# On vector matrix game and symmetric dual vector optimization problem 

Jeong Min Hong ${ }^{1}$, Moon Hee Kim² and Gue Myung Lee ${ }^{1 *}$

"Correspondence:
gmlee@pknu.ac.kr
'Department of Applied Mathematics, Pukyong National University, Busan, 608-737, Korea Full list of author information is available at the end of the article


#### Abstract

A vector matrix game with more than two skew symmetric matrices, which is an extension of the matrix game, is defined and the symmetric dual problem for a nonlinear vector optimization problem is considered. Using the Kakutani fixed point theorem, we prove an existence theorem for a vector matrix game. We establish equivalent relations between the symmetric dual problem and its related vector matrix game. Moreover, we give an example illustrating the equivalent relations.


## 1 Introduction

A matrix game is defined by $B$ of a real $m \times n$ matrix together with the Cartesian product $S_{n} \times S_{m}$ of all $n$-dimensional probability vectors $S_{n}$ and all $m$-dimensional probability vectors $S_{m}$; that is, $S_{n}:=\left\{x=\left(x_{1}, \ldots, x_{n}\right)^{T} \in \mathbb{R}^{n}: x_{i} \geqq 0, \sum_{i=1}^{n} x_{i}=1\right\}$, where the symbol ${ }^{T}$ denotes the transpose. A point $(\bar{x}, \bar{y}) \in S_{n} \times S_{n}$ is called an equilibrium point of a matrix game $B$ if $x^{T} B \bar{y} \leqq \bar{x}^{T} B \bar{y} \leqq \bar{x}^{T} B y$ for all $x, y \in S_{n}$ and $\bar{x} B \bar{y}=v$, where $v$ is value of the game. If $n=m$ and $B$ is skew symmetric, then we can check that $(\bar{x}, \bar{y}) \in S_{n} \times S_{n}$ is an equilibrium point of the game $B$ if and only if $B \bar{x} \leqq 0$ and $B \bar{y} \leqq 0$. When $B$ is an $n \times n$ skew symmetric matrix, $\bar{x} \in S_{n}$ is called a solution of the matrix game $B$ if $B \bar{x} \leqq 0$ [1].
Consider the linear programming problem (LP) and its dual (LD) as follows:
(LP) Minimize $c^{T} x \quad$ subject to $A x \geqq b, x \geqq 0$,
(LD) Maximize $b^{T} y \quad$ subject to $A^{T} y \leqq c, y \geqq 0$,
where $c \in \mathbb{R}^{n}, x \in \mathbb{R}^{n}, b \in \mathbb{R}^{m}, y \in \mathbb{R}^{m}, A=\left[a_{i j}\right]$ is an $m \times n$ real matrix.
Now consider the matrix game associated with the following $(n+m+1) \times(n+m+1)$ skew symmetric matrix $B$ :

$$
B=\left[\begin{array}{ccc}
0 & A^{T} & -c \\
-A & 0 & b \\
c^{T} & -b^{T} & 0
\end{array}\right] .
$$

Dantzig [1] gave the complete equivalence between the linear programming duality and the matrix game $B$. Many authors [2-5] have extended the equivalence results of Dantzig [1] to several kinds of scalar optimization problems. Very recently, Hong and Kim [6] defined a vector matrix game and generalized the equivalence results of Dantzig [1] to a vector optimization problem by using the vector matrix game.
Recently, Kim and Noh [4] established equivalent relations between a certain matrix game and symmetric dual problems. Symmetric duality in nonlinear programming, in

[^0]which the dual of the dual is the primal, was first introduced by Dorn [7]. Dantzig, Eisenberg and Cottle [8] formulated a pair of symmetric dual nonlinear problems and established duality results for convex and concave functions with non-negative orthant as the cone. Mond and Weir [9] presented two pairs of symmetric dual vector optimization problems and obtained symmetric duality results concerning pseudoconvex and pseudoconcave functions.
In this paper, a vector matrix game with more than two skew symmetric matrices, which is an extension of the matrix game, is defined and a nonlinear vector optimization problem is considered. We formulate a symmetric dual problem for the nonlinear vector optimization problem and establish equivalent relations between the symmetric dual problem and the corresponding vector matrix game. Moreover, we give a numerical example for showing such equivalent relations.

## 2 Vector matrix game and existence theorem

Throughout this paper, we will denote the relative interior of $S_{p}$ by $\stackrel{o}{S}_{p}$, and we will use the following conventions for vectors in the Euclidean space $\mathbb{R}^{n}$ for vectors $x:=\left(x_{1}, \ldots, x_{n}\right)$ and $y:=\left(y_{1}, \ldots, y_{n}\right)$ :

$$
\begin{aligned}
& x \leqq y \text { if and only if } x_{i} \leqq y_{i}, \quad i=1, \ldots, n ; \\
& x<y \text { if and only if } x_{i}<y_{i}, \quad i=1, \ldots, n ; \\
& x \leq y \text { if and only if } x_{i} \leqq y_{i}, \text { and } x \neq y ; \text { and } \\
& x \not \leq y \text { is the negation of } x \leq y .
\end{aligned}
$$

Consider the nonlinear programming problem (VOP):
$(\mathrm{VOP})$ Minimize $f(x):=\left(f_{1}(x), \ldots, f_{p}(x)\right)$
subject to $x \in X$,
where $X=\left\{x \in \mathbb{R}^{n}: g(x) \geqq b, x \geqq 0\right\}, f: \mathbb{R}^{n} \rightarrow \mathbb{R}^{p}, g: \mathbb{R}^{n} \rightarrow \mathbb{R}^{m}$ are continuously differentiable. The gradient $\nabla f(x)$ is an $n \times p$ matrix, and $\nabla g(x)$ is an $n \times m$ matrix.

