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# Viscosity approximation methods for nonexpansive semigroups in CAT(0) spaces

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# Abstract

In this paper, we study the strong convergence of Moudafi's viscosity approximation methods for approximating a common fixed point of a one-parameter continuous semigroup of nonexpansive mappings in CAT(0) spaces. We prove that the proposed iterative scheme converges strongly to a common fixed point of a one-parameter continuous semigroup of nonexpansive mappings which is also a unique solution of the variational inequality. The results presented in this paper extend and enrich the existing literature.

**Keywords:** viscosity approximation method; nonexpansive semigroup; variational inequality; CAT(0) space; common fixed point

# **1** Introduction

Let (X, d) be a metric space. A *geodesic path* joining  $x \in X$  to  $y \in X$  (or, more briefly, a *geodesic* from x to y) is a map c from a closed interval  $[0, l] \subset \mathbb{R}$  to X such that c(0) = x, c(l) = y, and d(c(t), c(t')) = |t - t'| for all  $t, t' \in [0, l]$ . In particular, c is an isometry and d(x, y) = l. The image  $\alpha$  of c is called a *geodesic* (or metric) *segment* joining x and y. When it is unique, this geodesic segment is denoted by [x, y]. The space (X, d) is said to be a *geodesic space* if every two points of X are joined by a geodesic, and X is said to be uniquely geodesic if there is exactly one geodesic joining x and y for each  $x, y \in X$ . A subset  $Y \subseteq X$  is said to be convex if Y includes every geodesic segment joining any two of its points. A geodesic triangle  $\triangle(x_1, x_2, x_3)$  in a geodesic metric space (X, d) consists of three points  $x_1, x_2, x_3$ in X (the vertices of  $\triangle$ ) and a geodesic segment between each pair of vertices (the edges of  $\triangle$ ). A comparison triangle for the geodesic triangle  $\triangle(x_1, x_2, x_3)$  in (X, d) is a triangle  $\overline{\triangle}(x_1, x_2, x_3) := \triangle(\overline{x}_1, \overline{x}_2, \overline{x}_3)$  in the Euclidean plane  $\mathbb{E}^2$  such that  $d_{\mathbb{E}_2}(\overline{x}_i, \overline{x}_j) = d(x_i, x_j)$  for all  $i, j \in \{1, 2, 3\}$ .

A geodesic space is said to be a CAT(0) space if all geodesic triangles of appropriate size satisfy the following comparison axiom.

CAT(0): Let  $\triangle$  be a geodesic triangle in X and let  $\overline{\triangle}$  be a comparison triangle for  $\triangle$ . Then  $\triangle$  is said to satisfy the CAT(0) *inequality* if for all  $x, y \in \triangle$  and all comparison points  $\overline{x}, \overline{y} \in \overline{\triangle}$ ,

$$d(x,y) \le d_{\mathbb{E}^2}(\bar{x},\bar{y}).$$



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If *x*,  $y_1$ ,  $y_2$  are points in a CAT(0) space and if  $y_0$  is the midpoint of the segment  $[y_1, y_2]$ , then the CAT(0) inequality implies

$$d^{2}(x, y_{0}) \leq \frac{1}{2}d^{2}(x, y_{1}) + \frac{1}{2}d^{2}(x, y_{2}) - \frac{1}{4}d^{2}(y_{1}, y_{2}).$$

$$(1.1)$$

This is the (CN)-inequality of Bruhat and Tits [1]. In fact (*cf.* [2], p.163), a geodesic space is a CAT(0) space if and only if it satisfies the (CN)-inequality.

It is well known that any complete, simply connected Riemannian manifold having nonpositive sectional curvature is a CAT(0) space. Other examples include pre-Hilbert spaces,  $\mathbb{R}$ -trees (see [2]), Euclidean buildings (see [3]), the complex Hilbert ball with a hyperbolic metric (see [4]), and many others. Complete CAT(0) spaces are often called Hadamard spaces.

It is proved in [2] that a normed linear space satisfies the (CN)-inequality if and only if it satisfies the parallelogram identity, *i.e.*, is a pre-Hilbert space; hence it is not so unusual to have an inner product-like notion in Hadamard spaces. Berg and Nikolaev [5] introduced the concept of quasilinearization as follows.

Let us formally denote a pair  $(a, b) \in X \times X$  by  $\overline{ab}$  and call it a vector. Then *quasilinearization* is defined as a map  $\langle \cdot, \cdot \rangle : (X \times X) \times (X \times X) \to \mathbb{R}$  defined by

$$\langle \overrightarrow{ab}, \overrightarrow{cd} \rangle = \frac{1}{2} \left( d^2(a,d) + d^2(b,c) - d^2(a,c) - d^2(b,d) \right) \quad (a,b,c,d \in X).$$
(1.2)

It is easily seen that  $\langle \vec{ab}, \vec{cd} \rangle = \langle \vec{cd}, \vec{ab} \rangle$ ,  $\langle \vec{ab}, \vec{cd} \rangle = -\langle \vec{ba}, \vec{cd} \rangle$  and  $\langle \vec{ax}, \vec{cd} \rangle + \langle \vec{xb}, \vec{cd} \rangle = \langle \vec{ab}, \vec{cd} \rangle$ for all  $a, b, c, d, x \in X$ . We say that X satisfies the Cauchy-Schwarz inequality if

$$\langle \overrightarrow{ab}, \overrightarrow{cd} \rangle \le d(a, b)d(c, d)$$
 (1.3)

for all  $a, b, c, d \in X$ . It is known [5, Corollary 3] that a geodesically connected metric space is a CAT(0) space if and only if it satisfies the Cauchy-Schwarz inequality.

In 2010, Kakavandi and Amini [6] introduced the concept of a dual space for CAT(0) spaces as follows. Consider the map  $\Theta : \mathbb{R} \times X \times X \to C(X)$  defined by

$$\Theta(t,a,b)(x) = t \langle \overrightarrow{ab}, \overrightarrow{ax} \rangle, \tag{1.4}$$

where C(X) is the space of all continuous real-valued functions on X. Then the Cauchy-Schwarz inequality implies that  $\Theta(t, a, b)$  is a Lipschitz function with a Lipschitz seminorm  $L(\Theta(t, a, b)) = |t|d(a, b)$  for all  $t \in \mathbb{R}$  and  $a, b \in X$ , where

$$L(f) = \sup\left\{\frac{f(x) - f(y)}{d(x, y)} : x, y \in X, x \neq y\right\}$$

\_ \_ \_

is the Lipschitz semi-norm of the function  $f : X \to \mathbb{R}$ . Now, define the pseudometric D on  $\mathbb{R} \times X \times X$  by

$$D((t,a,b),(s,c,d)) = L(\Theta(t,a,b) - \Theta(s,c,d)).$$

**Lemma 1.1** [6, Lemma 2.1] D((t, a, b), (s, c, d)) = 0 if and only if  $t\langle \vec{ab}, \vec{xy} \rangle = s \langle \vec{cd}, \vec{xy} \rangle$  for all  $x, y \in X$ .

