right\}, \quad \forall x \in E, \quad (2.13)$$

then the mapping K_r has the following properties:

- (i) K_r is single valued,
- (ii) K_r is a firmly nonexpansive-type mapping, that is,

$$\langle K_r x - K_r y, JK_r x - JK_r y \rangle \leq \langle K_r x - K_r y, Jx - Jy \rangle, \quad \forall x, y \in E, \quad (2.14)$$

- (iii) $F(K_r) = \widehat{F}(K_r) = \text{EP}$,
- (iv) EP is a closed convex subset of C ,
- (v) $\phi(p, K_r x) + \phi(K_r x, x) \leq \phi(p, x)$, for all $p \in F(K_r)$.

Proof. Define a bifunction $F : C \times C \rightarrow \mathcal{R}$ as follows:

$$F(x, y) = f(x, y) + \langle Ax, y - x \rangle, \quad \forall x, y \in C. \quad (2.15)$$

Then it is easy to verify that F satisfies the conditions (A1)–(A4). Therefore, The conclusions (I) and (II) of Proposition 2.8 follow immediately from Lemmas 2.5, 2.6 and 2.7. \square

Lemma 2.9 (see [13, 14]). *Let E be a reflexive, strictly convex and smooth Banach space, and let $T : E \rightarrow 2^{E^*}$ be a maximal monotone operator with $T^{-1}0 \neq \emptyset$, then,*

$$\phi(z, J_r x) + \phi(J_r x, x) \leq \phi(z, x), \quad \forall r > 0, z \in T^{-1}0, x \in E. \quad (2.16)$$

3. Main Results

Throughout this section, unless otherwise stated, we assume that $T : E \rightarrow 2^{E^*}$ is a maximal monotone operator with domain $D(T) = C$, $S : C \rightarrow C$ is a relatively nonexpansive mapping, $A : C \rightarrow E^*$ is an α -inverse-strongly monotone mapping and $f : C \times C \rightarrow \mathcal{R}$ is a bifunction satisfying (A1)–(A4), where C is a nonempty closed convex subset of a reflexive, strictly convex, and smooth Banach space E . In this section, we study the following algorithm.

Algorithm 3.1.

$$\begin{aligned}
& x_0 \in C \text{ arbitrarily chosen,} \\
& 0 = v_n + \frac{1}{r_n}(J\tilde{x}_n - Jx_n), \quad v_n \in T\tilde{x}_n, \\
& z_n = J^{-1}(\beta_n J\tilde{x}_n + (1 - \beta_n)JS\tilde{x}_n), \\
& y_n = J^{-1}(\alpha_n J\tilde{x}_n + (1 - \alpha_n)JSz_n), \\
& u_n \in C \text{ such that} \tag{3.1} \\
& f(u_n, y) + \langle Au_n, y - u_n \rangle + \frac{1}{r_n} \langle y - u_n, Ju_n - Jy_n \rangle \geq 0, \quad \forall y \in C, \\
& H_n = \{v \in C : \phi(v, u_n) \leq \alpha_n \phi(v, \tilde{x}_n) + (1 - \alpha_n) \phi(v, z_n), \langle v - \tilde{x}_n, v_n \rangle \leq 0\}, \\
& W_n = \{v \in C : \langle v - x_n, Jx_0 - Jx_n \rangle \leq 0\}, \\
& x_{n+1} = \Pi_{H_n \cap W_n} x_0, \quad n = 0, 1, 2, \dots,
\end{aligned}$$

where $\{r_n\}_{n=0}^{\infty}$ is a sequence in $(0, \infty)$ and $\{\alpha_n\}_{n=0}^{\infty}, \{\beta_n\}_{n=0}^{\infty}$ are sequences in $[0, 1]$.

First we investigate the condition under which the Algorithm 3.1 is well defined. Rockafellar [40] proved the following result.

Lemma 3.2 (Rockafellar [40]). *Let E be a reflexive, strictly convex, and smooth Banach space and let $T : E \rightarrow 2^{E^*}$ be a multivalued operator, then there hold the following:*

- (i) $T^{-1}0$ is closed and convex if T is maximal monotone such that $T^{-1}0 \neq \emptyset$;
- (ii) T is maximal monotone if and only if T is monotone with $R(J + rT) = E^*$ for all $r > 0$.

Utilizing this result, we can show the following lemma.

Lemma 3.3. *Let E be a reflexive, strictly convex, and smooth Banach space. If $EP \cap F(S) \cap T^{-1}0 \neq \emptyset$, then the sequence $\{x_n\}$ generated by Algorithm 3.1 is well defined.*

Proof. For each $n \geq 0$, define two sets C_n and D_n as follows:

$$\begin{aligned}
C_n &= \{v \in C : \phi(v, u_n) \leq \alpha_n \phi(v, \tilde{x}_n) + (1 - \alpha_n) \phi(v, z_n)\}, \\
D_n &= \{v \in C : \langle v - \tilde{x}_n, v_n \rangle \leq 0\}.
\end{aligned} \tag{3.2}$$

It is obvious that C_n is closed and D_n, W_n are closed convex sets for each $n \geq 0$. Let us show that C_n is convex. For $v_1, v_2 \in C_n$ and $t \in (0, 1)$, put $v = tv_1 + (1 - t)v_2$. It is sufficient to show that $v \in C_n$. Indeed, observe that

$$\phi(v, u_n) \leq \alpha_n \phi(v, \tilde{x}_n) + (1 - \alpha_n) \phi(v, z_n) \tag{3.3}$$

is equivalent to

$$2\alpha_n \langle v, J\tilde{x}_n \rangle + 2(1 - \alpha_n) \langle v, Jz_n \rangle - 2 \langle v, Ju_n \rangle \leq \alpha_n \|\tilde{x}_n\|^2 + (1 - \alpha_n) \|z_n\|^2 - \|u_n\|^2. \quad (3.4)$$

Note that there hold the following:

$$\begin{aligned} \phi(v, u_n) &= \|v\|^2 - 2 \langle v, Ju_n \rangle + \|u_n\|^2, \\ \phi(v, \tilde{x}_n) &= \|v\|^2 - 2 \langle v, J\tilde{x}_n \rangle + \|\tilde{x}_n\|^2, \\ \phi(v, z_n) &= \|v\|^2 - 2 \langle v, Jz_n \rangle + \|z_n\|^2, \end{aligned} \quad (3.5)$$

Thus we have

$$\begin{aligned} &2\alpha_n \langle v, J\tilde{x}_n \rangle + 2(1 - \alpha_n) \langle v, Jz_n \rangle - 2 \langle v, Ju_n \rangle \\ &= 2\alpha_n \langle tv_1 + (1 - t)v_2, J\tilde{x}_n \rangle + 2(1 - \alpha_n) \langle tv_1 + (1 - t)v_2, Jz_n \rangle \\ &\quad - 2 \langle tv_1 + (1 - t)v_2, Ju_n \rangle \\ &= 2t\alpha_n \langle v_1, J\tilde{x}_n \rangle + 2(1 - t)\alpha_n \langle v_2, J\tilde{x}_n \rangle + 2(1 - \alpha_n)t \langle v_1, Jz_n \rangle \\ &\quad + 2(1 - \alpha_n)(1 - t) \langle v_2, Jz_n \rangle - 2t \langle v_1, Ju_n \rangle - 2(1 - t) \langle v_2, Ju_n \rangle \\ &\leq \alpha_n \|\tilde{x}_n\|^2 + (1 - \alpha_n) \|z_n\|^2 - \|u_n\|^2. \end{aligned} \quad (3.6)$$

This implies that $v \in C_n$. Therefore, C_n is convex and hence $H_n = C_n \cap D_n$ is closed and convex.