Definition 2.1 [10] A point $\bar{x} \in X$ is said to be an efficient solution for (VOP) if there exists no other feasible point $x \in X$ such that $\left(f_{1}(x), \ldots, f_{p}(x)\right) \leq\left(f_{1}(\bar{x}), \ldots, f_{p}(\bar{x})\right)$.

Now, we define solutions for a vector matrix game as follows.

Definition 2.2 [6] Let $B_{i}, i=1, \ldots, p$, be real $n \times n$ skew-symmetric matrices. A point $\bar{x} \in S_{n}$ is said to be a vector solution of the vector matrix game $B_{i}, i=1, \ldots, p$ if $\left(\bar{x}^{T} B_{1} x, \ldots, \bar{x}^{T} B_{p} x\right) \not \leq\left(\bar{x}^{T} B_{1} \bar{x}, \ldots, \bar{x}^{T} B_{p} \bar{x}\right) \not \leq\left(x^{T} B_{1} \bar{x}, \ldots, x^{T} B_{p} \bar{x}\right)$ for any $x \in S_{n}$.

We proved the characterization of a vector solution of the vector matrix game in [6].

Lemma 2.1 [6] Let $B_{i}, i=1, \ldots, p$, be an $n \times n$ skew symmetric matrix. Then $\bar{y} \in S_{n}$ is a vector solution of the vector matrix game $B_{i}, i=1, \ldots, p$, if and only if there exists $\xi \in \stackrel{o}{S}_{p}$ such that $\left(\sum_{i=1}^{p} \xi_{i} B_{i}\right) \bar{y} \leqq 0$.

Remark 2.1 Let $B_{i}, i=1, \ldots, p$, be an $n \times n$ skew symmetric matrix. From Lemma 2.1, we can obtain the following remark saying that the vector matrix game can be solved by fixed point problems; $\bar{y} \in S_{n}$ is a vector solution of the vector matrix game $B_{i}, i=1, \ldots, p$, if and only if there exists $\xi \in \stackrel{o}{S}_{p}$ such that $\bar{y} \in F_{\xi}(\bar{y})$, where $F_{\xi}(x)=\left\{y \in S_{n} \mid y \in x-\left(\sum_{i=1}^{p} \xi_{i} B_{i}\right) x-\right.$ $\left.\mathbb{R}_{+}^{n}\right\}$.

Noticing Remark 2.1, we can obtain an existence theorem for the vector matrix game.

Theorem 2.1 Let $B_{i}, i=1, \ldots, p$, be an $n \times n$ skew symmetric matrix. Then there exists $a$ vector solution of the vector matrix game $B_{i}, i=1, \ldots, p$.

Proof Let $\xi \in \stackrel{o}{S}_{p}$. Define a multifunction $F_{\xi}: S_{n} \rightarrow S_{n}$ by, for any $x \in S_{n}$,

$$
F_{\xi}(x)=\left\{y \in S_{n} \mid y \in x-\left(\sum_{i=1}^{p} \xi_{i} B_{i}\right) x-\mathbb{R}_{+}^{n}\right\} .
$$

Then the multifunction $F_{\xi}$ is closed and hence upper semi-continuous, and so it follows from the well-known Kakutani fixed point theorem [11] that the multifunction $F_{\xi}$ has a fixed point. So, by Remark 2.1, there exists a vector solution of the vector matrix game $B_{i}$, $i=1, \ldots, p$.

## 3 Equivalence relations

Now, we consider the nonlinear symmetric programming problem (SP) together with its dual (SD) as follows:

$$
\begin{align*}
& \text { Minimize }\left(f_{1}(x, y)-y^{T} \nabla_{y}\left(\lambda^{T} f\right)(x, y), \ldots, f_{p}(x, y)-y^{T} \nabla_{y}\left(\lambda^{T} f\right)(x, y)\right)  \tag{SP}\\
& \text { subject to }-\nabla_{y}\left(\lambda^{T} f\right)(x, y) \geqq 0, \\
& x \geqq 0, \quad \lambda>0, \\
& \text { Maximize }\left(f_{1}(u, v)-u^{T} \nabla_{u}\left(\lambda^{T} f\right)(u, v), \ldots, f_{p}(u, v)-u^{T} \nabla_{u}\left(\lambda^{T} f\right)(u, v)\right)  \tag{SD}\\
& \text { subject to }-\nabla_{u}\left(\lambda^{T} f\right)(u, v) \leqq 0, \\
& v \geqq 0, \quad \lambda>0,
\end{align*}
$$

where $f:=\left(f_{1}, \ldots, f_{p}\right): \mathbb{R}^{n} \times \mathbb{R}^{m} \rightarrow \mathbb{R}^{p}$ are continuously differentiable.
Consider the vector matrix game defined by the following $(n+m+1) \times(n+m+1)$ skew symmetric matrix $B_{i}(x, y), i=1, \ldots, p$, related to (SP) and (SD):

$$
B_{i}(x, y)=\left[\begin{array}{ccc}
0 & -x \nabla_{y} f_{i}(x, y)^{T} & -\nabla_{x} f_{i}(x, y) \\
\nabla_{y} f_{i}(x, y) x^{T} & 0 & \nabla_{y} f_{i}(x, y) \\
\nabla_{x} f_{i}(x, y)^{T} & -\nabla_{y} f_{i}(x, y)^{T} & 0
\end{array}\right] .
$$

Now, we give equivalent relations between (SD) and the vector matrix game $B_{i}(x, y)$, $i=1, \ldots, p$.