For a complete CAT(0) space (X, d), the pseudometric space  $(\mathbb{R} \times X \times X, D)$  can be considered as a subspace of the pseudometric space (Lip(X, R), L) of all real-valued Lipschitz functions. Also, D defines an equivalence relation on  $\mathbb{R} \times X \times X$ , where the equivalence class of tab := (t, a, b) is

$$[t\overrightarrow{ab}] = \{ \overrightarrow{scd} : t\langle \overrightarrow{ab}, \overrightarrow{xy} \rangle = s\langle \overrightarrow{cd}, \overrightarrow{xy} \rangle \ \forall x, y \in X \}.$$

The set  $X^* := \{[tab] : (t, a, b) \in \mathbb{R} \times X \times X\}$  is a metric space with metric *D*, which is called the dual metric space of (X, d).

Recently, Dehghan and Rooin [7] introduced the duality mapping in CAT(0) spaces and studied its relation with subdifferential, by using the concept of quasilinearization. Then they presented a characterization of metric projection in CAT(0) spaces as follows.

**Theorem 1.2** [7, Theorem 2.4] *Let C be a nonempty convex subset of a complete* CAT(0) *space*  $X, x \in X$  *and*  $u \in C$ . *Then* 

$$u = P_C x$$
 if and only if  $\langle \overline{yu}, \overline{ux} \rangle \ge 0$  for all  $y \in C$ .

From now on, let  $\mathbb{N}$  be the set of positive integers, let  $\mathbb{R}$  be the set of real numbers, and let  $\mathbb{R}^+$  be the set of nonnegative real numbers. Let *C* be a nonempty, closed and convex subset of a complete CAT(0) space *X*. A family  $S := \{T(t) : t \in \mathbb{R}^+\}$  of self-mappings of *C* is called a one-parameter continuous semigroup of nonexpansive mappings if the following conditions hold:

(i) for each  $t \in \mathbb{R}^+$ , T(t) is a nonexpansive mapping on *C*, *i.e.*,

$$d(T(t)x, T(t)y) \leq d(x, y), \quad \forall x, y \in C;$$

(ii)  $T(s + t) = T(t) \circ T(s)$  for all  $t, s \in \mathbb{R}^+$ ;

(iii) for each  $x \in X$ , the mapping  $T(\cdot)x$  from  $\mathbb{R}^+$  into *C* is continuous.

A family  $S := \{T(t) : t \in \mathbb{R}^+\}$  of mappings is called a one-parameter strongly continuous semigroup of nonexpansive mappings if conditions (i), (ii) and (iii) and the following condition are satisfied:

(iv) T(0)x = x for all  $x \in C$ .

We shall denote by  $\mathcal{F}$  the common fixed point set of  $\mathcal{S}$ , that is,

$$\mathcal{F} := F(\mathcal{S}) = \left\{ x \in C : T(t)x = x, t \in \mathbb{R}^+ \right\} = \bigcap_{t \in \mathbb{R}^+} F(T(t)).$$

One classical way to study nonexpansive mappings is to use contractions to approximate nonexpansive mappings. More precisely, take  $t \in (0, 1)$  and define a contraction  $T_t : C \to C$  by

$$T_t = tu + (1-t)Tx$$
,  $\forall x \in C$ ,

where  $u \in C$  is an arbitrary fixed element. Banach's contraction mapping principle guarantees that  $T_t$  has a unique fixed point  $x_t$  in C. It is unclear, in general, what the behavior of  $x_t$  is as  $t \to 0$ , even if T has a fixed point. However, in the case of T having a fixed point,

Browder [8] proved that  $x_t$  converges strongly to a fixed point of T that is nearest to u in the framework of Hilbert spaces. Reich [9] extended Browder's result to the setting of Banach spaces and proved, in a uniformly smooth Banach space, that  $x_t$  converges strongly to a fixed point of T and the limit defines the (unique) sunny nonexpansive retraction from C onto F(T).

Halpern [10] introduced the following explicit iterative scheme (1.5) for a nonexpansive mapping *T* on a subset *C* of a Hilbert space by taking any points  $u, x_1 \in C$  and defined the iterative sequence  $\{x_n\}$  by

$$x_{n+1} = \alpha_n u + (1 - \alpha_n) T x_n.$$
(1.5)

He proved that the sequence  $\{x_n\}$  generated by (1.5) converges to a fixed point of *T*.

It is an interesting problem to extend the above (Browder's [8] and Halpern's [10]) results to the nonexpansive semigroup case. In [11], Shioji and Takahashi introduced the following implicit iteration in a Hilbert space:

$$x_n = \alpha_n u + (1 - \alpha_n) \frac{1}{t_n} \int_0^{t_n} T(s) x_n \, ds,$$
(1.6)

where *C* is a nonempty closed convex subset of a real Hilbert space *H*,  $u \in C$ ,  $\{\alpha_n\}$  is a sequence in (0,1),  $\{t_n\}$  is a sequence of positive real numbers divergent to  $\infty$ . Under suitable conditions, they proved strong convergence of  $\{x_n\}$  to a member of  $\mathcal{F}$ .