On the other hand, let $w \in EP \cap F(S) \cap T^{-1}0$ be arbitrarily chosen, then $w \in EP, w \in F(S)$ and $w \in T^{-1}0$. From Algorithm 3.1, it follows that

$$\begin{aligned} \phi(w, u_n) &= \phi(w, K_{r_n}y_n) \leq \phi(w, y_n) \\ &= \phi\left(w, J^{-1}(\alpha_n J\tilde{x}_n + (1 - \alpha_n)JSz_n)\right) \\ &= \|w\|^2 - 2 \langle w, \alpha_n J\tilde{x}_n + (1 - \alpha_n)JSz_n \rangle + \|\alpha_n J\tilde{x}_n + (1 - \alpha_n)JSz_n\|^2 \\ &\leq \|w\|^2 - 2\alpha_n \langle w, J\tilde{x}_n \rangle - 2(1 - \alpha_n) \langle w, JSz_n \rangle + \alpha_n \|\tilde{x}_n\|^2 + (1 - \alpha_n) \|S z_n\|^2 \\ &\leq \alpha_n \phi(w, \tilde{x}_n) + (1 - \alpha_n) \phi(w, S z_n) \\ &\leq \alpha_n \phi(w, \tilde{x}_n) + (1 - \alpha_n) \phi(w, z_n). \end{aligned} \quad (3.7)$$

So $w \in C_n$ for all $n \geq 0$. Now, from Lemma 3.2 it follows that there exists $(\tilde{x}_0, v_0) \in E \times E^*$ such that $0 = v_0 + (1/r_0)(J\tilde{x}_0 - Jx_0)$ and $v_0 \in T\tilde{x}_0$. Since T is monotone, it follows that $\langle \tilde{x}_0 - w, v_0 \rangle \geq 0$, which implies that $w \in D_0$ and hence $w \in H_0$. Furthermore, it is clear that $w \in W_0 = C$, then $w \in H_0 \cap W_0$, and therefore $x_1 = \Pi_{H_0 \cap W_0} x_0$ is well defined. Suppose that $w \in H_{n-1} \cap W_{n-1}$ and x_n is well defined for some $n \geq 1$. Again by Lemma 3.2, we deduce that $(\tilde{x}_n, v_n) \in E \times E^*$ such that $0 = v_n + (1/r_n)(J\tilde{x}_n - Jx_n)$ and $v_n \in T\tilde{x}_n$, then from the monotonicity of T we

conclude that $\langle \tilde{x}_n - w, v_n \rangle \geq 0$, which implies that $w \in D_n$ and hence $w \in H_n$. It follows from Lemma 2.4 that

$$\langle w - x_n, Jx_0 - Jx_n \rangle = \langle w - \Pi_{H_{n-1} \cap W_{n-1}} x_0, Jx_0 - J\Pi_{H_{n-1} \cap W_{n-1}} x_0 \rangle \leq 0, \quad (3.8)$$

which implies that $w \in W_n$. Consequently, $w \in H_n \cap W_n$ and so $\text{EP} \cap F(S) \cap T^{-1}0 \subset H_n \cap W_n$. Therefore $x_{n+1} = \Pi_{H_n \cap W_n} x_0$ is well defined, then, by induction, the sequence $\{x_n\}$ generated by Algorithm 3.1, is well defined for each integer $n \geq 0$. \square

Remark 3.4. From the above proof, we obtain that

$$\text{EP} \cap F(S) \cap T^{-1}0 \subset H_n \cap W_n \quad (3.9)$$

for each integer $n \geq 0$.

We are now in a position to prove the main theorem.

Theorem 3.5. *Let E be a uniformly smooth and uniformly convex Banach space. Let $\{r_n\}_{n=0}^{\infty}$ be a sequence in $(0, \infty)$ and $\{\alpha_n\}_{n=0}^{\infty}, \{\beta_n\}_{n=0}^{\infty}$ be sequences in $[0, 1]$ such that*

$$\liminf_{n \rightarrow \infty} r_n > 0, \quad \limsup_{n \rightarrow \infty} \alpha_n < 1, \quad \lim_{n \rightarrow \infty} \beta_n = 1. \quad (3.10)$$

Let $\text{EP} \cap F(S) \cap T^{-1}0 \neq \emptyset$. If S is uniformly continuous, then the sequence $\{x_n\}$ generated by Algorithm 3.1 converges strongly to $\Pi_{\text{EP} \cap F(S) \cap T^{-1}0} x_0$.

Proof. First of all, it follows from the definition of W_n that $x_n = \Pi_{W_n} x_0$. Since $x_{n+1} = \Pi_{H_n \cap W_n} x_0 \in W_n$, we have

$$\phi(x_n, x_0) \leq \phi(x_{n+1}, x_0), \quad \forall n \geq 0. \quad (3.11)$$

Thus $\{\phi(x_n, x_0)\}$ is nondecreasing. Also from $x_n = \Pi_{W_n} x_0$ and Lemma 2.3, we have that

$$\phi(x_n, x_0) = \phi(\Pi_{W_n} x_0, x_0) \leq \phi(w, x_0) - \phi(w, x_n) \leq \phi(w, x_0) \quad (3.12)$$

for each $w \in \text{EP} \cap F(S) \cap T^{-1}0 \subset W_n$ and for each $n \geq 0$. Consequently, $\{\phi(x_n, x_0)\}$ is bounded. Moreover, according to the inequality

$$(\|x_n\| - \|x_0\|)^2 \leq \phi(x_n, x_0) \leq (\|x_n\| + \|x_0\|)^2, \quad (3.13)$$

we conclude that $\{x_n\}$ is bounded. Thus, we have that $\lim_{n \rightarrow \infty} \phi(x_n, x_0)$ exists. From Lemma 2.3, we derive the following:

$$\begin{aligned} \phi(x_{n+1}, x_n) &= \phi(x_{n+1}, \Pi_{W_n} x_0) \\ &\leq \phi(x_{n+1}, x_0) - \phi(\Pi_{W_n} x_0, x_0) \\ &= \phi(x_{n+1}, x_0) - \phi(x_n, x_0), \end{aligned} \quad (3.14)$$

for all $n \geq 0$. This implies that $\phi(x_{n+1}, x_n) \rightarrow 0$. So it follows from Lemma 2.1 that $x_{n+1} - x_n \rightarrow 0$. Since $x_{n+1} = \Pi_{H_n \cap W_n} x_0 \in H_n$, from the definition of H_n , we also have

$$\phi(x_{n+1}, u_n) \leq \alpha_n \phi(x_{n+1}, \tilde{x}_n) + (1 - \alpha_n) \phi(x_{n+1}, z_n), \quad \langle x_{n+1} - \tilde{x}_n, v_n \rangle \leq 0. \quad (3.15)$$

