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# Hierarchical convergence of an implicit double-net algorithm for nonexpansive semigroups and variational inequality problems

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## Abstract

In this paper, we show the hierarchical convergence of the following implicit double-net algorithm:

$$x_{s,t} = s[tf(x_{s,t}) + (1-t)(x_{s,t} - \mu Ax_{s,t})] + (1-s) \frac{1}{\lambda_s} \int_0^{\lambda_s} T(v)x_{s,t} dv, \quad \forall s, t \in (0, 1),$$

where  $f$  is a  $\rho$ -contraction on a real Hilbert space  $H$ ,  $A : H \rightarrow H$  is an  $\alpha$ -inverse strongly monotone mapping and  $S = \{T(s)\}_{s \geq 0} : H \rightarrow H$  is a nonexpansive semigroup with the common fixed points set  $\text{Fix}(S) \neq \emptyset$ , where  $\text{Fix}(S)$  denotes the set of fixed points of the mapping  $S$ , and, for each fixed  $t \in (0, 1)$ , the net  $\{x_{s,t}\}$  converges in norm as  $s \rightarrow 0$  to a common fixed point  $x_t \in \text{Fix}(S)$  of  $\{T(s)\}_{s \geq 0}$  and, as  $t \rightarrow 0$ , the net  $\{x_t\}$  converges in norm to the solution  $x^*$  of the following variational inequality:

$$\begin{cases} x^* \in \text{Fix}(S); \\ \langle Ax^*, x - x^* \rangle \geq 0, \forall x \in \text{Fix}(S). \end{cases}$$

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## 1 Introduction

In nonlinear analysis, a common approach to solving a problem with multiple solutions is to replace it by a family of perturbed problems admitting a unique solution and to obtain a particular solution as the limit of these perturbed solutions when the perturbation vanishes.

In this paper, we introduce a more general approach which consists in finding a particular part of the solution set of a given fixed point problem, i.e., fixed points which solve a variational inequality. More precisely, the goal of this paper is to present a method for finding hierarchically a fixed point of a nonexpansive semigroup  $S = \{T(s)\}_{s \geq 0}$  with respect to another monotone operator  $A$ , namely,

Find  $x^* \in \text{Fix}(S)$  such that

$$\langle Ax^*, x - x^* \rangle \geq 0, \quad \forall x \in \text{Fix}(S). \quad (1.1)$$

This is an interesting topic due to the fact that it is closely related to convex programming problems. For the related works, refer to [1-19].

This paper is devoted to solve the problem (1.1). For this purpose, we propose a double-net algorithm which generates a net  $\{x_{s,t}\}$  and prove that the net  $\{x_{s,t}\}$  hierarchically converges to the solution of the problem (1.1), that is, for each fixed  $t \in (0, 1)$ , the net  $\{x_{s,t}\}$  converges in norm as  $s \rightarrow 0$  to a common fixed point  $x_t \in \text{Fix}(S)$  of the nonexpansive semigroup  $\{T(s)\}_{s \geq 0}$  and, as  $t \rightarrow 0$ , the net  $\{x_t\}$  converges in norm to the unique solution  $x^*$  of the problem (1.1).

## 2 Preliminaries

Let  $H$  be a real Hilbert space with inner product  $\langle \cdot, \cdot \rangle$  and norm  $\|\cdot\|$ , respectively. Recall a mapping  $f: H \rightarrow H$  is called a contraction if there exists  $\rho \in [0, 1)$  such that

$$\|f(x) - f(y)\| \leq \rho \|x - y\|, \quad \forall x, y \in H.$$

A mapping  $T: C \rightarrow C$  is said to be nonexpansive if

$$\|Tx - Ty\| \leq \|x - y\|, \quad \forall x, y \in H.$$

Denote the set of fixed points of the mapping  $T$  by  $\text{Fix}(T)$ .