Later, Suzuki [12] was the first to introduce in a Hilbert space the following iteration process:

$$x_n = \alpha_n u + (1 - \alpha_n) T(t_n) x_n, \quad \forall n \ge 1,$$
(1.7)

where  $\{T(t) : t \ge 0\}$  is a strongly continuous semigroup of nonexpansive mappings on *C* such that  $\mathcal{F} \neq \emptyset$  and  $\{\alpha_n\}$  and  $\{t_n\}$  are appropriate sequences of real numbers. He proved that  $\{x_n\}$  generated by (1.7) converges strongly to the element of  $\mathcal{F}$  nearest to *u*. Using Moudafi's viscosity approximation methods, Song and Xu [13] introduced the following iteration process:

$$x_n = \alpha_n f(x_n) + (1 - \alpha_n) T(t_n) x_n, \quad \forall n \ge 1,$$
(1.8)

and

$$x_{n+1} = \alpha_n f(x_n) + (1 - \alpha_n) T(t_n) x_n, \quad \forall n \ge 1.$$
(1.9)

They proved that  $\{x_n\}$  converges to the same point of  $\mathcal{F}$  in a reflexive strictly Banach space with a uniformly Gâteaux differentiable norm.

In the similar way, Dhompongsa *et al.* [14] extended Browder's iteration to a strongly continuous semigroup of nonexpansive mappings  $\{T(t) : t \ge 0\}$  in a complete CAT(0) space *X* as follows:

$$x_n = \alpha_n x_0 \oplus T(t_n) x_n, \quad \forall n \ge 1,$$

where *C* is a nonempty closed convex subset of a complete CAT(0) space *X*,  $x_0 \in C$ ,  $\{\alpha_n\}$  and  $\{t_n\}$  are sequences of real numbers satisfying  $0 < \alpha_n < 1$ ,  $t_n > 0$ , and  $\lim_{n\to\infty} t_n = \lim_{n\to\infty} \alpha_n/t_n = 0$ . The proved that  $\mathcal{F} \neq \emptyset$  and  $\{x_n\}$  converges to the element of  $\mathcal{F}$  nearest to *u*. For other related results, see [15, 16].

In 2012, Shi and Chen [17], studied the convergence theorems of the following Moudafi's viscosity iterations for a nonexpansive mapping *T*: for a contraction *f* on *C* and  $t \in (0, 1)$ , let  $x_t \in C$  be a unique fixed point of the contraction  $x \mapsto tf(x) \oplus (1 - t)Tx$ ; *i.e.*,

$$x_t = tf(x_t) \oplus (1-t)Tx_t, \tag{1.10}$$

and  $x_0 \in C$  is arbitrarily chosen and

$$x_{n+1} = \alpha_n f(x_n) \oplus (1 - \alpha_n) T x_n, \quad \forall n \ge 0,$$
(1.11)

where  $\{\alpha_n\} \subset (0,1)$ . They proved  $\{x_t\}$  defined by (1.10) converges strongly as  $t \to 0$  to  $\tilde{x} \in F(T)$  such that  $\tilde{x} = P_{F(T)}f(\tilde{x})$  in the framework of CAT(0) space satisfying property  $\mathcal{P}$ , *i.e.*, if for  $x, u, y_1, y_2 \in X$ ,

$$d(x, P_{[x,y_1]}u)d(x,y_1) \le d(x, P_{[x,y_2]}u)d(x,y_2) + d(x,u)d(y_1,y_2).$$

Furthermore, they also obtained that  $\{x_n\}$  defined by (1.11) converges strongly as  $n \to \infty$  to  $\tilde{x} \in F(T)$  under certain appropriate conditions imposed on  $\{\alpha_n\}$ .

By using the concept of quasilinearization, Wangkeeree and Preechasilp [18] improved Shi and Chen's results. In fact, they proved the strong convergence theorems for two given iterative schemes (1.10) and (1.11) in a complete CAT(0) space without the property  $\mathcal{P}$ .

Motivated and inspired by Song and Xu [13], Dhompongsa *et al.* [14], and Wangkeeree and Preechasilp [18], in this paper we aim to study the strong convergence theorems of Moudafi's viscosity approximation methods for a one-parameter continuous semigroup of nonexpansive mappings  $S := \{T(t) : t \in \mathbb{R}^+\}$  in CAT(0) spaces. Let *C* be a nonempty, closed and convex subset of a CAT(0) space *X*. For a given contraction *f* on *C* and  $\alpha_n \in (0, 1)$ , let  $x_n \in C$  be a unique fixed point of the contraction  $x \mapsto \alpha_n f(x) \oplus (1 - \alpha_n) T(t_n) x$ ; *i.e.*,

$$x_n = \alpha_n f(x_n) \oplus (1 - \alpha_n) T(t_n) x_n, \quad n \ge 0,$$
(1.12)

and

$$x_{n+1} = \alpha_n f(x_n) \oplus (1 - \alpha_n) T(t_n) x_n, \quad n \ge 0.$$
(1.13)

We prove that the iterative schemes  $\{x_n\}$  defined by (1.12) and  $\{x_n\}$  defined by (1.13) converge strongly to the same point  $\tilde{x}$  such that  $\tilde{x} = P_{\mathcal{F}}f(\tilde{x})$ , which is the unique solution of the variational inequality

$$\langle \widetilde{\tilde{x}f}\widetilde{\tilde{x}}, \widetilde{x}\widetilde{\tilde{x}} \rangle \geq 0, \quad x \in \mathcal{F},$$

where  $\mathcal{F}$  is the common fixed point set of  $\mathcal{S}$ , that is,

$$\mathcal{F} := F(\mathcal{S}) = \left\{ x \in C : T(t)x = x, t \in \mathbb{R}^+ \right\} = \bigcap_{t \in \mathbb{R}^+} F(T(t)).$$

## 2 Preliminaries

In this paper, we write  $(1 - t)x \oplus ty$  for the unique point *z* in the geodesic segment joining from *x* to *y* such that

d(z, x) = td(x, y) and d(z, y) = (1 - t)d(x, y).

We also denote by [x, y] the geodesic segment joining from x to y, that is,  $[x, y] = \{(1-t)x \oplus ty : t \in [0,1]\}$ . A subset C of a CAT(0) space is convex if  $[x, y] \subseteq C$  for all  $x, y \in C$ .

The following lemmas play an important role in our paper.