Observe that

$$\begin{aligned} \phi(x_{n+1}, z_n) &= \phi\left(x_{n+1}, J^{-1}(\beta_n J \tilde{x}_n + (1 - \beta_n) JS \tilde{x}_n)\right) \\ &= \|x_{n+1}\|^2 - 2\langle x_{n+1}, \beta_n J \tilde{x}_n + (1 - \beta_n) JS \tilde{x}_n \rangle + \|\beta_n J \tilde{x}_n + (1 - \beta_n) JS \tilde{x}_n\|^2 \\ &\leq \|x_{n+1}\|^2 - 2\beta_n \langle x_{n+1}, J \tilde{x}_n \rangle - 2(1 - \beta_n) \langle x_{n+1}, JS \tilde{x}_n \rangle + \beta_n \|\tilde{x}_n\|^2 + (1 - \beta_n) \|S \tilde{x}_n\|^2 \\ &= \beta_n \phi(x_{n+1}, \tilde{x}_n) + (1 - \beta_n) \phi(x_{n+1}, S \tilde{x}_n). \end{aligned} \quad (3.16)$$

At the same time,

$$\begin{aligned} \phi(\Pi_{H_n} x_n, x_n) - \phi(\tilde{x}_n, x_n) &= \|\Pi_{H_n} x_n\|^2 - \|\tilde{x}_n\|^2 + 2\langle \tilde{x}_n - \Pi_{H_n} x_n, J x_n \rangle \\ &\geq 2\langle \Pi_{H_n} x_n - \tilde{x}_n, J \tilde{x}_n \rangle + 2\langle \tilde{x}_n - \Pi_{H_n} x_n, J x_n \rangle \\ &= 2\langle \tilde{x}_n - \Pi_{H_n} x_n, J x_n - J \tilde{x}_n \rangle. \end{aligned} \quad (3.17)$$

Since $\Pi_{H_n} x_n \in H_n$ and $v_n = (1/r_n)(J x_n - J \tilde{x}_n)$, it follows that

$$\langle \tilde{x}_n - \Pi_{H_n} x_n, J x_n - J \tilde{x}_n \rangle = r_n \langle \tilde{x}_n - \Pi_{H_n} x_n, v_n \rangle \geq 0 \quad (3.18)$$

and hence that $\phi(\Pi_{H_n} x_n, x_n) \geq \phi(\tilde{x}_n, x_n)$. Further, from $x_{n+1} \in H_n$, we have $\phi(x_{n+1}, x_n) \geq \phi(\Pi_{H_n} x_n, x_n)$, which yields

$$\phi(x_{n+1}, x_n) \geq \phi(\Pi_{H_n} x_n, x_n) \geq \phi(\tilde{x}_n, x_n). \quad (3.19)$$

Then it follows from $\phi(x_{n+1}, x_n) \rightarrow 0$ that $\phi(\tilde{x}_n, x_n) \rightarrow 0$. Hence it follows from Lemma 2.1 that $\tilde{x}_n - x_n \rightarrow 0$. Since from (3.15) we derive

$$\begin{aligned}
& \phi(x_{n+1}, \tilde{x}_n) - \phi(\tilde{x}_n, x_n) \\
&= \|x_{n+1}\|^2 - 2\langle x_{n+1}, J\tilde{x}_n \rangle + \|\tilde{x}_n\|^2 - \left(\|\tilde{x}_n\|^2 - 2\langle \tilde{x}_n, Jx_n \rangle + \|x_n\|^2 \right) \\
&= \|x_{n+1}\|^2 - \|x_n\|^2 - 2\langle x_{n+1}, J\tilde{x}_n \rangle + 2\langle \tilde{x}_n, Jx_n \rangle \\
&= \|x_{n+1}\|^2 - \|x_n\|^2 - 2\langle x_{n+1} - \tilde{x}_n, J\tilde{x}_n - Jx_n \rangle \\
&\quad - 2\langle x_{n+1} - \tilde{x}_n, Jx_n \rangle + 2\langle \tilde{x}_n, Jx_n - J\tilde{x}_n \rangle \\
&= (\|x_{n+1}\| - \|x_n\|)(\|x_{n+1}\| + \|x_n\|) + 2r_n\langle x_{n+1} - \tilde{x}_n, v_n \rangle - 2\langle x_{n+1} - \tilde{x}_n, Jx_n \rangle \\
&\quad + 2\langle \tilde{x}_n, Jx_n - J\tilde{x}_n \rangle \\
&\leq \|x_{n+1} - x_n\|(\|x_{n+1}\| + \|x_n\|) + 2\|x_{n+1} - \tilde{x}_n\|\|x_n\| + 2\|\tilde{x}_n\|\|Jx_n - J\tilde{x}_n\| \\
&\leq \|x_{n+1} - x_n\|(\|x_{n+1}\| + \|x_n\|) + 2(\|x_{n+1} - x_n\| + \|x_n - \tilde{x}_n\|)\|x_n\| + 2\|\tilde{x}_n\|\|Jx_n - J\tilde{x}_n\|,
\end{aligned} \tag{3.20}$$

we have

$$\begin{aligned}
\phi(x_{n+1}, \tilde{x}_n) &\leq \phi(\tilde{x}_n, x_n) + \|x_{n+1} - x_n\|(\|x_{n+1}\| + \|x_n\|) \\
&\quad + 2(\|x_{n+1} - x_n\| + \|x_n - \tilde{x}_n\|)\|x_n\| + 2\|\tilde{x}_n\|\|Jx_n - J\tilde{x}_n\|.
\end{aligned} \tag{3.21}$$