Theorem 3.1 Let $(\bar{x}, \bar{y}, \bar{\xi})$ be feasiblefor $(\mathrm{SP})$ and (SD), with $\bar{y}^{T} \nabla_{y}\left(\bar{\xi}^{T} f\right)(\bar{x}, \bar{y})=\bar{x}^{T} \nabla_{x}\left(\bar{\xi}^{T} f\right) \times$ $(\bar{x}, \bar{y})=0$. Let $z^{*}=1 /\left(1+\sum_{i} \bar{x}_{i}+\sum_{j} \bar{y}_{j}\right), x^{*}=z^{* *} \bar{x}$ and $y^{*}=z^{*} \bar{y}$. Then $\left(x^{*}, y^{*}, z^{*}\right)$ is a vector solution of the vector matrix game $B_{i}(\bar{x}, \bar{y}), i=1, \ldots, p$.

Proof Let $(\bar{x}, \bar{y}, \bar{\xi})$ be feasible for (SP) and (SD). Then the following holds:

$$
\begin{align*}
& -\nabla_{y}\left(\bar{\xi}^{T} f\right)(\bar{x}, \bar{y}) \geqq 0  \tag{3.1}\\
& -\nabla_{x}\left(\bar{\xi}^{T} f\right)(\bar{x}, \bar{y}) \leqq 0  \tag{3.2}\\
& \bar{y}^{T} \nabla_{y}\left(\bar{\xi}^{T} f\right)(\bar{x}, \bar{y})=\bar{x}^{T} \nabla_{x}\left(\bar{\xi}^{T} f\right)(\bar{x}, \bar{y})=0,  \tag{3.3}\\
& \bar{x} \geqq 0, \quad \bar{y} \geqq 0, \quad \bar{\xi} \in \stackrel{o}{S}_{p} \tag{3.4}
\end{align*}
$$

Multiplying (3.3) by $\bar{x} \geqq 0$ gives $-\bar{x} \nabla_{y}\left(\bar{\xi}^{T} f\right)(\bar{x}, \bar{y})^{T} \bar{y}=0$ and from (3.2),

$$
\begin{equation*}
-\bar{x} \nabla_{y}\left(\bar{\xi}^{T} f\right)(\bar{x}, \bar{y})^{T} \bar{y}-\nabla_{x}\left(\bar{\xi}^{T} f\right)(\bar{x}, \bar{y}) \leqq 0 . \tag{3.5}
\end{equation*}
$$

Multiplying (3.1) by $\bar{x}^{T} \bar{x} \geqq 0, \nabla_{y}\left(\bar{\xi}^{T} f\right)(\bar{x}, \bar{y}) \bar{x}^{T} \bar{x} \leqq 0$. It implies that since $\nabla_{y}\left(\bar{\xi}^{T} f\right)(\bar{x}, \bar{y}) \leqq 0$,

$$
\begin{equation*}
\nabla_{y}\left(\bar{\xi}^{T} f\right)(\bar{x}, \bar{y}) \bar{x}^{T} \bar{x}+\nabla_{y}\left(\bar{\xi}^{T} f\right)(\bar{x}, \bar{y}) \leqq 0 . \tag{3.6}
\end{equation*}
$$

From (3.3) we have

$$
\begin{equation*}
\nabla_{x}\left(\bar{\xi}^{T} f\right)(\bar{x}, \bar{y})^{T} \bar{x}-\nabla_{y}\left(\bar{\xi}^{T} f\right)(\bar{x}, \bar{y})^{T} \bar{y}=0 . \tag{3.7}
\end{equation*}
$$

But $z^{*}>0$ by (3.4), from (3.5), (3.6) and (3.7), we get

$$
\begin{align*}
& -\bar{x} \nabla_{y}\left(\bar{\xi}^{T} f\right)(\bar{x}, \bar{y})^{T} y^{*}-\nabla_{x}\left(\bar{\xi}^{T} f\right)(\bar{x}, \bar{y}) z^{*} \leqq 0,  \tag{3.8}\\
& \nabla_{y}\left(\bar{\xi}^{T} f\right)(\bar{x}, \bar{y}) \bar{x}^{T} x^{* *}+\nabla_{y}\left(\bar{\xi}^{T} f\right)(\bar{x}, \bar{y}) z^{*} \leqq 0,  \tag{3.9}\\
& \nabla_{x}\left(\bar{\xi}^{T} f\right)(\bar{x}, \bar{y})^{T} x^{*}-\nabla_{y}\left(\bar{\xi}^{T} f\right)(\bar{x}, \bar{y})^{T} y^{*}=0,  \tag{3.10}\\
& x^{*} \geqq 0, \quad y^{*} \geqq 0, \quad z^{*}>0 .
\end{align*}
$$

From (3.8), (3.9) and (3.10), we have the following inequality:

$$
\left(\sum_{i=1}^{p} \bar{\xi}_{i} B_{i}(\bar{x}, \bar{y})\right)\left(\begin{array}{l}
x^{*} \\
y^{*} \\
z^{*}
\end{array}\right) \leqq 0 .
$$

By Lemma 2.1, $\left(x^{*}, y^{*}, z^{*}\right)$ is a vector solution of the vector matrix game $B_{i}(\bar{x}, \bar{y}), i=1, \ldots, p$.