**Lemma 2.1** [2, Proposition 2.2] Let X be a CAT(0) space,  $p, q, r, s \in X$  and  $\lambda \in [0, 1]$ . Then

 $d(\lambda p \oplus (1-\lambda)q, \lambda r \oplus (1-\lambda)s) \leq \lambda d(p,r) + (1-\lambda)d(q,s).$ 

**Lemma 2.2** [19, Lemma 2.4] Let X be a CAT(0) space,  $x, y, z \in X$  and  $\lambda \in [0, 1]$ . Then

 $d(\lambda x \oplus (1-\lambda)y, z) \leq \lambda d(x, z) + (1-\lambda)d(y, z).$ 

**Lemma 2.3** [19, Lemma 2.5] Let X be a CAT(0) space,  $x, y, z \in X$  and  $\lambda \in [0, 1]$ . Then

$$d^2(\lambda x \oplus (1-\lambda)y, z) \leq \lambda d^2(x, z) + (1-\lambda)d^2(y, z) - \lambda(1-\lambda)d^2(x, y).$$

The concept of  $\Delta$ -convergence introduced by Lim [20] in 1976 was shown by Kirk and Panyanak [21] in CAT(0) spaces to be very similar to the weak convergence in Banach space setting. Next, we give the concept of  $\Delta$ -convergence and collect some basic properties.

Let  $\{x_n\}$  be a bounded sequence in a CAT(0) space *X*. For  $x \in X$ , we set

$$r(x, \{x_n\}) = \limsup_{n \to \infty} d(x, x_n).$$

The asymptotic radius  $r({x_n})$  of  ${x_n}$  is given by

$$r(\lbrace x_n\rbrace) = \inf\{r(x, \lbrace x_n\rbrace) : x \in X\},\$$

and the asymptotic center  $A(\{x_n\})$  of  $\{x_n\}$  is the set

$$A(\{x_n\}) = \{x \in X : r(x, \{x_n\}) = r(\{x_n\})\}.$$

It is known from Proposition 7 of [22] that in a complete CAT(0) space,  $A(\{x_n\})$  consists of exactly one point. A sequence  $\{x_n\} \subset X$  is said to  $\Delta$ -converge to  $x \in X$  if  $A(\{x_{n_k}\}) =$  $\{x\}$  for every subsequence  $\{x_{n_k}\}$  of  $\{x_n\}$ . The uniqueness of an asymptotic center implies that a CAT(0) space X satisfies Opial's property, *i.e.*, for given  $\{x_n\} \subset X$  such that  $\{x_n\}\Delta$ converges to x and given  $y \in X$  with  $y \neq x$ ,

$$\limsup_{n\to\infty} d(x_n,x) < \limsup_{n\to\infty} d(x_n,y).$$

Since it is not possible to formulate the concept of demiclosedness in a CAT(0) setting, as stated in linear spaces, let us formally say that  ${}^{\prime}I - T$  is demiclosed at zero' if the conditions  $\{x_n\} \subseteq C \Delta$ -converges to x and  $d(x_n, Tx_n) \rightarrow 0$  imply  $x \in F(T)$ .

**Lemma 2.4** [21] *Every bounded sequence in a complete* CAT(0) *space always has a*  $\Delta$ *-convergent subsequence.* 

**Lemma 2.5** [23] If C is a closed convex subset of a complete CAT(0) space and if  $\{x_n\}$  is a bounded sequence in C, then the asymptotic center of  $\{x_n\}$  is in C.

**Lemma 2.6** [23] If C is a closed convex subset of X and  $T : C \to X$  is a nonexpansive mapping, then the conditions  $\{x_n\}$   $\Delta$ -converges to x and  $d(x_n, Tx_n) \to 0$  imply  $x \in C$  and Tx = x.

Having the notion of quasilinearization, Kakavandi and Amini [6] introduced the following notion of convergence.

A sequence  $\{x_n\}$  in the complete CAT(0) space (X, d) *w*-converges to  $x \in X$  if

$$\lim_{n\to\infty}\langle \overrightarrow{xx_n}, \overrightarrow{xy}\rangle = 0,$$

*i.e.*,  $\lim_{n\to\infty} (d^2(x_n, x) - d^2(x_n, y) + d^2(x, y)) = 0$  for all  $y \in X$ .

It is obvious that convergence in the metric implies *w*-convergence, and it is easy to check that *w*-convergence implies  $\Delta$ -convergence [6, Proposition 2.5], but it is showed in [24, Example 4.7] that the converse is not valid. However, the following lemma shows another characterization of  $\Delta$ -convergence as well as, more explicitly, a relation between *w*-convergence and  $\Delta$ -convergence.

**Lemma 2.7** [24, Theorem 2.6] Let X be a complete CAT(0) space,  $\{x_n\}$  be a sequence in X and  $x \in X$ . Then  $\{x_n\}\Delta$ -converges to x if and only if  $\limsup_{n\to\infty} \langle \overrightarrow{xx_n}, \overrightarrow{xy} \rangle \leq 0$  for all  $y \in X$ .

**Lemma 2.8** [25, Lemma 2.1] Let  $\{a_n\}$  be a sequence of non-negative real numbers satisfying the property

 $a_{n+1} \leq (1-\alpha_n)a_n + \alpha_n\beta_n, \quad n \geq 0,$ 

where  $\{\alpha_n\} \subseteq (0,1)$  and  $\{\beta_n\} \subseteq \mathbb{R}$  such that

(i)  $\sum_{n=0}^{\infty} \alpha_n = \infty$ ;

(ii)  $\limsup_{n\to\infty} \beta_n \le 0 \text{ or } \sum_{n=0}^{\infty} |\alpha_n \beta_n| < \infty$ . Then  $\{a_n\}$  converges to zero as  $n \to \infty$ .

# 3 Viscosity approximation methods

In this section, we present the strong convergence theorems of Moudafi's viscosity approximation methods for a one-parameter continuous semigroup of nonexpansive mappings  $S := \{T(t) : t \in \mathbb{R}^+\}$  in CAT(0) spaces. Before proving main results, we need the following two vital lemmas.

**Lemma 3.1** Let X be a complete CAT(0) space. Then, for all  $u, x, y \in X$ , the following inequality holds:

$$d^2(x,u) \le d^2(y,u) + 2\langle \overrightarrow{xy}, \overrightarrow{xu} \rangle.$$

$$\begin{aligned} d^2(y,u) - d^2(x,u) - 2\langle \overrightarrow{yx}, \overrightarrow{xu} \rangle &= d^2(y,u) - d^2(x,u) - 2\langle \overrightarrow{yu}, \overrightarrow{xu} \rangle - 2\langle \overrightarrow{ux}, \overrightarrow{xu} \rangle \\ &= d^2(y,u) - d^2(x,u) - 2\langle \overrightarrow{yu}, \overrightarrow{xu} \rangle + 2d^2(x,u) \\ &= d^2(y,u) + d^2(x,u) - 2\langle \overrightarrow{yu}, \overrightarrow{xu} \rangle \\ &\geq d^2(y,u) + d^2(x,u) - 2d(y,u)d(x,u) \\ &= \left(d^2(y,u) - d^2(x,u)\right)^2 \ge 0. \end{aligned}$$

Therefore we obtain that

$$d^2(x,u) \le d^2(y,u) + 2\langle \overrightarrow{xy}, \overrightarrow{xu} \rangle,$$

which is the desired result.