Recall also that a family  $S := \{T(s)\}_{s \geq 0}$  of mappings of  $H$  into itself is called a nonexpansive semigroup if it satisfies the following conditions:

- (S1)  $T(0)x = x$  for all  $x \in H$ ;
- (S2)  $T(s + t) = T(s)T(t)$  for all  $s, t \geq 0$ ;
- (S3)  $\|T(s)x - T(s)y\| \leq \|x - y\|$  for all  $x, y \in H$  and  $s \geq 0$ ;
- (S4) for all  $x \in H, s \rightarrow T(s)x$  is continuous.

We denote by  $\text{Fix}(T(s))$  the set of fixed points of  $T(s)$  and by  $\text{Fix}(S)$  the set of all common fixed points of  $S$ , i.e.,  $\text{Fix}(S) = \bigcap_{s \geq 0} \text{Fix}(T(s))$ . It is known that  $\text{Fix}(S)$  is closed and convex ([20], Lemma 1).

A mapping  $A$  of  $H$  into itself is said to be monotone if

$$\langle Au - Av, u - v \rangle \geq 0, \quad \forall u, v \in H,$$

and  $A: C \rightarrow H$  is said to be  $\alpha$ -inverse strongly monotone if there exists a positive real number  $\alpha$  such that

$$\langle Au - Av, u - v \rangle \geq \alpha \|Au - Av\|^2, \quad \forall u, v \in H.$$

It is obvious that any  $\alpha$ -inverse strongly monotone mapping  $A$  is monotone and  $\frac{1}{\alpha}$ -Lipschitz continuous.

Now, we introduce some lemmas for our main results in this paper.

**Lemma 2.1.** [21] *Let  $H$  be a real Hilbert space. Let the mapping  $A: H \rightarrow H$  be  $\alpha$ -inverse strongly monotone and  $\mu > 0$  be a constant. Then, we have*

$$\|(I - \mu A)x - (I - \mu A)y\|^2 \leq \|x - y\|^2 + \mu(\mu - 2\alpha)\|Ax - Ay\|^2, \quad \forall x, y \in H.$$

*In particular, if  $0 \leq \mu \leq 2\alpha$ , then  $I - \mu A$  is nonexpansive.*

**Lemma 2.2.** [22] *Let  $C$  be a nonempty bounded closed convex subset of a Hilbert space  $H$  and  $\{T(s)\}_{s \geq 0}$  be a nonexpansive semigroup on  $C$ . Then, for all  $h \geq 0$ ,*

$$\limsup_{t \rightarrow \infty} \sup_{x \in C} \left\| \frac{1}{t} \int_0^t T(s)x ds - T(h) \frac{1}{t} \int_0^t T(s)x ds \right\| = 0.$$

**Lemma 2.3.** [23] (Demiclosedness Principle for Nonexpansive Mappings) *Let  $C$  be a nonempty closed convex subset of a real Hilbert space  $H$  and  $T : C \rightarrow C$  be a nonexpansive mapping with  $\text{Fix}(T) \neq \emptyset$ . If  $\{x_n\}$  is a sequence in  $C$  converging weakly to a point  $x \in C$  and  $\{(I - T)x_n\}$  converges strongly to a point  $y \in C$ , then  $(I - T)x = y$ . In particular, if  $y = 0$ , then  $x \in \text{Fix}(T)$ .*

**Lemma 2.4.** *Let  $H$  be a real Hilbert space. Let  $f : H \rightarrow H$  be a  $\rho$ -contraction with coefficient  $\rho \in [0, 1)$  and  $A : H \rightarrow H$  be an  $\alpha$ -inverse strongly monotone mapping. Let  $\mu \in (0, 2\alpha)$  and  $t \in (0, 1)$ . Then, the variational inequality*

$$\begin{cases} x^* \in \text{Fix}(S); \\ \langle tf(z) + (1 - t)(I - \mu A)z - z, x^* - z \rangle \geq 0, \quad \forall z \in \text{Fix}(S), \end{cases} \tag{2.1}$$

is equivalent to its dual variational inequality

$$\begin{cases} x^* \in \text{Fix}(S); \\ \langle tf(x^*) + (1 - t)(I - \mu A)x^* - x^*, x^* - z \rangle \geq 0, \quad \forall z \in \text{Fix}(S). \end{cases} \tag{2.2}$$