Thus, from $\phi(\tilde{x}_n, x_n) \rightarrow 0$, $x_n - \tilde{x}_n \rightarrow 0$, and $x_{n+1} - x_n \rightarrow 0$, we know that $\phi(x_{n+1}, \tilde{x}_n) \rightarrow 0$. Consequently from (3.16), $\phi(x_{n+1}, \tilde{x}_n) \rightarrow 0$, and $\beta_n \rightarrow 1$ it follows that

$$\phi(x_{n+1}, z_n) \rightarrow 0. \tag{3.22}$$

So it follows from (3.15), $\phi(x_{n+1}, \tilde{x}_n) \rightarrow 0$, and $\phi(x_{n+1}, z_n) \rightarrow 0$ that $\phi(x_{n+1}, u_n) \rightarrow 0$. Utilizing Lemma 2.1 we deduce that

$$\lim_{n \rightarrow \infty} \|x_{n+1} - u_n\| = \lim_{n \rightarrow \infty} \|x_{n+1} - \tilde{x}_n\| = \lim_{n \rightarrow \infty} \|x_{n+1} - z_n\| = 0. \tag{3.23}$$

Furthermore, for $u \in \text{EP} \cap F(S) \cap T^{-1}0$ arbitrarily fixed, it follows from Proposition 2.8 that

$$\begin{aligned}
\phi(u_n, y_n) &= \phi(K_{r_n} y_n, y_n) \leq \phi(u, y_n) - \phi(u, K_{r_n} y_n) \\
&= \phi\left(u, J^{-1}(\alpha_n J \tilde{x}_n + (1 - \alpha_n) JSz_n)\right) - \phi(u, u_n) \\
&= \|u\|^2 - 2\langle u, \alpha_n J \tilde{x}_n + (1 - \alpha_n) JSz_n \rangle + \|\alpha_n J \tilde{x}_n + (1 - \alpha_n) JSz_n\|^2 - \phi(u, u_n) \\
&\leq \|u\|^2 - 2\alpha_n \langle u, J \tilde{x}_n \rangle - 2(1 - \alpha_n) \langle u, JSz_n \rangle + \alpha_n \|\tilde{x}_n\|^2 + (1 - \alpha_n) \|S z_n\|^2 - \phi(u, u_n) \\
&= \alpha_n \phi(u, \tilde{x}_n) + (1 - \alpha_n) \phi(u, S z_n) - \phi(u, u_n) \\
&\leq (1 - \alpha_n) \phi(u, z_n) + \alpha_n \phi(u, \tilde{x}_n) - \phi(u, u_n) \\
&= (1 - \alpha_n) \phi\left(u, J^{-1}(\beta_n J \tilde{x}_n + (1 - \beta_n) JS \tilde{x}_n)\right) + \alpha_n \phi(u, \tilde{x}_n) - \phi(u, u_n) \\
&= (1 - \alpha_n) \left[\|u\|^2 - 2\langle u, \beta_n J \tilde{x}_n + (1 - \beta_n) JS \tilde{x}_n \rangle + \|\beta_n J \tilde{x}_n + (1 - \beta_n) JS \tilde{x}_n\|^2 \right] \\
&\quad + \alpha_n \phi(u, \tilde{x}_n) - \phi(u, u_n) \\
&\leq (1 - \alpha_n) \left[\|u\|^2 - 2\beta_n \langle u, J \tilde{x}_n \rangle - 2(1 - \beta_n) \langle u, JS \tilde{x}_n \rangle + \beta_n \|\tilde{x}_n\|^2 + (1 - \beta_n) \|S \tilde{x}_n\|^2 \right] \\
&\quad + \alpha_n \phi(u, \tilde{x}_n) - \phi(u, u_n) \\
&= (1 - \alpha_n) [\beta_n \phi(u, \tilde{x}_n) + (1 - \beta_n) \phi(u, S \tilde{x}_n)] + \alpha_n \phi(u, \tilde{x}_n) - \phi(u, u_n) \\
&\leq (1 - \alpha_n) [\beta_n \phi(u, \tilde{x}_n) + (1 - \beta_n) \phi(u, \tilde{x}_n)] + \alpha_n \phi(u, \tilde{x}_n) - \phi(u, u_n) \\
&= (1 - \alpha_n) \phi(u, \tilde{x}_n) + \alpha_n \phi(u, \tilde{x}_n) - \phi(u, u_n) \\
&= \phi(u, \tilde{x}_n) - \phi(u, u_n) \\
&= \phi(u, \tilde{x}_n) - \phi(u, x_{n+1}) + \phi(u, x_{n+1}) - \phi(u, u_n) \\
&= \|\tilde{x}_n\|^2 - \|x_{n+1}\|^2 + 2\langle u, Jx_{n+1} - J\tilde{x}_n \rangle + \|x_{n+1}\|^2 - \|u_n\|^2 + 2\langle u, Ju_n - Jx_{n+1} \rangle \\
&\leq \|\tilde{x}_n - x_{n+1}\|(\|\tilde{x}_n\| + \|x_{n+1}\|) + 2\|u\| \|Jx_{n+1} - J\tilde{x}_n\| \\
&\quad + \|x_{n+1} - u_n\|(\|x_{n+1}\| + \|u_n\|) + 2\|u\| \|Ju_n - Jx_{n+1}\|.
\end{aligned} \tag{3.24}$$

Since J is uniformly norm-to-norm continuous on bounded subsets of E , it follows from (3.23) that $\|Jx_{n+1} - J\tilde{x}_n\| \rightarrow 0$ and $\|Ju_n - Jx_{n+1}\| \rightarrow 0$, which hence yield $\phi(u_n, y_n) \rightarrow 0$. Utilizing Lemma 2.1, we get $\|u_n - y_n\| \rightarrow 0$. Observe that

$$\|x_{n+1} - y_n\| \leq \|x_{n+1} - u_n\| + \|u_n - y_n\| \rightarrow 0, \tag{3.25}$$

due to (3.23). Since J is uniformly norm-to-norm continuous on bounded subsets of E , we have that

$$\lim_{n \rightarrow \infty} \|Jx_{n+1} - Jy_n\| = \lim_{n \rightarrow \infty} \|Jx_{n+1} - J\tilde{x}_n\| = 0. \tag{3.26}$$

On the other hand, we have

$$\|x_n - z_n\| \leq \|x_n - x_{n+1}\| + \|x_{n+1} - z_n\| \longrightarrow 0. \quad (3.27)$$

Noticing that

$$\begin{aligned} \|Jx_{n+1} - Jy_n\| &= \|Jx_{n+1} - (\alpha_n J\tilde{x}_n + (1 - \alpha_n)JSz_n)\| \\ &= \|\alpha_n(Jx_{n+1} - J\tilde{x}_n) + (1 - \alpha_n)(Jx_{n+1} - JSz_n)\| \\ &= \|(1 - \alpha_n)(Jx_{n+1} - JSz_n) - \alpha_n(J\tilde{x}_n - Jx_{n+1})\| \\ &\geq (1 - \alpha_n)\|Jx_{n+1} - JSz_n\| - \alpha_n\|J\tilde{x}_n - Jx_{n+1}\|, \end{aligned} \quad (3.28)$$

we have

$$\|Jx_{n+1} - JSz_n\| \leq \frac{1}{1 - \alpha_n} (\|Jx_{n+1} - Jy_n\| + \alpha_n\|J\tilde{x}_n - Jx_{n+1}\|). \quad (3.29)$$

From (3.26) and $\limsup_{n \rightarrow \infty} \alpha_n < 1$, we obtain

$$\lim_{n \rightarrow \infty} \|Jx_{n+1} - JSz_n\| = 0. \quad (3.30)$$

Since J^{-1} is also uniformly norm-to-norm continuous on bounded subsets of E^* , we obtain

$$\lim_{n \rightarrow \infty} \|x_{n+1} - Sz_n\| = 0. \quad (3.31)$$

Observe that

$$\|x_n - Sx_n\| \leq \|x_n - x_{n+1}\| + \|x_{n+1} - Sz_n\| + \|Sz_n - Sx_n\|. \quad (3.32)$$

Since S is uniformly continuous, it follows from (3.27), (3.31) and $x_{n+1} - x_n \rightarrow 0$ that $x_n - Sx_n \rightarrow 0$.