Theorem 3.2 Let $\left(x^{*}, y^{*}, z^{*}\right)$ with $z^{*}>0$ be a vector solution of the vector matrix game $B_{i}(\bar{x}, \bar{y}), i=1, \ldots, p$, where $\bar{x}=x^{*} / z^{*}$ and $\bar{y}=y^{*} / z^{*}$. Then there exists $\bar{\xi} \in \stackrel{o}{S}_{p}$ such that $(\bar{x}, \bar{y}, \bar{\xi})$ is feasible for (SP) and (SD), and $\bar{y}^{T} \nabla_{y}\left(\bar{\xi}^{T} f\right)(\bar{x}, \bar{y})=\bar{x}^{T} \nabla_{x}\left(\bar{\xi}^{T} f\right)(\bar{x}, \bar{y})=0$. Moreover, iff $f_{i}(\cdot, y)$, $i=1, \ldots, p$, are convex for fixed $y$ and $f_{i}(x, \cdot), i=1, \ldots, p$, are concave for fixed $x$, then $(\bar{x}, \bar{y})$ is efficient for (SP) with fixed $\bar{\xi}$ and $(\bar{x}, \bar{y})$ is efficient for (SD) with fixed $\bar{\xi}$.

Proof Let $\left(x^{*}, y^{*}, z^{*}\right)$ with $z^{*}>0$ be a vector solution of the vector matrix game $B_{i}(\bar{x}, \bar{y})$, $i=1, \ldots, p$. Then by Lemma 2.1, there exists $\bar{\xi} \in \stackrel{o}{S}_{p}$ such that

$$
\left(\sum_{i=1}^{p} \bar{\xi}_{i} B_{i}(\bar{x}, \bar{y})\right)\left(\begin{array}{l}
x^{*} \\
y^{*} \\
z^{*}
\end{array}\right) \leqq 0
$$

Thus, we get

$$
\begin{align*}
& -\bar{x} \nabla_{y}\left(\bar{\xi}^{T} f\right)(\bar{x}, \bar{y})^{T} y^{*}-\nabla_{x}\left(\bar{\xi}^{T} f\right)(\bar{x}, \bar{y}) z^{*} \leqq 0,  \tag{3.11}\\
& \nabla_{y}\left(\bar{\xi}^{T} f\right)(\bar{x}, \bar{y}) \bar{x}^{T} x^{*}+\nabla_{y}\left(\bar{\xi}^{T} f\right)(\bar{x}, \bar{y}) z^{*} \leqq 0,  \tag{3.12}\\
& \nabla_{x}\left(\bar{\xi}^{T} f\right)(\bar{x}, \bar{y})^{T} x^{*}-\nabla_{y}\left(\bar{\xi}^{T} f\right)(\bar{x}, \bar{y})^{T} y^{*} \leqq 0,  \tag{3.13}\\
& x^{*} \geqq 0, \quad y^{*} \geqq 0, \quad z^{*}>0 . \tag{3.14}
\end{align*}
$$

Dividing (3.11), (3.12) and (3.13) by $z^{*}>0$, we have

$$
\begin{align*}
& -\bar{x} \nabla_{y}\left(\bar{\xi}^{T} f\right)(\bar{x}, \bar{y})^{T} \bar{y}-\nabla_{x}\left(\bar{\xi}^{T} f\right)(\bar{x}, \bar{y}) \leqq 0,  \tag{3.15}\\
& \nabla_{y}\left(\bar{\xi}^{T} f\right)(\bar{x}, \bar{y})^{T} \bar{x}+\nabla_{y}\left(\bar{\xi}^{T} f\right)(\bar{x}, \bar{y}) \leqq 0,  \tag{3.16}\\
& \nabla_{x}\left(\bar{\xi}^{T} f\right)(\bar{x}, \bar{y})^{T} \bar{x}-\nabla_{y}\left(\bar{\xi}^{T} f\right)(\bar{x}, \bar{y})^{T} \bar{y} \leqq 0 . \tag{3.17}
\end{align*}
$$

From (3.14),

$$
\begin{equation*}
\bar{x} \geqq 0, \quad \bar{y} \geqq 0 . \tag{3.18}
\end{equation*}
$$

By (3.16), $\nabla_{y}\left(\bar{\xi}^{T} f\right)(\bar{x}, \bar{y})\left(\bar{x}^{T} \bar{x}+1\right) \leqq 0$. It implies that since $\bar{x}^{T} \bar{x}+1>0$,

$$
\begin{equation*}
-\nabla_{y}\left(\bar{\xi}^{T} f\right)(\bar{x}, \bar{y}) \geqq 0 . \tag{3.19}
\end{equation*}
$$