*Proof.* Assume that  $x^* \in \text{Fix}(S)$  solves the problem (2.1). For all  $y \in \text{Fix}(S)$ , set

$$x = x^* + s(y - x^*) \in \text{Fix}(S), \quad \forall s \in (0, 1).$$

We note that

$$\langle tf(x) + (1 - t)(I - \mu A)x - x, x^* - x \rangle \geq 0.$$

Hence, we have

$$\langle tf(x^* + s(y - x^*)) + (1 - t)(I - \mu A)(x^* + s(y - x^*)) - x^* - s(y - x^*), s(x^* - y) \rangle \geq 0,$$

which implies that

$$\langle tf(x^* + s(y - x^*)) + (1 - t)(I - \mu A)(x^* + s(y - x^*)) - x^* - s(y - x^*), x^* - y \rangle \geq 0.$$

Letting  $s \rightarrow 0$ , we have

$$\langle tf(x^*) + (1 - t)(I - \mu A)(x^*) - x^*, x^* - y \rangle \geq 0,$$

which implies the point  $x^* \in \text{Fix}(S)$  is a solution of the problem (2.2).

Conversely, assume that the point  $x^* \in \text{Fix}(S)$  solves the problem (2.2). Then, we have

$$\langle tf(x^*) + (1 - t)(I - \mu A)x^* - x^*, x^* - z \rangle \geq 0.$$

Noting that  $I - f$  and  $A$  are monotone, we have

$$\langle (I - f)z - (I - f)x^*, z - x^* \rangle \geq 0$$

and

$$\langle Az - Ax^*, z - x^* \rangle \geq 0.$$

Thus, it follows that

$$t\langle(I - f)z - (I - f)x^*, z - x^*\rangle + (1 - t)\mu\langle Az - Ax^*, z - x^*\rangle \geq 0,$$

which implies that

$$\begin{aligned} &\langle tf(z) + (1 - t)(I - \mu A)z - z, x^* - z \rangle \\ &\geq \langle tf(x^*) + (1 - t)(I - \mu A)x^* - x^*, x^* - z \rangle \\ &\geq 0. \end{aligned}$$

This implies that the point  $x^* \in \text{Fix}(S)$  solves the problem (2.1). This completes the proof.  $\square$

### 3 Main results

In this section, we first introduce our double-net algorithm and then prove a strong convergence theorem for this algorithm.

Throughout, we assume that

(C1)  $H$  is a real Hilbert space;

(C2)  $f : H \rightarrow H$  is a  $\rho$ -contraction with coefficient  $\rho \in [0, 1)$ ,  $A : H \rightarrow H$  is an  $\alpha$ -inverse strongly monotone mapping, and  $S = \{T(s)\}_{s \geq 0} : H \rightarrow H$  is a nonexpansive semigroup with  $\text{Fix}(S) \neq \emptyset$ ;

(C3) the solution set  $\Omega$  of the problem (1.1) is nonempty;

(C4)  $\mu \in (0, 2\alpha)$  is a constant, and  $\{\lambda_s\}_{0 < s < 1}$  is a continuous net of positive real numbers satisfying  $\lim_{s \rightarrow 0} \lambda_s = +\infty$ .