Now let us show that $\omega_w(\{x_n\}) \subset \text{EP} \cap F(S) \cap T^{-1}0$, where

$$\omega_w(\{x_n\}) := \{\hat{x} \in C : x_{n_k} \rightarrow \hat{x} \text{ for some subsequence } \{n_k\} \subset \{n\} \text{ with } n_k \uparrow \infty\}. \quad (3.33)$$

Indeed, since $\{x_n\}$ is bounded and X is reflexive, we know that $\omega_w(\{x_n\}) \neq \emptyset$. Take $\hat{x} \in \omega_w(\{x_n\})$ arbitrarily, then there exists a subsequence $\{x_{n_k}\}$ of $\{x_n\}$ such that $x_{n_k} \rightarrow \hat{x}$. Hence $\hat{x} \in F(S)$. Let us show that $\hat{x} \in T^{-1}0$. Since $x_n - \tilde{x}_n \rightarrow 0$, we have that $\tilde{x}_{n_k} \rightarrow \hat{x}$. Moreover, since J is uniformly norm-to-norm continuous on bounded subsets of E and $\liminf_{n \rightarrow \infty} r_n > 0$, we obtain

$$v_n = \frac{1}{r_n}(Jx_n - J\tilde{x}_n) \longrightarrow 0. \quad (3.34)$$

It follows from $v_n \in T\tilde{x}_n$ and the monotonicity of T that

$$\langle z - \tilde{x}_n, z' - v_n \rangle \geq 0 \quad (3.35)$$

for all $z \in D(T)$ and $z' \in Tz$. This implies that

$$\langle z - \hat{x}, z' \rangle \geq 0 \quad (3.36)$$

for all $z \in D(T)$ and $z' \in Tz$. Thus from the maximality of T , we infer that $\hat{x} \in T^{-1}0$. Therefore, $\hat{x} \in F(S) \cap T^{-1}0$. Further, let us show that $\hat{x} \in \text{EP}$. Since $u_n - y_n \rightarrow 0$ and $x_n - u_n \rightarrow 0$, from $x_{n_k} \rightarrow \hat{x}$ we obtain that $y_{n_k} \rightarrow \hat{x}$ and $u_{n_k} \rightarrow \hat{x}$.

Since J is uniformly norm-to-norm continuous on bounded subsets of E , from $u_n - y_n \rightarrow 0$ we derive

$$\lim_{n \rightarrow \infty} \|Ju_n - Jy_n\| = 0. \quad (3.37)$$

From $\liminf_{n \rightarrow \infty} r_n > 0$, it follows that

$$\lim_{n \rightarrow \infty} \frac{\|Ju_n - Jy_n\|}{r_n} = 0. \quad (3.38)$$

By the definition of $u_n := K_{r_n}y_n$, we have

$$F(u_n, y) + \frac{1}{r_n} \langle y - u_n, Ju_n - Jy_n \rangle \geq 0, \quad \forall y \in C, \quad (3.39)$$

where

$$F(u_n, y) = f(u_n, y) + \langle Au_n, y - u_n \rangle. \quad (3.40)$$

Replacing n by n_k , we have from (A2) that

$$\frac{1}{r_{n_k}} \langle y - u_{n_k}, Ju_{n_k} - Jy_{n_k} \rangle \geq -F(u_{n_k}, y) \geq F(y, u_{n_k}), \quad \forall y \in C. \quad (3.41)$$

Since $y \mapsto f(x, y) + \langle Ax, y - x \rangle$ is convex and lower semicontinuous, it is also weakly lower semicontinuous. Letting $n_k \rightarrow \infty$ in the last inequality, from (3.38) and (A4) we have

$$F(y, \hat{x}) \leq 0, \quad \forall y \in C. \quad (3.42)$$

For t , with $0 < t \leq 1$, and $y \in C$, let $y_t = ty + (1-t)\hat{x}$. Since $y \in C$ and $\hat{x} \in C$, then $y_t \in C$ and hence $F(y_t, \hat{x}) \leq 0$. So, from (A1) we have

$$0 = F(y_t, y_t) \leq tF(y_t, y) + (1-t)F(y_t, \hat{x}) \leq tF(y_t, y). \quad (3.43)$$

Dividing by t , we have

$$F(y_t, y) \geq 0, \quad \forall y \in C. \quad (3.44)$$

Letting $t \downarrow 0$, from (A3) it follows that

$$F(\hat{x}, y) \geq 0, \quad \forall y \in C. \quad (3.45)$$

So, $\hat{x} \in \text{EP}$. Therefore, we obtain that $\omega_w(\{x_n\}) \subset \text{EP} \cap F(S) \cap T^{-1}0$ by the arbitrariness of \hat{x} .

Next, let us show that $\omega_w(\{x_n\}) = \{\Pi_{\text{EP} \cap F(S) \cap T^{-1}0} x_0\}$ and $x_n \rightarrow \Pi_{\text{EP} \cap F(S) \cap T^{-1}0} x_0$.