From (3.15), $-\bar{x} \nabla_{y}\left(\bar{\xi}^{T} f\right)(\bar{x}, \bar{y})^{T} \bar{y} \leqq \nabla_{x}\left(\bar{\xi}^{T} f\right)(\bar{x}, \bar{y})$. Using (3.18) and (3.19), we obtain $0 \leqq$ $-\bar{x} \nabla_{y}\left(\bar{\xi}^{T} f\right)(\bar{x}, \bar{y})^{T} \bar{y} \leqq \nabla_{x}\left(\bar{\xi}^{T} f\right)(\bar{x}, \bar{y})$. It implies that $-\nabla_{x}\left(\bar{\xi}^{T} f\right)(\bar{x}, \bar{y}) \leqq 0$. From (3.17), $\bar{x}^{T} \nabla_{x}\left(\bar{\xi}^{T} f\right)(\bar{x}, \bar{y}) \leqq \bar{y}^{T} \nabla_{y}\left(\bar{\xi}^{T} f\right)(\bar{x}, \bar{y})$. But since $\bar{x} \geqq 0$ and $\nabla_{x}\left(\bar{\xi}^{T} f\right)(\bar{x}, \bar{y}) \geqq 0, \bar{x}^{T} \nabla_{x}\left(\bar{\xi}^{T} f\right)(\bar{x}, \bar{y}) \geqq$ 0 and since $\bar{y} \geqq 0$ and $\nabla_{y}\left(\bar{\xi}^{T} f\right)(\bar{x}, \bar{y}) \leqq 0, \bar{y}^{T} \nabla_{y}\left(\bar{\xi}^{T} f\right)(\bar{x}, \bar{y}) \leqq 0$. Then we have

$$
0 \leqq \bar{x}^{T} \nabla_{x}\left(\bar{\xi}^{T} f\right)(\bar{x}, \bar{y}) \leqq \bar{y}^{T} \nabla_{y}\left(\bar{\xi}^{T} f\right)(\bar{x}, \bar{y}) \leqq 0
$$

Hence, $\bar{x}^{T} \nabla_{x}\left(\bar{\xi}^{T} f\right)(\bar{x}, \bar{y})=\bar{y}^{T} \nabla_{y}\left(\bar{\xi}^{T} f\right)(\bar{x}, \bar{y})$. Thus, $(\bar{x}, \bar{y}, \bar{\xi})$ is feasible for (SP) and (SD) with $f_{i}(\bar{x}, \bar{y})-\bar{y}^{T} \nabla_{y}\left(\bar{\xi}^{T} f\right)(\bar{x}, \bar{y})=f_{i}(\bar{x}, \bar{y})-\bar{x}^{T} \nabla_{x}\left(\bar{\xi}^{T} f\right)(\bar{x}, \bar{y}), i=1, \ldots, p$. Since $(\bar{x}, \bar{y}, \bar{\xi})$ is feasible for (SD), by weak duality in [9], $\left(f_{1}(x, y)-y^{T} \nabla_{y}\left(\xi^{T} f\right)(x, y), \ldots, f_{p}(x, y)-y^{T} \nabla_{y}\left(\xi^{T} f\right)(x, y)\right) \not \leq$ $\left(f_{1}(\bar{x}, \bar{y})-\bar{y}^{T} \nabla_{y}\left(\bar{\xi}^{T} f\right)(\bar{x}, \bar{y}), \ldots, f_{p}(\bar{x}, \bar{y})-\bar{y}^{T} \nabla_{y}\left(\bar{\xi}^{T} f\right)(\bar{x}, \bar{y})\right)$ and $\left(f_{1}(\bar{x}, \bar{y})-\bar{x}^{T} \nabla_{x}\left(\bar{\xi}^{T} f\right)(\bar{x}, \bar{y}), \ldots, f_{p}(\bar{x}, \bar{y})-\right.$ $\left.\bar{x}^{T} \nabla_{x}\left(\bar{\xi}^{T} f\right)(\bar{x}, \bar{y})\right) \not \leq\left(f_{1}(u, v)-u^{T} \nabla_{u}\left(\xi^{T} f\right)(u, v), \ldots, f_{p}(u, v)-u^{T} \nabla_{u}\left(\xi^{T} f\right)(u, v)\right)$ for any feasible ( $u, v, \xi$ ) of (SP) and (SD). Therefore, ( $\bar{x}, \bar{y}$ ) is efficient for (SP) with fixed $\bar{\xi}$ and $(\bar{x}, \bar{y})$ is efficient for (SD) with fixed $\bar{\xi}$.

Now, we give an example illustrating Theorems 3.1 and 3.2.