For any  $s, t \in (0, 1)$ , we define the following mapping

$$x \mapsto W_{s,t}x := s[tf(x) + (1 - t)(x - \mu Ax)] + (1 - s) \frac{1}{\lambda_s} \int_0^{\lambda_s} T(v)x dv.$$

We note that the mapping  $W_{s,t}$  is a contraction. In fact, we have

$$\begin{aligned} \|W_{s,t}x - W_{s,t}y\| &= \left\| s[tf(x) + (1 - t)(x - \mu Ax)] + (1 - s) \frac{1}{\lambda_s} \int_0^{\lambda_s} T(v)x dv \right. \\ &\quad \left. - s[tf(y) + (1 - t)(y - \mu Ay)] - (1 - s) \frac{1}{\lambda_s} \int_0^{\lambda_s} T(v)y dv \right\| \\ &\leq st \|f(x) - f(y)\| + s(1 - t) \|(x - \mu Ax) - (y - \mu Ay)\| \\ &\quad + (1 - s) \left\| \frac{1}{\lambda_s} \int_0^{\lambda_s} (T(v)x - T(v)y) dv \right\| \\ &\leq st\rho \|x - y\| + s(1 - t) \|x - y\| + (1 - s) \|x - y\| \\ &= [1 - (1 - \rho)st] \|x - y\|, \end{aligned}$$

which implies that  $W_{s,t}$  is a contraction. Hence, by Banach's Contraction Principle,  $W_{s,t}$  has a unique fixed point, which is denoted  $x_{s,t} \in H$ , that is,  $x_{s,t}$  is the unique solution in  $H$  of the fixed point equation

$$\begin{aligned} x_{s,t} &= s[tf(x_{s,t}) + (1 - t)(x_{s,t} - \mu Ax_{s,t})] \\ &\quad + (1 - s) \frac{1}{\lambda_s} \int_0^{\lambda_s} T(v)x_{s,t} dv, \quad \forall s, t \in (0, 1). \end{aligned} \tag{3.1}$$

Now, we give some lemmas for our main result.

**Lemma 3.1.** *For each fixed  $t \in (0, 1)$ , the net  $\{x_{s,t}\}$  defined by (3.1) is bounded.*

*Proof.* Taking any  $z \in \text{Fix}(S)$ , since  $I - \mu A$  is nonexpansive (by Lemma 2.1), it follows from (3.1) that

$$\begin{aligned} & \|x_{s,t} - z\| \\ = & \left\| s[tf(x_{s,t}) + (1-t)(I - \mu A)x_{s,t}] + (1-s) \frac{1}{\lambda_s} \int_0^{\lambda_s} T(v)x_{s,t}dv - z \right\| \\ \leq & s \|tf(x_{s,t}) + (1-t)(I - \mu A)x_{s,t} - z\| + (1-s) \left\| \frac{1}{\lambda_s} \int_0^{\lambda_s} T(v)x_{s,t}dv - z \right\| \\ \leq & s [t \|f(x_{s,t}) - f(z)\| + t \|f(z) - z\| + (1-t) \|(I - \mu A)x_{s,t} - (I - \mu A)z\| \\ & + (1-t) \|(I - \mu A)z - z\|] + (1-s) \|x_{s,t} - z\| \\ \leq & s[t\rho \|x_{s,t} - z\| + t\|f(z) - z\| + (1-t)\|x_{s,t} - z\| + (1-t)\mu \|Az\| \\ & + (1-s) \|x_{s,t} - z\| \\ = & [1 - (1-\rho)s]t \|x_{s,t} - z\| + st\|f(z) - z\| + s(1-t)\mu \|Az\|. \end{aligned}$$

This implies that

$$\begin{aligned} \|x_{s,t} - z\| & \leq \frac{1}{(1-\rho)t} (t\|f(z) - z\| + (1-t)\mu \|Az\|) \\ & \leq \frac{1}{(1-\rho)t} \max\{\|f(z) - z\|, \mu \|Az\|\}. \end{aligned}$$

Thus, it follows that, for each fixed  $t \in (0, 1)$ ,  $\{x_{s,t}\}$  is bounded and so are the nets  $\{f(x_{s,t})\}$  and  $\{(I - \mu A)x_{s,t}\}$ . This completes the proof.  $\square$