Indeed, put $\bar{x} = \Pi_{\text{EP} \cap F(S) \cap T^{-1}0} x_0$. From $x_{n+1} = \Pi_{H_n \cap W_n} x_0$ and $\bar{x} \in \text{EP} \cap F(S) \cap T^{-1}0 \subset H_n \cap W_n$, we have $\phi(x_{n+1}, x_0) \leq \phi(\bar{x}, x_0)$. Now from weakly lower semicontinuity of the norm, we derive for each $\hat{x} \in \omega_w(\{x_n\})$

$$\begin{aligned} \phi(\hat{x}, x_0) &= \|\hat{x}\|^2 - 2\langle \hat{x}, x_0 \rangle + \|x_0\|^2 \\ &\leq \liminf_{k \rightarrow \infty} (\|x_{n_k}\|^2 - 2\langle x_{n_k}, x_0 \rangle + \|x_0\|^2) \\ &= \liminf_{k \rightarrow \infty} \phi(x_{n_k}, x_0) \\ &\leq \limsup_{k \rightarrow \infty} \phi(x_{n_k}, x_0) \\ &\leq \phi(\bar{x}, x_0). \end{aligned} \quad (3.46)$$

It follows from the definition of $\Pi_{\text{EP} \cap F(S) \cap T^{-1}0} x_0$ that $\hat{x} = \bar{x}$ and hence

$$\lim_{k \rightarrow \infty} \phi(x_{n_k}, x_0) = \phi(\bar{x}, x_0). \quad (3.47)$$

So we have $\lim_{k \rightarrow \infty} \|x_{n_k}\| = \|\bar{x}\|$. Utilizing the Kadec-Klee property of E , we conclude that $\{x_{n_k}\}$ converges strongly to $\Pi_{\text{EP} \cap F(S) \cap T^{-1}0} x_0$. Since $\{x_{n_k}\}$ is an arbitrary weakly convergent subsequence of $\{x_n\}$, we know that $\{x_n\}$ converges strongly to $\Pi_{\text{EP} \cap F(S) \cap T^{-1}0} x_0$. This completes the proof. \square

Theorem 3.5 covers [25, Theorem 3.1] by taking $C = E, f \equiv 0$ and $A \equiv 0$. Also Theorem 3.5 covers [24, Theorem 2.1] by taking $f \equiv 0, A \equiv 0$ and $T \equiv 0$.

Theorem 3.6. *Let C be a nonempty closed convex subset of a uniformly smooth and uniformly convex Banach space E . Let $T : E \rightarrow 2^{E^*}$ be a maximal monotone operator with domain $D(T) = C, S : C \rightarrow C$ be a relatively nonexpansive mapping, $A : C \rightarrow E^*$ be an α -inverse-strongly monotone mapping and $f : C \times C \rightarrow \mathcal{R}$ be a bifunction satisfying (A1)–(A4). Assume that $\{r_n\}_{n=0}^{\infty}$ is a sequence in $(0, \infty)$ satisfying $\liminf_{n \rightarrow \infty} r_n > 0$ and that $\{\alpha_n\}_{n=0}^{\infty}$ is a sequences in $(0, 1)$ satisfying $\lim_{n \rightarrow \infty} \alpha_n = 0$.*

Define a sequence $\{x_n\}$ by the following algorithm.

Algorithm 3.7.

$$\begin{aligned}
& x_0 \in C \text{ arbitrarily chosen,} \\
& 0 = v_n + \frac{1}{r_n}(J\tilde{x}_n - Jx_n), \quad v_n \in T\tilde{x}_n, \\
& y_n = J^{-1}(\alpha_n Jx_0 + (1 - \alpha_n)JS\tilde{x}_n), \\
& u_n \in C \text{ such that} \\
& f(u_n, y) + \langle Au_n, y - u_n \rangle + \frac{1}{r_n} \langle y - u_n, Ju_n - Jy_n \rangle \geq 0, \quad \forall y \in C, \\
& H_n = \{v \in C : \phi(v, u_n) \leq \alpha_n \phi(v, x_0) + (1 - \alpha_n)\phi(v, \tilde{x}_n), \langle v - \tilde{x}_n, v_n \rangle \leq 0\}, \\
& W_n = \{v \in C : \langle v - x_n, Jx_0 - Jx_n \rangle \leq 0\}, \\
& x_{n+1} = \Pi_{H_n \cap W_n} x_0, \quad n = 0, 1, 2, \dots,
\end{aligned} \tag{3.48}$$

where J is the single valued duality mapping on E . Let $EP \cap F(S) \cap T^{-1}0 \neq \emptyset$. If S is uniformly continuous, then $\{x_n\}$ converges strongly to $\Pi_{EP \cap F(S) \cap T^{-1}0} x_0$.

Proof. For each $n \geq 0$, define two sets C_n and D_n as follows:

$$\begin{aligned}
C_n &= \{v \in C : \phi(v, u_n) \leq \alpha_n \phi(v, x_0) + (1 - \alpha_n)\phi(v, \tilde{x}_n)\}, \\
D_n &= \{v \in C : \langle v - \tilde{x}_n, v_n \rangle \leq 0\}.
\end{aligned} \tag{3.49}$$

It is obvious that C_n is closed and D_n, W_n are closed convex sets for each $n \geq 0$. Let us show that C_n is convex and so $H_n = C_n \cap D_n$ is closed and convex. Similarly to the proof of Lemma 3.3, since

$$\phi(v, u_n) \leq \alpha_n \phi(v, x_0) + (1 - \alpha_n)\phi(v, \tilde{x}_n) \tag{3.50}$$

is equivalent to

$$2\alpha_n \langle v, Jx_0 \rangle + 2(1 - \alpha_n) \langle v, J\tilde{x}_n \rangle - 2 \langle v, Ju_n \rangle \leq \alpha_n \|x_0\|^2 + (1 - \alpha_n) \|\tilde{x}_n\|^2 - \|u_n\|^2, \tag{3.51}$$

we know that C_n is convex and so is $H_n = C_n \cap D_n$. Next, let us show that $\text{EP} \cap F(S) \cap T^{-1}0 \subset C_n$ for each $n \geq 0$. Indeed, utilizing Proposition 2.8, we have, for each $w \in \text{EP} \cap F(S) \cap T^{-1}0$,

$$\begin{aligned}
\phi(w, u_n) &= \phi(w, K_{r_n} y_n) \leq \phi(w, y_n) \\
&= \phi\left(w, J^{-1}(\alpha_n Jx_0 + (1 - \alpha_n)JS\tilde{x}_n)\right) \\
&= \|w\|^2 - 2\langle w, \alpha_n Jx_0 + (1 - \alpha_n)JS\tilde{x}_n \rangle + \|\alpha_n Jx_0 + (1 - \alpha_n)JS\tilde{x}_n\|^2 \\
&\leq \|w\|^2 - 2\alpha_n \langle w, Jx_0 \rangle - 2(1 - \alpha_n) \langle w, JS\tilde{x}_n \rangle + \alpha_n \|x_0\|^2 + (1 - \alpha_n) \|S\tilde{x}_n\|^2 \\
&= \alpha_n \phi(w, x_0) + (1 - \alpha_n) \phi(w, S\tilde{x}_n) \\
&\leq \alpha_n \phi(w, x_0) + (1 - \alpha_n) \phi(w, \tilde{x}_n).
\end{aligned} \tag{3.52}$$