Example 3.1 Let $f_{1}(x, y)=x^{2}-y^{2}$ and $f_{2}(x, y)=y-x$. Consider the following vector optimization problem (SP) together with its dual (SD) as follows:
(SP) Minimize $\left(x^{2}-y^{2}+2 \lambda_{1} y^{2}-\lambda_{2} y, y-x+2 \lambda_{1} y^{2}-\lambda_{2} y\right)$ subject to $2 \lambda_{1} y-\lambda_{2} \geqq 0$,

$$
x \geqq 0, \quad \lambda=\left(\lambda_{1}, \lambda_{2}\right) \in \stackrel{o}{S}_{2}
$$

(SD) Maximize $\left(u^{2}-v^{2}-2 \lambda_{1} u^{2}+\lambda_{2} u, v-u-2 \lambda_{1} u^{2}+\lambda_{2} u\right)$
subject to $2 \lambda_{1} u-\lambda_{2} \geqq 0$,

$$
v \geqq 0, \quad \lambda=\left(\lambda_{1}, \lambda_{2}\right) \in \stackrel{o}{S}_{2} .
$$

Now, we determine the set of all vector solutions of the vector matrix game $B_{i}(x, y), i=1,2$. Let

$$
B_{i}(x, y)=\left(\begin{array}{ccc}
0 & -x \nabla_{y} f_{i}(x, y)^{T} & -\nabla_{x} f_{i}(x, y) \\
-\nabla_{y} f_{i}(x, y) x^{T} & 0 & \nabla_{y} f_{i}(x, y) \\
\nabla_{x} f_{i}(x, y)^{T} & -\nabla_{y} f_{i}(x, y)^{T} & 0
\end{array}\right) .
$$

Then

$$
B_{1}(x, y)=\left(\begin{array}{ccc}
0 & 2 x y & -2 x \\
-2 x y & 0 & -2 y \\
2 x & 2 y & 0
\end{array}\right) \quad \text { and } \quad B_{2}(x, y)=\left(\begin{array}{ccc}
0 & -x & 1 \\
x & 0 & 1 \\
-1 & -1 & 0
\end{array}\right) .
$$

Let $(x, y) \in \mathbb{R}^{2}$ and $\left(x^{*}, y^{*}, z^{*}\right) \in S_{3}$ be a vector solution of the vector matrix game $B_{i}(x, y)$, $i=1,2$, if and only if there exist $\xi_{1}>0, \xi_{2}>0, \xi_{1}+\xi_{2}=1$ such that

$$
\left(\xi_{1}\left(\begin{array}{ccc}
0 & 2 x y & -2 x \\
-2 x y & 0 & -2 y \\
2 x & 2 y & 0
\end{array}\right)+\xi_{2}\left(\begin{array}{ccc}
0 & -x & 1 \\
x & 0 & 1 \\
-1 & -1 & 0
\end{array}\right)\right)\left(\begin{array}{l}
x^{*} \\
y^{* *} \\
z^{*}
\end{array}\right) \leqq\left(\begin{array}{l}
0 \\
0 \\
0
\end{array}\right) .
$$

$\Longleftrightarrow$ there exist $\xi_{1}>0, \xi_{2}>0, \xi_{1}+\xi_{2}=1$ such that

$$
\left(\begin{array}{c}
x\left(2 y \xi_{1}-\xi_{2}\right) y^{* *}-\left(2 x \xi_{1}-\xi_{2}\right) z^{*} \\
-x\left(2 y \xi_{1}-\xi_{2}\right) x^{* *}-\left(2 y \xi_{1}-\xi_{2}\right) z^{* *} \\
\left(2 x \xi_{1}-\xi_{2}\right) x^{*}+\left(2 y \xi_{1}-\xi_{2}\right) y^{*}
\end{array}\right) \leqq\left(\begin{array}{l}
0 \\
0 \\
0
\end{array}\right) .
$$

Thus, we determine the set of all the vector solutions of the vector matrix game $B_{i}(x, y)$, $i=1,2$.
(I) the case that $x>0$ :
(a) $2 x \xi_{1}-\xi_{2}>0,2 y \xi_{1}-\xi_{2}>0:\left(x^{*}, y^{*}, z^{*}\right)=(0,0,1)$.
(b) $2 x \xi_{1}-\xi_{2}>0,2 y \xi_{1}-\xi_{2}=0:\left(x^{*}, y^{*}, z^{*}\right):\{(0, \alpha, 1-\alpha) \mid 0 \leqq \alpha \leqq 1\}$.
(c) $2 x \xi_{1}-\xi_{2}>0,2 y \xi_{1}-\xi_{2}<0:\left(x^{* *}, y^{*}, z^{*}\right)=(0,1,0)$.
(d) $2 x \xi_{1}-\xi_{2}=0,2 y \xi_{1}-\xi_{2}>0:\left(x^{*}, y^{*}, z^{*}\right):\{(\alpha, 0,1-\alpha) \mid 0 \leqq \alpha \leqq 1\}$.
(e) $2 x \xi_{1}-\xi_{2}=0,2 y \xi_{1}-\xi_{2}=0$ : $\left(x^{*}, y^{*}, z^{*}\right):\left\{\left(x_{1}, x_{2}, x_{3}\right) \mid x_{1} \geqq 0, x_{2} \geqq 0, x_{3} \geqq 0, x_{1}+x_{2}+x_{3}=1\right\}$.
(f) $2 x \xi_{1}-\xi_{2}=0,2 y \xi_{1}-\xi_{2}<0:\left(x^{*}, y^{*}, z^{*}\right)=(0,1,0)$.
(g) $2 x \xi_{1}-\xi_{2}<0,2 y \xi_{1}-\xi_{2}>0:\left(x^{*}, y^{*}, z^{*}\right)=(1,0,0)$.
(h) $2 x \xi_{1}-\xi_{2}<0,2 y \xi_{1}-\xi_{2}=0:\left(x^{*}, y^{*}, z^{*}\right):\{(\alpha, 1-\alpha, 0) \mid 0 \leqq \alpha \leqq 1\}$.
(i) $2 x \xi_{1}-\xi_{2}<0,2 y \xi_{1}-\xi_{2}<0:\left(x^{*}, y^{*}, z^{*}\right)=(0,1,0)$.
(II) the case that $x=0$ :
(a) $2 y \xi_{1}-\xi_{2}>0:\left(x^{*}, y^{*}, z^{*}\right):\left\{(1-\alpha, \alpha, 0) \left\lvert\, \alpha \leqq \frac{\xi_{2}}{2 y \xi_{1}}\right., y>0, \xi_{1}>0, \xi_{2}>0, \xi_{1}+\xi_{2}=1\right\}$.
(b) $2 y \xi_{1}-\xi_{2}=0:\left(x^{*}, y^{*}, z^{*}\right):\{(\alpha, 1-\alpha, 0) \mid 0 \leqq \alpha \leqq 1\}$.
(c) $2 y \xi_{1}-\xi_{2}<0:\left(x^{*}, y^{*}, z^{*}\right):\{(\alpha, 1-\alpha, 0) \mid 0 \leqq \alpha \leqq 1\}$.
(III) the case that $x<0$ :
(a) $2 y \xi_{1}-\xi_{2}>0$ :