**Lemma 3.2.**  $x_{s,t} \rightarrow x_t \in \text{Fix}(S)$  as  $s \rightarrow 0$ .

*Proof.* For each fixed  $t \in (0, 1)$ , we set  $R_t := \frac{1}{(1-\rho)t} \max\{\|f(z) - z\|, \mu \|Az\|\}$ . It is clear that, for each fixed  $t \in (0, 1)$ ,  $\{x_{s,t}\} \subset B(p, R_t)$ , where  $B(p, R_t)$  denotes a closed ball with the center  $p$  and radius  $R_t$ . Notice that

$$\left\| \frac{1}{\lambda_s} \int_0^{\lambda_s} T(v)x_{s,t}dv - p \right\| \leq \|x_{s,t} - p\| \leq R_t.$$

Moreover, we observe that if  $x \in B(p, R_t)$ , then

$$\|T(s)x - p\| \leq \|T(s)x - T(s)p\| \leq \|x - p\| \leq R_t,$$

that is,  $B(p, R_t)$  is  $T(s)$ -invariant for all  $s \in (0, 1)$ . From (3.1), it follows that

$$\begin{aligned} \|T(\tau)x_{s,t} - x_{s,t}\| & \leq \left\| T(\tau)x_{s,t} - T(\tau) \frac{1}{\lambda_s} \int_0^{\lambda_s} T(v)x_{s,t}dv \right\| \\ & \quad + \left\| T(\tau) \frac{1}{\lambda_s} \int_0^{\lambda_s} T(v)x_{s,t}dv - \frac{1}{\lambda_s} \int_0^{\lambda_s} T(v)x_{s,t}dv \right\| \\ & \quad + \left\| \frac{1}{\lambda_s} \int_0^{\lambda_s} T(v)x_{s,t}dv - x_{s,t} \right\| \\ & \leq \left\| T(\tau) \frac{1}{\lambda_s} \int_0^{\lambda_s} T(v)x_{s,t}dv - \frac{1}{\lambda_s} \int_0^{\lambda_s} T(v)x_{s,t}dv \right\| \\ & \quad + 2 \left\| x_{s,t} - \frac{1}{\lambda_s} \int_0^{\lambda_s} T(v)x_{s,t}dv \right\| \\ & \leq 2s \left\| tf(x_{s,t}) + (1-t)(x_{s,t} - \mu Ax_{s,t}) - \frac{1}{\lambda_s} \int_0^{\lambda_s} T(v)x_{s,t}dv \right\| \\ & \quad + \left\| T(\tau) \frac{1}{\lambda_s} \int_0^{\lambda_s} T(v)x_{s,t}dv - \frac{1}{\lambda_s} \int_0^{\lambda_s} T(v)x_{s,t}dv \right\|. \end{aligned}$$

By Lemma 2.2, for all  $0 \leq \tau < \infty$  and fixed  $t \in (0, 1)$ , we deduce

$$\lim_{s \rightarrow 0} \|T(\tau)x_{s,t} - x_{s,t}\| = 0. \tag{3.2}$$

Next, we show that, for each fixed  $t \in (0, 1)$ , the net  $\{x_{s,t}\}$  is relatively norm-compact as  $s \rightarrow 0$ . In fact, from Lemma 2.1, it follows that

$$\|x_{s,t} - \mu Ax_{s,t} - (z - \mu Az)\|^2 \leq \|x_{s,t} - z\|^2 + \mu(\mu - 2\alpha)\|Ax_{s,t} - Az\|^2. \tag{3.3}$$