So $w \in C_n$ for all $n \geq 0$ and $\text{EP} \cap F(S) \cap T^{-1}0 \subset C_n$. As in the proof of Lemma 3.3, we can obtain $w \in D_n$ and hence $w \in H_n$. It follows from Lemma 2.4 that

$$\langle w - x_n, Jx_0 - Jx_n \rangle = \langle w - \Pi_{H_{n-1} \cap W_{n-1}} x_0, Jx_0 - J\Pi_{H_{n-1} \cap W_{n-1}} x_0 \rangle \leq 0, \tag{3.53}$$

which implies that $w \in W_n$. Consequently, $w \in H_n \cap W_n$ and so $\text{EP} \cap F(S) \cap T^{-1}0 \subset H_n \cap W_n$ for all $n \geq 0$. Therefore, the sequence $\{x_n\}$ generated by Algorithm 3.7 is well defined. As in the proof of Theorem 3.5, we can obtain $\phi(x_{n+1}, x_n) \rightarrow 0$. Since $x_{n+1} = \Pi_{H_n \cap W_n} x_0 \in H_n$, from the definition of H_n we also have

$$\phi(x_{n+1}, u_n) \leq \alpha_n \phi(x_{n+1}, x_0) + (1 - \alpha_n) \phi(x_{n+1}, \tilde{x}_n), \quad \langle x_{n+1} - \tilde{x}_n, v_n \rangle \leq 0. \tag{3.54}$$

As in the proof of Theorem 3.5, we can deduce not only from $\phi(x_{n+1}, x_n) \rightarrow 0$ that $\phi(\tilde{x}_n, x_n) \rightarrow 0$ but also from $\phi(\tilde{x}_n, x_n) \rightarrow 0$, $x_n - \tilde{x}_n \rightarrow 0$ and $x_{n+1} - x_n \rightarrow 0$ that

$$\lim_{n \rightarrow \infty} \phi(x_{n+1}, \tilde{x}_n) = 0. \tag{3.55}$$

Since $x_{n+1} = \Pi_{H_n \cap W_n} x_0 \in H_n$, from the definition of H_n , we also have

$$\phi(x_{n+1}, u_n) \leq \alpha_n \phi(x_{n+1}, x_0) + (1 - \alpha_n) \phi(x_{n+1}, \tilde{x}_n). \tag{3.56}$$

It follows from (3.55) and $\alpha_n \rightarrow 0$ that

$$\lim_{n \rightarrow \infty} \phi(x_{n+1}, u_n) = 0. \tag{3.57}$$

Utilizing Lemma 2.1 we have

$$\lim_{n \rightarrow \infty} \|x_{n+1} - u_n\| = \lim_{n \rightarrow \infty} \|x_{n+1} - x_n\| = \lim_{n \rightarrow \infty} \|x_{n+1} - \tilde{x}_n\| = 0. \tag{3.58}$$

Furthermore, for $u \in \text{EP} \cap F(S) \cap T^{-1}0$ arbitrarily fixed, it follows from Proposition 2.8 that

$$\begin{aligned}
\phi(u_n, y_n) &= \phi(K_{r_n} y_n, y_n) \leq \phi(u, y_n) - \phi(u, K_{r_n} y_n) \\
&= \phi\left(u, J^{-1}(\alpha_n Jx_0 + (1 - \alpha_n)JS\tilde{x}_n)\right) - \phi(u, u_n) \\
&= \|u\|^2 - 2\langle u, \alpha_n Jx_0 + (1 - \alpha_n)JS\tilde{x}_n \rangle + \|\alpha_n Jx_0 + (1 - \alpha_n)JS\tilde{x}_n\|^2 - \phi(u, u_n) \\
&\leq \|u\|^2 - 2\alpha_n \langle u, Jx_0 \rangle - 2(1 - \alpha_n) \langle u, JS\tilde{x}_n \rangle + \alpha_n \|x_0\|^2 + (1 - \alpha_n) \|S\tilde{x}_n\|^2 - \phi(u, u_n) \\
&= \alpha_n \phi(u, x_0) + (1 - \alpha_n) \phi(u, S\tilde{x}_n) - \phi(u, u_n) \\
&\leq \alpha_n \phi(u, x_0) + \phi(u, \tilde{x}_n) - \phi(u, u_n) \\
&= \alpha_n \phi(u, x_0) + \phi(u, \tilde{x}_n) - \phi(u, x_{n+1}) + \phi(u, x_{n+1}) - \phi(u, u_n) \\
&= \alpha_n \phi(u, x_0) + \|\tilde{x}_n\|^2 - \|x_{n+1}\|^2 + 2\langle u, Jx_{n+1} - J\tilde{x}_n \rangle + \|x_{n+1}\|^2 \\
&\quad - \|u_n\|^2 + 2\langle u, Ju_n - Jx_{n+1} \rangle \\
&\leq \alpha_n \phi(u, x_0) + \|\tilde{x}_n - x_{n+1}\|(\|\tilde{x}_n\| + \|x_{n+1}\|) + 2\|u\| \|Jx_{n+1} - J\tilde{x}_n\| \\
&\quad + \|x_{n+1} - u_n\|(\|x_{n+1}\| + \|u_n\|) + 2\|u\| \|Ju_n - Jx_{n+1}\|.
\end{aligned} \tag{3.59}$$

Since J is uniformly norm-to-norm continuous on bounded subsets of E , it follows from (3.58) that $\|Jx_{n+1} - J\tilde{x}_n\| \rightarrow 0$ and $\|Ju_n - Jx_{n+1}\| \rightarrow 0$, which together with $\alpha_n \rightarrow 0$, yield $\phi(u_n, y_n) \rightarrow 0$. Utilizing Lemma 2.1, we get $\|u_n - y_n\| \rightarrow 0$. Observe that

$$\|x_{n+1} - y_n\| \leq \|x_{n+1} - u_n\| + \|u_n - y_n\| \rightarrow 0, \tag{3.60}$$

due to (3.58). Since J is uniformly norm-to-norm continuous on bounded subsets of E , we have

$$\lim_{n \rightarrow \infty} \|Jx_{n+1} - Jy_n\| = \lim_{n \rightarrow \infty} \|Jx_{n+1} - Jx_n\| = \lim_{n \rightarrow \infty} \|Jx_{n+1} - J\tilde{x}_n\| = 0. \tag{3.61}$$

Note that

$$\|JS\tilde{x}_n - Jy_n\| = \|JS\tilde{x}_n - (\alpha_n Jx_0 + (1 - \alpha_n)JS\tilde{x}_n)\| = \alpha_n \|Jx_0 - JS\tilde{x}_n\|. \tag{3.62}$$

Therefore, from $\alpha_n \rightarrow 0$ we get

$$\lim_{n \rightarrow \infty} \|JS\tilde{x}_n - Jy_n\| = 0. \tag{3.63}$$

Since J^{-1} is also uniformly norm-to-norm continuous on bounded subsets of E^* , we obtain

$$\lim_{n \rightarrow \infty} \|S\tilde{x}_n - y_n\| = 0. \tag{3.64}$$

It follows that

$$\|x_n - Sx_n\| \leq \|x_n - x_{n+1}\| + \|x_{n+1} - y_n\| + \|y_n - S\tilde{x}_n\| + \|S\tilde{x}_n - Sx_n\|. \quad (3.65)$$

Since S is uniformly continuous, it follows from (3.58) and (3.64) that $x_n - Sx_n \rightarrow 0$.