$$
\left(x^{*}, y^{* \prime}, z^{* \prime}\right):\left\{\left(\frac{2 y \xi_{1}-\xi_{2}}{2 y \xi_{1}-2 x \xi_{1}-2 x y \xi_{1}+x \xi_{2}},-\frac{2 x \xi_{1}-\xi_{2}}{2 y \xi_{1}-2 x \xi_{1}-2 x y \xi_{1}+x \xi_{2}},-\frac{2 x y \xi_{1}-x \xi_{2}}{2 y \xi_{1}-2 x \xi_{1}-2 x y \xi_{1}+x \xi_{2}}\right):\right.
$$

$$
\left.2 y \xi_{1}-2 x \xi_{1}-2 x y \xi_{1}+x \xi_{2}>0,2 y \xi_{1}-\xi_{2}>0,2 x \xi_{1}-\xi_{2}<0, \xi_{1}>0, \xi_{2}>0, \xi_{1}+\xi_{2}=1\right\}
$$

(b) $2 y \xi_{1}-\xi_{2}=0:\left(x^{*}, y^{*}, z^{*}\right):\{(\alpha, 1-\alpha, 0) \mid 0 \leqq \alpha \leqq 1\}$.
(c) $2 y \xi_{1}-\xi_{2}<0:\left(x^{*}, y^{*}, z^{*}\right)=(1,0,0)$.

Let $(x, y) \in \mathbb{R}^{2}$ and $S_{(x, y)}$ be the set of vector solutions of the vector matrix game $B_{i}(x, y)$, $i=1,2$. From (I), (II) and (III),

$$
\begin{aligned}
\bigcup_{(x, y) \in \mathbb{R}^{2}} S(x, y)= & \{(\alpha, 1-\alpha, 0) \mid 0 \leqq \alpha \leqq 1\} \cup\{(0, \alpha, 1-\alpha) \mid 0 \leqq \alpha \leqq 1\} \\
& \cup\{(\alpha, 0,1-\alpha) \mid 0 \leqq \alpha \leqq 1\} \\
& \cup\{(\alpha, \beta, \gamma) \mid \alpha \geqq 0, \beta \leqq 0, \gamma \leqq 0, \alpha+\beta+\gamma=1\} \\
& \cup\left\{\left(\frac{2 y \xi_{1}-\xi_{2}}{2 y \xi_{1}-2 x \xi_{1}-2 x y \xi_{1}+x \xi_{2}},-\frac{2 x \xi_{1}-\xi_{2}}{2 y \xi_{1}-2 x \xi_{1}-2 x y \xi_{1}+x \xi_{2}}\right.\right. \\
& \left.-\frac{2 x y \xi_{1}-x \xi_{2}}{2 y \xi_{1}-2 x \xi_{1}-2 x y \xi_{1}+x \xi_{2}}\right) \mid x<0,2 y \xi_{1}-2 x \xi_{1}-2 x y \xi_{1}+x \xi_{2}>0 \\
& \left.2 y \xi_{1}-\xi_{2}>0,2 x \xi_{1}-\xi_{2}<0, \xi_{1}>0, \xi_{2}>0, \xi_{1}+\xi_{2}=1\right\}
\end{aligned}
$$

Let $(\bar{x}, \bar{y}, \bar{\xi})$ be feasible for $(\mathrm{SP})$ and (SD) with $\bar{y} \nabla_{y}\left(\bar{\xi}^{T} f\right)(\bar{x}, \bar{y})=\bar{x} \nabla_{x}\left(\bar{\xi}^{T} f\right)(\bar{x}, \bar{y})=0$. We can easily check that

$$
\begin{aligned}
& \left\{(x, y, \xi) \mid(x, y, \xi) \text { is feasible for (SP) and (SD), } \bar{y} \nabla_{y}\left(\xi^{T} f\right)(x, y)=\bar{x} \nabla_{x}\left(\xi^{T} f\right)(x, y)=0\right\} \\
& \quad=\left\{\left.\left(\frac{\xi_{2}}{2 \xi_{1}}, \frac{\xi_{2}}{2 \xi_{1}}, \xi_{1}, \xi_{2}\right) \right\rvert\, \xi_{1}>0, \xi_{2}>0, \xi_{1}+\xi_{2}=1\right\}
\end{aligned}
$$