By (3.1), we have

$$\begin{aligned} & \|x_{s,t} - z\|^2 \\ = & st\langle f(x_{s,t}) - f(z), x_{s,t} - z \rangle + st\langle f(z) - z, x_{s,t} - z \rangle \\ & + s(1-t)\langle (I - \mu A)x_{s,t} - (I - \mu A)z, x_{s,t} - z \rangle \\ & + s(1-t)\langle (I - \mu A)z - z, x_{s,t} - z \rangle \\ & + (1-s)\left\langle \frac{1}{\lambda_s} \int_0^{\lambda_s} T(v)X_{s,t} dv - z, x_{s,t} - z \right\rangle \\ \leq & st\|f(x_{s,t}) - f(z)\| \|x_{s,t} - z\| + st\langle f(z) - z, x_{s,t} - z \rangle \\ & + s(1-t)\|(I - \mu A)x_{s,t} - (I - \mu A)z\| \|x_{s,t} - z\| - s(1-t)\mu \langle Az, x_{s,t} - z \rangle \\ & + (1-s)\left\| \frac{1}{\lambda_s} \int_0^{\lambda_s} T(v)X_{s,t} dv - z \right\| \|x_{s,t} - z\| \\ \leq & st\rho \|x_{s,t} - z\|^2 + st\langle f(z) - z, x_{s,t} - z \rangle - s(1-t)\mu \langle Az, x_{s,t} - z \rangle \\ & + s(1-t)\|(I - \mu A)x_{s,t} - (I - \mu A)z\| \|x_{s,t} - z\| + (1-s)\|x_{s,t} - z\|^2 \\ \leq & st\rho \|x_{s,t} - z\|^2 + st\langle f(z) - z, x_{s,t} - z \rangle - s(1-t)\mu \langle Az, x_{s,t} - z \rangle \\ & + \frac{s(1-t)}{2} (\|(I - \mu A)x_{s,t} - (I - \mu A)z\|^2 + \|x_{s,t} - z\|^2) + (1-s)\|x_{s,t} - z\|^2. \end{aligned}$$

This together with (3.3) imply that

$$\begin{aligned} & \|x_{s,t} - z\|^2 \\ \leq & st\rho \|x_{s,t} - z\|^2 + st\langle f(z) - z, x_{s,t} - z \rangle - s(1-t)\mu \langle Az, x_{s,t} - z \rangle \\ & + \frac{s(1-t)}{2} (\|x_{s,t} - z\|^2 + \mu(\mu - 2\alpha)\|Ax_{s,t} - Az\|^2 + \|x_{s,t} - z\|^2) + (1-s)\|x_{s,t} - z\|^2 \\ \leq & [1 - (1 - \rho)st]\|x_{s,t} - z\|^2 + st\langle f(z) - z, x_{s,t} - z \rangle \\ & - s(1-t)\mu \langle Az, x_{s,t} - z \rangle, \end{aligned}$$

which implies that

$$\begin{aligned} & \|x_{s,t} - z\|^2 \\ \leq & \frac{1}{(1 - \rho)t} \langle tf(z) + (1-t)(I - \mu A)z - z, x_{s,t} - z \rangle, \quad \forall z \in \text{Fix}(S). \end{aligned} \tag{3.4}$$

Assume that  $\{s_n\} \subset (0, 1)$  is such that  $s_n \rightarrow 0$  as  $n \rightarrow \infty$ . By (3.4), we obtain immediately that

$$\begin{aligned} & \|x_{s_n,t} - z\|^2 \\ \leq & \frac{1}{(1 - \rho)t} \langle tf(z) + (1-t)(I - \mu A)z - z, x_{s_n,t} - z \rangle, \quad \forall z \in \text{Fix}(S). \end{aligned} \tag{3.5}$$

Since  $\{x_{s_n,t}\}$  is bounded, without loss of generality, we may assume that, as  $s_n \rightarrow 0$ ,  $\{x_{s_n,t}\}$  converges weakly to a point  $x_t$ . From (3.2) and Lemma 2.3, we get  $x_t \in \text{Fix}(S)$ .