**Lemma 3.2** Let X be a CAT(0) space. For any  $t \in [0,1]$  and  $u, v \in X$ , let  $u_t = tu \oplus (1-t)v$ . Then, for all  $x, y \in X$ ,

- (i)  $\langle \overrightarrow{u_t x}, \overrightarrow{u_t y} \rangle \leq t \langle \overrightarrow{u x}, \overrightarrow{u_t y} \rangle + (1-t) \langle \overrightarrow{v x}, \overrightarrow{u_t y} \rangle;$
- (ii)  $\langle \overrightarrow{u_t x}, \overrightarrow{uy} \rangle \leq t \langle \overrightarrow{ux}, \overrightarrow{uy} \rangle + (1-t) \langle \overrightarrow{vx}, \overrightarrow{uy} \rangle$  and  $\langle \overrightarrow{u_t x}, \overrightarrow{vy} \rangle \leq t \langle \overrightarrow{ux}, \overrightarrow{vy} \rangle + (1-t) \langle \overrightarrow{vx}, \overrightarrow{vy} \rangle$ .

*Proof* (i) It follows from (CN)-inequality (1.1) that

$$\begin{aligned} 2\langle \overrightarrow{u_t} \overrightarrow{x}, \overrightarrow{u_t} \overrightarrow{y} \rangle &= d^2(u_t, y) + d^2(x, u_t) - d^2(x, y) \\ &\leq td^2(u, y) + (1 - t)d^2(v, y) - t(1 - t)d^2(u, v) + d^2(x, u_t) - d^2(x, y) \\ &= td^2(u, y) + td^2(x, u_t) - td^2(u, u_t) - td^2(x, y) \\ &+ (1 - t)d^2(v, y) + (1 - t)d^2(x, u_t) - (1 - t)d^2(v, u_t) - (1 - t)d^2(x, y) \\ &+ td^2(u, u_t) + (1 - t)d^2(v, u_t) - t(1 - t)d^2(u, v) \\ &= t\left[d^2(u, y) + d^2(x, u_t) - d^2(u, u_t) - d^2(x, y)\right] \\ &+ (1 - t)\left[d^2(v, y) + d^2(x, u_t) - d^2(v, u_t) - d^2(x, y)\right] \\ &+ t(1 - t)^2d^2(u, v) + (1 - t)t^2d^2(u, v) - t(1 - t)d^2(u, v) \\ &= t\langle \overrightarrow{ux}, \overrightarrow{u_ty} \rangle + (1 - t)\langle \overrightarrow{vx}, \overrightarrow{u_ty} \rangle. \end{aligned}$$

(ii) The proof is similar to (i).

For any  $\alpha_n \in (0,1)$ ,  $t_n \in [0,\infty)$  and a contraction f with coefficient  $\alpha \in (0,1)$ , define the mapping  $G_n : C \to C$  by

$$G_n(x) = \alpha_n f(x) \oplus (1 - \alpha_n) T(t_n) x, \quad \forall x \in C.$$
(3.1)

It is not hard to see that  $G_n$  is a contraction on *C*. Indeed, for  $x, y \in C$ , we have

$$d(G_n(x), G_n(y)) = d(\alpha_n f(x) \oplus (1 - \alpha_n) T(t_n) x, \alpha_n f(y) \oplus (1 - \alpha_n) T(t_n) y)$$
  
$$\leq d(\alpha_n f(x) \oplus (1 - \alpha_n) T(t_n) x, \alpha_n f(y) \oplus (1 - \alpha_n) T(t_n) x)$$

$$+ d(\alpha_n f(y) \oplus (1 - \alpha_n) T(t_n) x, \alpha_n f(y) \oplus (1 - \alpha_n) T(t_n) y)$$
  

$$\leq \alpha_n d(f(x), f(y)) + (1 - \alpha_n) d(T(t_n) x, T(t_n) y)$$
  

$$\leq \alpha_n \alpha d(x, y) + (1 - \alpha_n) d(x, y)$$
  

$$= (1 - \alpha_n (1 - \alpha)) d(x, y).$$

Therefore we have that  $G_n$  is a contraction mapping. Let  $x_n \in C$  be the unique fixed point of  $G_n$ ; that is,

$$x_n = \alpha_n f(x_n) \oplus (1 - \alpha_n) T(t_n) x_n \quad \text{for all } n \ge 0.$$
(3.2)

Now we are in a position to state and prove our main results.

**Theorem 3.3** Let C be a closed convex subset of a complete CAT(0) space X, and let  $\{T(t)\}$  be a one-parameter continuous semigroup of nonexpansive mappings on C satisfying  $\mathcal{F} \neq \emptyset$  and uniformly asymptotically regular (in short, u.a.r.) on C, that is, for all  $h \ge 0$  and any bounded subset B of C,

 $\lim_{t\to\infty}\sup_{x\in B}d\big(T(h)\big(T(t)x\big),T(t)x\big)=0.$ 

Let f be a contraction on C with coefficient  $0 < \alpha < 1$ . Suppose that  $t_n \in [0, \infty)$ ,  $\alpha_n \in (0, 1)$  such that  $\lim_{n\to\infty} t_n = \infty$ ,  $\lim_{n\to\infty} \alpha_n = 0$  and let  $\{x_n\}$  be given by (3.2). Then  $\{x_n\}$  converges strongly as  $n \to \infty$  to  $\tilde{x}$  such that  $\tilde{x} = P_{\mathcal{F}}f(\tilde{x})$ , which is equivalent to the following variational inequality:

$$\langle \vec{x} \vec{f} \cdot \vec{x}, \vec{x} \vec{x} \rangle \ge 0, \quad \forall x \in \mathcal{F}.$$
 (3.3)