Thus,

$$
\begin{aligned}
& \left(\frac{\bar{x}}{1+\bar{x}+\bar{y}}, \frac{\bar{y}}{1+\bar{x}+\bar{y}}, \frac{1}{1+\bar{x}+\bar{y}}\right) \\
& \quad \in\left\{\left.\left(\frac{\xi_{2}}{2}, \frac{\xi_{2}}{2}, \xi_{1}\right) \right\rvert\, \xi_{1}>0, \xi_{2}>0, \xi_{1}+\xi_{2}=1\right\}
\end{aligned}
$$

$\subset S_{(\bar{x}, \bar{y})}$.

Therefore, Theorem 3.1 holds.
Let $(x, y) \in \mathbb{R}^{2}$ and $S_{(x, y)}$ be the set of vector solutions of the vector matrix game $B_{i}(x, y)$, $i=1,2$. Then

$$
\begin{aligned}
\bigcup_{(x, y) \in \mathbb{R}^{2}} S_{(x, y)}= & \{(\alpha, 1-\alpha, 0) \mid 0 \leqq \alpha \leqq 1\} \cup\{(0, \alpha, 1-\alpha) \mid 0 \leqq \alpha \leqq 1\} \\
& \cup\{(\alpha, 0,1-\alpha) \mid 0 \leqq \alpha \leqq 1\} \\
& \cup\{(\alpha, \beta, \gamma) \mid \alpha \leqq 0, \beta \leqq 0, \gamma \geqq 0, \alpha+\beta+\gamma=1\} \\
& \cup\left\{\left(\frac{2 y \xi_{1}-\xi_{2}}{2 y \xi_{1}-2 x \xi_{1}-2 x y \xi_{1}+x \xi_{2}},-\frac{2 x \xi_{1}-\xi_{2}}{2 y \xi_{1}-2 x \xi_{1}-2 x y \xi_{1}+x \xi_{2}},\right.\right.
\end{aligned}
$$

$$
\begin{aligned}
& \left.-\frac{2 x y \xi_{1}-x \xi_{2}}{2 y \xi_{1}-2 x \xi_{1}-2 x y \xi_{1}+x \xi_{2}}\right) \mid x<0,2 y \xi_{1}-2 x \xi_{1}-2 x y \xi_{1}+x \xi_{2}>0 \\
& \left.2 y \xi_{1}-\xi_{2}>0,2 x \xi_{1}-\xi_{2}<0, \xi_{1}>0, \xi_{2}>0, \xi_{1}+\xi_{2}=1\right\}
\end{aligned}
$$

So,

$$
\left\{\left.\left(\frac{x^{*}}{z^{\prime \prime}}, \frac{y^{*}}{z^{* \prime}}\right) \right\rvert\, z^{*}>0 \text { and }\left(x^{*}, y^{*}, z^{*}\right) \in S_{\left(\frac{x^{*}}{z^{*}}, \frac{y^{*}}{z^{*}}\right)}\right\}=\left\{\left.\left(\frac{\xi_{2}}{2 \xi_{1}}, \frac{\xi_{2}}{2 \xi_{1}}\right) \right\rvert\, \xi_{1}>0, \xi_{2}>0, \xi_{1}+\xi_{2}=1\right\} .
$$

Let $F$ be the set of all feasible solutions of (SP) and let $G$ be the set of all feasible solutions of (SD). Then we can check that $\left\{\left.\left(\frac{\xi_{2}}{2 \xi_{1}}, \frac{\xi_{2}}{2 \xi_{1}}, \xi_{1}, \xi_{2}\right) \right\rvert\, \xi_{1}>0, \xi_{2}>0, \xi_{1}+\xi_{2}=1\right\} \subset F \cap G$ and $\left(\frac{\xi_{2}}{2 \xi_{1}}\right) \nabla_{y}\left(\xi^{T} f\right)\left(\frac{\xi_{2}}{2 \xi_{1}}, \frac{\xi_{2}}{2 \xi_{1}}\right)=\left(\frac{\xi_{2}}{2 \xi_{1}}\right) \nabla_{x}\left(\xi^{T} f\right)\left(\frac{\xi_{2}}{2 \xi_{1}}, \frac{\xi_{2}}{2 \xi_{1}}\right)=0$. Therefore, Theorem 3.2 holds.

## Competing interests

The authors declare that they have no competing interests.

## Authors' contributions

The authors, together discussed and solved the problems in the manuscript. All authors read and approved the final manuscript.

## Author details

'Department of Applied Mathematics, Pukyong National University, Busan, 608-737, Korea. ${ }^{2}$ School of Free Major, Tongmyong University, Busan, 608-711, Korea

## Acknowledgements

The authors would like to thank the referees for giving valuable comments for the revision of the paper.

Received: 30 June 2012 Accepted: 26 November 2012 Published: 28 December 2012

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## doi:10.1186/1687-1812-2012-233

Cite this article as: Hong et al.: On vector matrix game and symmetric dual vector optimization problem. Fixed Point Theory and Applications 2012 2012:233.


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