Further, if we substitute  $x_t$  for  $z$  in (3.5), then it follows that

$$\|x_{s_n,t} - x_t\|^2 \leq \frac{1}{(1-\rho)t} \langle tf(x_t) + (1-t)(I - \mu A)x_t - x_t, x_{s_n,t} - x_t \rangle.$$

Therefore, the weak convergence of  $\{x_{s_n,t}\}$  to  $x_t$  actually implies that  $x_{s_n,t} \rightarrow x_t$  strongly. This has proved the relative norm-compactness of the net  $\{x_{s,t}\}$  as  $s \rightarrow 0$ .

Now, if we take the limit as  $n \rightarrow \infty$  in (3.5), we have

$$\begin{aligned} & \|x_t - z\|^2 \\ & \leq \frac{1}{(1-\rho)t} \langle tf(z) + (1-t)(I - \mu A)z - z, x_t - z \rangle, \quad \forall z \in \text{Fix}(S). \end{aligned}$$

In particular,  $x_t$  solves the following variational inequality:

$$\begin{cases} x_t \in \text{Fix}(S); \\ \langle tf(z) + (1-t)(I - \mu A)z - z, x_t - z \rangle \geq 0, \quad \forall z \in \text{Fix}(S), \end{cases}$$

or the equivalent dual variational inequality (see Lemma 2.4):

$$\begin{cases} x_t \in \text{Fix}(S); \\ \langle tf(x_t) + (1-t)(I - \mu A)x_t - x_t, x_t - z \rangle \geq 0, \quad \forall z \in \text{Fix}(S). \end{cases} \quad (3.6)$$

Notice that (3.6) is equivalent to the fact that  $x_t = P_{\text{Fix}(S)}(tf + (1-t)(I - \mu A))x_t$ , that is,  $x_t$  is the unique element in  $\text{Fix}(S)$  of the contraction  $P_{\text{Fix}(S)}(tf + (1-t)(I - \mu A))$ . Clearly, it is sufficient to conclude that the entire net  $\{x_{s,t}\}$  converges in norm to  $x_t \in \text{Fix}(S)$  as  $s \rightarrow 0$ . This completes the proof.  $\square$

**Lemma 3.3.** *The net  $\{x_t\}$  is bounded.*

*Proof.* In (3.6), if we take any  $y \in \Omega$ , then we have

$$\langle tf(x_t) + (1-t)(I - \mu A)x_t - x_t, x_t - y \rangle \geq 0. \quad (3.7)$$

By virtue of the monotonicity of  $A$  and the fact that  $y \in \Omega$ , we have

$$\langle (I - \mu A)x_t - x_t, x_t - y \rangle \leq \langle (I - \mu A)y - y, x_t - y \rangle \leq 0. \quad (3.8)$$

Thus, it follows from (3.7) and (3.8) that

$$\langle f(x_t) - x_t, x_t - y \rangle \geq 0, \quad \forall y \in \Omega \quad (3.9)$$

and hence

$$\begin{aligned} \|x_t - y\|^2 & \leq \langle x_t - y, x_t - y \rangle + \langle f(x_t) - x_t, x_t - y \rangle \\ & = \langle f(x_t) - f(y), x_t - y \rangle + \langle f(y) - y, x_t - y \rangle \\ & \leq \rho \|x_t - y\|^2 + \langle f(y) - y, x_t - y \rangle. \end{aligned}$$

Therefore, we have

$$\|x_t - y\|^2 \leq \frac{1}{1-\rho} \langle f(y) - y, x_t - y \rangle, \quad \forall y \in \Omega. \quad (3.10)$$

In particular,

$$\|x_t - y\| \leq \frac{1}{1-\rho} \|f(y) - y\|, \quad \forall t \in (0, 1),$$

which implies that  $\{x_t\}$  is bounded. This completes the proof.  $\square$

**Lemma 3.4.** *If the net  $\{x_t\}$  converges in norm to a point  $x^* \in \Omega$ , then the point solves the variational inequality*

$$\langle (I - f)x^*, x - x^* \rangle \geq 0, \quad \forall x \in \Omega. \tag{3.11}$$

*Proof.* First, we note that the solution of the variational inequality (3.11) is unique.