*Proof* We first show that  $\{x_n\}$  is bounded. For any  $p \in \mathcal{F}$ , we have that

$$d(x_n,p) = d(\alpha_n f(x_n) \oplus (1-\alpha_n)T(t_n)x_n,p) \le \alpha_n d(f(x_n),p) + (1-\alpha_n)d(T(t_n)x_n,p)$$
  
$$\le \alpha_n d(f(x_n),p) + (1-\alpha_n)d(x_n,p).$$

Then

$$d(x_n,p) \leq d(f(x_n),p) \leq d(f(x_n),f(p)) + d(f(p),p) \leq \alpha d(x_n,p) + d(f(p),p).$$

This implies that

$$d(x_n,p) \leq \frac{1}{1-\alpha} d(f(p),p).$$

Hence  $\{x_n\}$  is bounded, so are  $\{T(t_n)x_n\}$  and  $\{f(x_n)\}$ . We get that

$$d(x_n, T(t_n)x_n) = d(\alpha_n f(x_n) \oplus (1 - \alpha_n) T(t_n)x_n, T(t_n)x_n)$$
  
$$\leq \alpha_n d(f(x_n), T(t_n)x_n) + (1 - \alpha_n) d(T(t_n)x_n, T(t_n)x_n)$$
  
$$\leq \alpha_n d(f(x_n), T(t_n)x_n) \to 0 \quad \text{as } n \to \infty.$$

Since  $\{T(t)\}$  is u.a.r. and  $\lim_{n\to\infty} t_n = \infty$ , then for all h > 0,

$$\lim_{n\to\infty}d\big(T(h)\big(T(t_n)x_n\big),T(t_n)x_n\big)\leq \lim_{n\to\infty}\sup_{x\in B}d\big(T(h)\big(T(t_n)x\big),T(t_n)x\big)=0,$$

where *B* is any bounded subset of *C* containing  $\{x_n\}$ . Hence

$$d(x_n, T(h)x_n) \leq d(x_n, T(t_n)x_n) + d(T(t_n)x_n, T(h)(T(t_n)x_n))$$
  
+  $d(T(h)(T(t_n)x_n), T(h)x_n)$   
$$\leq 2d(x_n, T(t_n)x_n) + d(T(t_n)x_n, T(h)(T(t_n)x_n)) \to 0 \quad \text{as } n \to \infty.$$
(3.4)

We will show that  $\{x_n\}$  contains a subsequence converging strongly to  $\tilde{x}$  such that  $\tilde{x} = P_{F(T)}f(\tilde{x})$ , which is equivalent to the following variational inequality:

$$\langle \vec{x} \vec{f} \cdot \vec{x}, \vec{x} \vec{x} \rangle \ge 0, \quad x \in \mathcal{F}.$$
 (3.5)

Since  $\{x_n\}$  is bounded, by Lemma 2.4, there exists a subsequence  $\{x_{n_j}\}$  of  $\{x_n\}$  which  $\Delta$ -converges to a point  $\tilde{x}$ , denoted by  $\{x_j\}$ . We claim that  $\tilde{x} \in \mathcal{F}$ . Since every CAT(0) space has Opial's property, for any  $h \ge 0$ , if  $T(h)\tilde{x} \neq \tilde{x}$ , we have

$$\begin{split} \limsup_{j \to \infty} d\big(x_j, T(h)\tilde{x}\big) &\leq \limsup_{j \to \infty} \big\{ d\big(x_j, T(h)x_j\big) + d\big(T(h)x_j, T(h)\tilde{x}\big) \big\} \\ &\leq \limsup_{j \to \infty} \big\{ d\big(x_j, T(h)x_j\big) + d(x_j, \tilde{x}) \big\} \\ &= \limsup_{j \to \infty} d\big(x_j, \tilde{x}\big) \\ &< \limsup_{j \to \infty} d\big(x_j, T(h)\tilde{x}\big). \end{split}$$

This is a contradiction, and hence  $\tilde{x} \in \mathcal{F}$ . So we have the claim. It follows from Lemma 3.2(i) that

$$\begin{split} d^2(x_j, \tilde{x}) &= \langle \overrightarrow{x_j} \widetilde{\hat{x}}, \overrightarrow{x_j} \widetilde{\hat{x}} \rangle \\ &\leq \alpha_j \langle \overrightarrow{f(x_j)} \widetilde{\hat{x}}, \overrightarrow{x_j} \widetilde{\hat{x}} \rangle + (1 - \alpha_j) \langle \overrightarrow{T(t_j)} x_j \widetilde{\hat{x}}, \overrightarrow{x_j} \widetilde{\hat{x}} \rangle \\ &\leq \alpha_j \langle \overrightarrow{f(x_j)} \widetilde{\hat{x}}, \overrightarrow{x_j} \widetilde{\hat{x}} \rangle + (1 - \alpha_j) d \big( T(t_j) x_j, \widetilde{x} \big) d(x_j, \widetilde{x}) \\ &\leq \alpha_j \langle \overrightarrow{f(x_j)} \widetilde{\hat{x}}, \overrightarrow{x_j} \widetilde{\hat{x}} \rangle + (1 - \alpha_j) d^2(x_j, \widetilde{x}). \end{split}$$

It follows that

$$\begin{split} d^2(x_j, \tilde{x}) &\leq \langle \overline{f(x_j)} \dot{\tilde{x}}, \overline{x_j} \dot{\tilde{x}} \rangle \\ &= \langle \overline{f(x_j)} f(\vec{\tilde{x}}), \overline{x_j} \dot{\tilde{x}} \rangle + \langle \overline{f(\tilde{x})} \dot{\tilde{x}}, \overline{x_j} \dot{\tilde{x}} \rangle \\ &\leq d (f(x_j), f(\tilde{x})) d(x_j, \tilde{x}) + \langle \overline{f(\tilde{x})} \dot{\tilde{x}}, \overline{x_j} \dot{\tilde{x}} \rangle \\ &\leq \alpha d^2(x_j, \tilde{x}) + \langle \overline{f(\tilde{x})} \dot{\tilde{x}}, \overline{x_j} \dot{\tilde{x}} \rangle, \end{split}$$

and thus

$$d^{2}(x_{j},\tilde{x}) \leq \frac{1}{1-\alpha} \langle \overline{f(\tilde{x})} \overset{\rightarrow}{\tilde{x}}, \overline{x_{j}} \overset{\rightarrow}{\tilde{x}} \rangle.$$
(3.6)