Finally, we prove that $x_n \rightarrow \Pi_{\text{EP} \cap F(S) \cap T^{-1}0} x_0$. Indeed, for $\hat{x} \in \text{EP} \cap F(S) \cap T^{-1}0$ arbitrarily fixed, there exists a subsequence $\{x_{n_k}\}$ of $\{x_n\}$ such that $x_{n_k} \rightharpoonup \hat{x} \in C$, then $\hat{x} \in F(S)$. Now let us show that $\hat{x} \in T^{-1}0$. Since $x_n - \tilde{x}_n \rightarrow 0$, we have that $\tilde{x}_{n_k} \rightharpoonup \hat{x}$. Moreover, since J is uniformly norm-to-norm continuous on bounded subsets of E , and $\liminf_{n \rightarrow \infty} r_n > 0$, we obtain that $v_n = (1/r_n)(Jx_n - J\tilde{x}_n) \rightarrow 0$. It follows from $v_n \in T\tilde{x}_n$ and the monotonicity of T that $\langle z - \tilde{x}_n, z' - v_n \rangle \geq 0$ for all $z \in D(T)$ and $z' \in Tz$. This implies that $\langle z - \hat{x}, z' \rangle \geq 0$ for all $z \in D(T)$ and $z' \in Tz$. Thus from the maximality of T , we infer that $\hat{x} \in T^{-1}0$. Further, let us show that $\hat{x} \in \text{EP}$. Since $u_n - y_n \rightarrow 0$ and $x_n - u_n \rightarrow 0$, from $x_{n_k} \rightharpoonup \hat{x}$ we obtain that $y_{n_k} \rightharpoonup \hat{x}$ and $u_{n_k} \rightharpoonup \hat{x}$.

Since J is uniformly norm-to-norm continuous on bounded subsets of E , from $u_n - y_n \rightarrow 0$ we derive $\lim_{n \rightarrow \infty} \|Ju_n - Jy_n\| = 0$. From $\liminf_{n \rightarrow \infty} r_n > 0$ it follows that

$$\lim_{n \rightarrow \infty} \frac{\|Ju_n - Jy_n\|}{r_n} = 0. \quad (3.66)$$

By the definition of $u_n := K_{r_n} y_n$, we have

$$F(u_n, y) + \frac{1}{r_n} \langle y - u_n, Ju_n - Jy_n \rangle \geq 0, \quad \forall y \in C, \quad (3.67)$$

where $F(u_n, y) = f(u_n, y) + \langle Au_n, y - u_n \rangle$. Replacing n by n_k , we have from (A2) that

$$\frac{1}{r_{n_k}} \langle y - u_{n_k}, Ju_{n_k} - Jy_{n_k} \rangle \geq -F(u_{n_k}, y) \geq F(y, u_{n_k}), \quad \forall y \in C. \quad (3.68)$$

Since $y \mapsto f(x, y) + \langle Ax, y - x \rangle$ is convex and lower semicontinuous, it is also weakly lower semicontinuous. Letting $n_k \rightarrow \infty$ in the last inequality, from (3.66) and (A4) we have $F(y, \hat{x}) \leq 0$, for all $y \in C$. For t , with $0 < t \leq 1$, and $y \in C$, let $y_t = ty + (1-t)\hat{x}$. Since $y \in C$ and $\hat{x} \in C$, then $y_t \in C$ and hence $F(y_t, \hat{x}) \leq 0$. So, from (A1) we have

$$0 = F(y_t, y_t) \leq tF(y_t, y) + (1-t)F(y_t, \hat{x}) \leq tF(y_t, y). \quad (3.69)$$

Dividing by t , we have $F(y_t, y) \geq 0$, for all $y \in C$. Letting $t \downarrow 0$, from (A3) it follows that $F(\hat{x}, y) \geq 0$, for all $y \in C$. So, $\hat{x} \in \text{EP}$. Therefore, we obtain that $\omega_w(\{x_n\}) \subset \text{EP} \cap F(S) \cap T^{-1}0$ by the arbitrariness of \hat{x} .

Next, let us show that $\omega_w(\{x_n\}) = \{\Pi_{\text{EP} \cap F(S) \cap T^{-1}0} x_0\}$ and $x_n \rightarrow \Pi_{\text{EP} \cap F(S) \cap T^{-1}0} x_0$.

Indeed, put $\bar{x} = \Pi_{\text{EP} \cap F(S) \cap T^{-1}0} x_0$. From $x_{n+1} = \Pi_{H_n \cap W_n} x_0$ and $\bar{x} \in \text{EP} \cap F(S) \cap T^{-1}0 \subset H_n \cap W_n$, we have $\phi(x_{n+1}, x_0) \leq \phi(\bar{x}, x_0)$. Now from weakly lower semicontinuity of the norm, we derive for each $\hat{x} \in \omega_w(\{x_n\})$

$$\begin{aligned}
 \phi(\hat{x}, x_0) &= \|\hat{x}\|^2 - 2\langle \hat{x}, x_0 \rangle + \|x_0\|^2 \\
 &\leq \liminf_{k \rightarrow \infty} \left(\|x_{n_k}\|^2 - 2\langle x_{n_k}, x_0 \rangle + \|x_0\|^2 \right) \\
 &= \liminf_{k \rightarrow \infty} \phi(x_{n_k}, x_0) \\
 &\leq \limsup_{k \rightarrow \infty} \phi(x_{n_k}, x_0) \\
 &\leq \phi(\bar{x}, x_0).
 \end{aligned} \tag{3.70}$$

It follows from the definition of $\Pi_{\text{EP} \cap F(S) \cap T^{-1}0} x_0$ that $\hat{x} = \bar{x}$ and hence $\lim_{k \rightarrow \infty} \phi(x_{n_k}, x_0) = \phi(\bar{x}, x_0)$. So we have $\lim_{k \rightarrow \infty} \|x_{n_k}\| = \|\bar{x}\|$. Utilizing the Kadec-Klee property of E , we know that $x_{n_k} \rightarrow \Pi_{\text{EP} \cap F(S) \cap T^{-1}0} x_0$. Since $\{x_{n_k}\}$ is an arbitrary weakly convergent subsequence of $\{x_n\}$, we know that $x_n \rightarrow \Pi_{\text{EP} \cap F(S) \cap T^{-1}0} x_0$. This completes the proof. \square

Theorem 3.6 covers [25, Theorem 3.2] by taking $C = E, f \equiv 0$ and $A \equiv 0$. Also Theorem 3.6 covers [24, Theorem 2.2] by taking $f \equiv 0, A \equiv 0$ and $T \equiv 0$.

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