Next, we prove that  $\omega_w(x_t) \subset \Omega$ , that is, if  $(t_n)$  is a null sequence in  $(0, 1)$  such that  $x_{t_n} \rightarrow x'$  weakly as  $n \rightarrow \infty$ , then  $x' \in \Omega$ . To see this, we use (3.6) to get

$$\langle \mu Ax_t, z - x_t \rangle \geq \frac{t}{1-t} \langle (I - f)x_t, x_t - z \rangle, \quad \forall z \in \text{Fix}(S).$$

However, since  $A$  is monotone, we have

$$\langle Az, z - x_t \rangle \geq \langle Ax_t, z - x_t \rangle.$$

Combining the last two relations yields that

$$\langle \mu Az, z - x_t \rangle \geq \frac{t}{1-t} \langle (I - f)x_t, x_t - z \rangle, \quad \forall z \in \text{Fix}(S). \tag{3.12}$$

Letting  $t = t_n \rightarrow 0$  as  $n \rightarrow \infty$  in (3.12), we get

$$\langle Az, z - x' \rangle \geq 0, \quad \forall z \in \text{Fix}(S),$$

which is equivalent to its dual variational inequality

$$\langle Ax', z - x' \rangle \geq 0, \quad \forall z \in \text{Fix}(S).$$

That is,  $x'$  is a solution of the problem (1.1) and hence  $x' \in \Omega$ .

Finally, we prove that  $x' = x^*$ , the unique solution of the variational inequality (3.11). In fact, by (3.10), we have

$$\|x_{t_n} - x'\|^2 \leq \frac{1}{1-\rho} \langle f(x') - x', x_{t_n} - x' \rangle, \quad \forall x' \in \Omega.$$

Therefore, the weak convergence to  $x'$  of  $\{x_{t_n}\}$  implies that  $x_{t_n} \rightarrow x'$  in norm. Thus, if we let  $t = t_n \rightarrow 0$  in (3.10), then we have

$$\langle f(x') - x', \gamma - x' \rangle \leq 0, \quad \forall \gamma \in \Omega,$$

which implies that  $x' \in \Omega$  solves the problem (3.11). By the uniqueness of the solution, we have  $x' = x^*$  and it is sufficient to guarantee that  $x_t \rightarrow x^*$  in norm as  $t \rightarrow 0$ . This completes the proof.  $\square$

Thus, by the above lemmas, we can obtain immediately the following theorem.

**Theorem 3.5.** *For each  $(s, t) \in (0, 1) \times (0, 1)$ , let  $\{x_s, t\}$  be a double-net algorithm defined implicitly by (3.1). Then, the net  $\{x_s, t\}$  hierarchically converges to the unique solution  $x^*$  of the hierarchical fixed point problem and the variational inequality problem (1.1), that is, for each fixed  $t \in (0, 1)$ , the net  $\{x_s, t\}$  converges in norm as  $s \rightarrow 0$  to a common fixed point  $x_t \in \text{Fix}(S)$  of the nonexpansive semigroup  $\{T(s)\}_{s \geq 0}$ . Moreover, as  $t \rightarrow 0$ , the net  $\{x_t\}$  converges in norm to the unique solution  $x^* \in \Omega$  and the point  $x^*$*



also solves the following variational inequality.

$$\begin{cases} x^* \in \Omega; \\ \langle (I - f)x^*, x - x^* \rangle \geq 0, \quad \forall x \in \Omega. \end{cases}$$

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#### Authors' contributions

All authors read and approved the final manuscript.

#### Competing interests

The authors declare that they have no competing interests.

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