Since  $\{x_i\}$   $\Delta$ -converges to  $\tilde{x}$ , by Lemma 2.7, we have

$$\limsup_{n\to\infty}\langle \overline{f(\tilde{x})}\overline{\tilde{x}},\overline{x_j}\overline{\tilde{x}}\rangle \leq 0.$$

It follows from (3.6) that  $\{x_j\}$  converges strongly to  $\tilde{x}$ . Next, we show that  $\tilde{x}$  solves the variational inequality (3.3). Applying Lemma 2.3, for any  $q \in \mathcal{F}$ ,

$$\begin{aligned} d^{2}(x_{j},q) &= d^{2} \left( \alpha_{j} f(x_{j}) \oplus (1-\alpha_{j}) T(t_{j}) x_{j}, q \right) \\ &\leq \alpha_{j} d^{2} \left( f(x_{j}), q \right) + (1-\alpha_{j}) d^{2} \left( T(t_{j}) x_{j}, q \right) - \alpha_{j} (1-\alpha_{j}) d^{2} \left( f(x_{j}), T(t_{j}) x_{j} \right) \\ &\leq \alpha_{j} d^{2} \left( f(x_{j}), q \right) + (1-\alpha_{j}) d^{2} (x_{j},q) - \alpha_{j} (1-\alpha_{j}) d^{2} \left( f(x_{j}), T(t_{j}) x_{j} \right). \end{aligned}$$

It implies that

$$d^{2}(x_{j},q) \leq d^{2}(f(x_{j}),q) - (1-\alpha_{j})d^{2}(f(x_{j}),T(t_{j})x_{j}).$$

Taking the limit through  $j \rightarrow \infty$ , we can get that

$$d^{2}(\tilde{x},q) \leq d^{2}(f(\tilde{x}),q) - d^{2}(f(\tilde{x}),\tilde{x}).$$

Hence

$$0 \leq \frac{1}{2} \Big[ d^2(\tilde{x}, \tilde{x}) + d^2(f(\tilde{x}), q) - d^2(\tilde{x}, q) - d^2(f(\tilde{x}), \tilde{x}) \Big] = \langle \overrightarrow{\tilde{x}f(\tilde{x})}, \overrightarrow{q\tilde{x}} \rangle, \quad \forall q \in \mathcal{F}.$$

That is,  $\tilde{x}$  solves the inequality (3.3). Finally, we show that the sequence  $\{x_n\}$  converges to  $\tilde{x}$ . Assume that  $x_{n_i} \to \hat{x}$ , where  $i \to \infty$ . By the same argument, we get that  $\hat{x} \in \mathcal{F}$  and solves the variational inequality (3.3), *i.e.*,

$$\langle \vec{x} \vec{f} \cdot \vec{x}, \vec{x} \cdot \vec{x} \rangle \le 0,$$
 (3.7)

and

$$\langle \hat{\hat{x}} f \hat{\hat{x}}, \hat{\hat{x}} \hat{\hat{x}} \rangle \le 0.$$
(3.8)

Adding up (3.7) and (3.8), we get that

$$\begin{split} 0 &\geq \langle \widetilde{x}f(\widetilde{x}), \widetilde{x}\widehat{\hat{x}} \rangle - \langle \widetilde{x}f(\widetilde{x}), \widetilde{x}\widehat{\hat{x}} \rangle \\ &= \langle \widetilde{x}f(\widetilde{x}), \widetilde{x}\widehat{\hat{x}} \rangle + \langle f(\widehat{x})f(\widetilde{x}), \widetilde{x}\widehat{\hat{x}} \rangle - \langle \widetilde{x}\widehat{\hat{x}}, \widetilde{x}\widehat{\hat{x}} \rangle - \langle \widetilde{x}f(\widehat{x}), \widetilde{x}\widehat{\hat{x}} \rangle \\ &= \langle \widetilde{x}\widehat{\hat{x}}, \widetilde{x}\widehat{\hat{x}} \rangle - \langle \overline{f(\widehat{x})f(\widetilde{x})}, \widetilde{x}\widehat{\hat{x}} \rangle \\ &\geq \langle \widetilde{x}\widehat{x}, \widetilde{x}\widehat{\hat{x}} \rangle - d(f(\widehat{x}), f(\widetilde{x}))d(\widehat{x}, \widetilde{x}) \end{split}$$

$$\geq d^2( ilde{x}, \hat{x}) - lpha d(\hat{x}, ilde{x}) d(\hat{x}, ilde{x})$$
  
 $\geq d^2( ilde{x}, \hat{x}) - lpha d^2(\hat{x}, ilde{x})$   
 $\geq (1 - lpha) d^2( ilde{x}, \hat{x}).$ 

Since  $0 < \alpha < 1$ , we have that  $d(\tilde{x}, \hat{x}) = 0$ , and so  $\tilde{x} = \hat{x}$ . Hence the sequence  $x_n$  converges strongly to  $\tilde{x}$ , which is the unique solution to the variational inequality (3.3). This completes the proof.

If  $f \equiv u$ , then the following result can be obtained directly from Theorem 3.3.

**Corollary 3.4** Let C be a closed convex subset of a complete CAT(0) space X, and let  $\{T(t)\}$  be a one-parameter continuous semigroup of nonexpansive mappings on C satisfying  $\mathcal{F} \neq \emptyset$  and uniformly asymptotically regular (in short, u.a.r.) on C, that is, for all  $h \ge 0$  and any bounded subset B of C,

 $\lim_{t\to\infty}\sup_{x\in B}d\big(T(h)\big(T(t)x\big),T(t)x\big)=0.$ 

Let u be any element in C. Suppose  $t_n \in [0, \infty)$ ,  $\alpha_n \in (0, 1)$  such that  $\lim_{n\to\infty} t_n = \infty$  and  $\lim_{n\to\infty} \alpha_n = 0$  and let  $\{x_n\}$  be given by

 $x_n = \alpha_n u \oplus (1 - \alpha_n) T(t_n) x_n.$ 

Then  $\{x_n\}$  converges strongly as  $n \to \infty$  to  $\tilde{x}$  such that  $\tilde{x} = P_F \tilde{x}$ , which is equivalent to the following variational inequality:

$$\langle \vec{\tilde{x}u}, \vec{x\tilde{x}} \rangle \ge 0, \quad x \in \mathcal{F}.$$
 (3.9)

**Theorem 3.5** Let C be a closed convex subset of a complete CAT(0) space X, and let  $\{T(t)\}$ be a one-parameter continuous semigroup of nonexpansive mappings on C satisfying  $\mathcal{F} \neq \emptyset$ and uniformly asymptotically regular (in short, u.a.r.) on C, that is, for all  $h \ge 0$  and any bounded subset B of C,

$$\lim_{t\to\infty}\sup_{x\in B}d\big(T(h)\big(T(t)x\big),T(t)x\big)=0.$$

Let f be a contraction on C with coefficient  $0 < \alpha < 1$ . Suppose that  $t_n \in [0, \infty)$ ,  $\alpha_n \in (0, 1)$ ,  $x_0 \in C$ , and  $\{x_n\}$  is given by

$$x_{n+1} = \alpha_n f(x_n) \oplus (1 - \alpha_n) T(t_n) x_n, \quad \forall n \ge 0,$$
(3.10)

where  $\{\alpha_n\} \subset (0,1)$  satisfies the following conditions:

- (i)  $\lim_{n\to\infty} \alpha_n = 0$ ;
- (ii)  $\sum_{n=0}^{\infty} \alpha_n = \infty$  and
- (iii)  $\lim_{n\to\infty} t_n = \infty$ .

Then  $\{x_n\}$  converges strongly as  $n \to \infty$  to  $\tilde{x}$  such that  $\tilde{x} = P_{\mathcal{F}}f(\tilde{x})$ , which is equivalent to the variational inequality (3.3).

$$d(x_{n+1},p) = d(\alpha_n f(x_n) \oplus (1-\alpha_n)T(t_n)x_n,p)$$
  

$$\leq \alpha_n d(f(x_n),p) + (1-\alpha_n)d(T(t_n)x_n,p)$$
  

$$\leq \alpha_n (d(f(x_n),f(p)) + d(f(p),p)) + (1-\alpha_n)d(T(t_n)x_n,p)$$
  

$$\leq \max \left\{ d(x_n,p), \frac{1}{1-\alpha}d(f(p),p) \right\}.$$

By induction, we have

$$d(x_n,p) \le \max\left\{d(x_0,p), \frac{1}{1-\alpha}d(f(p),p)\right\}$$

for all  $n \in \mathbb{N}$ . Hence  $\{x_n\}$  is bounded, so are  $\{T(t_n)x_n\}$  and  $\{f(x_n)\}$ . Using the assumption that  $\lim_{n\to\infty} \alpha_n = 0$ , we get that

$$d(x_{n+1}, T(t_n)x_n) \leq \alpha_n d(f(x_n), T(t_n)x_n) \to 0 \text{ as } n \to \infty.$$

Since  $\{T(t)\}$  is u.a.r. and  $\lim_{n\to\infty} t_n = \infty$ , then for all  $h \ge 0$ ,

$$\lim_{n\to\infty}d\big(T(h)\big(T(t_n)x_n\big),T(t_n)x_n\big)\leq \lim_{n\to\infty}\sup_{x\in B}d\big(T(h)\big(T(t_n)x\big),T(t_n)x\big)=0,$$

where *B* is any bounded subset of *C* containing  $\{x_n\}$ . Hence

$$d(x_{n+1}, T(h)x_{n+1})$$

$$\leq d(x_{n+1}, T(t_n)x_n) + d(T(t_n)x_n, T(h)(T(t_n)x_n))$$

$$+ d(T(h)(T(t_n)x_n), T(h)x_{n+1})$$

$$\leq 2d(x_{n+1}, T(t_n)x_n) + d(T(t_n)x_n, T(h)(T(t_n)x_n)) \to 0 \quad \text{as } n \to \infty.$$
(3.11)

Let  $\{z_m\}$  be a sequence in *C* such that

$$z_m = \alpha_m f(z_m) \oplus (1 - \alpha_m) T(t_m) z_m.$$

It follows from Theorem 3.3 that  $\{z_m\}$  converges strongly as  $m \to \infty$  to a fixed point  $\tilde{x} \in \mathcal{F}$ , which solves the variational inequality (3.3). Now, we claim that

$$\limsup_{n\to\infty} \langle \overrightarrow{f(\tilde{x})} \overset{\rightarrow}{\tilde{x}}, \overrightarrow{x_{n+1}} \overset{\rightarrow}{\tilde{x}} \rangle \leq 0.$$

It follows from Lemma 3.2(i) that

$$d^{2}(z_{m}, x_{n+1}) = \langle \overline{z_{m} x_{n+1}}, \overline{z_{m} x_{n+1}} \rangle$$

$$\leq \alpha_{m} \langle \overline{f(z_{m}) x_{n+1}}, \overline{z_{m} x_{n+1}} \rangle + (1 - \alpha_{m}) \langle \overline{T(t_{m}) z_{m} x_{n+1}}, \overline{z_{m} x_{n+1}} \rangle$$

$$= \alpha_{m} \langle \overline{f(z_{m}) f(\tilde{x})}, \overline{z_{m} x_{n+1}} \rangle + \alpha_{m} \langle \overline{f(\tilde{x})} \tilde{x}, \overline{z_{m} x_{n+1}} \rangle + \alpha_{m} \langle \overline{\tilde{x} z_{m}}, \overline{z_{m} x_{n+1}} \rangle$$

$$+ \alpha_{m} \langle \overrightarrow{z_{m}x_{n+1}}, \overrightarrow{z_{m}x_{n+1}} \rangle + (1 - \alpha_{m}) \langle \overrightarrow{T(t_{m})z_{m}T(t_{m})x_{n+1}}, \overrightarrow{z_{m}x_{n+1}} \rangle$$

$$+ (1 - \alpha_{m}) \langle \overrightarrow{T(t_{m})x_{n+1}x_{n+1}}, \overrightarrow{z_{m}x_{n+1}} \rangle$$

$$\leq \alpha_{m} \alpha d(z_{m}, \widetilde{x}) d(z_{m}, x_{n+1}) + \alpha_{m} \langle \overrightarrow{f(\widetilde{x})} \overset{\circ}{x}, \overrightarrow{z_{m}x_{n+1}} \rangle + \alpha_{m} d(\widetilde{x}, z_{m}) d(z_{m}, x_{n+1})$$

$$+ \alpha_{m} d^{2}(z_{m}, x_{n+1}) + (1 - \alpha_{m}) d^{2}(z_{m}, x_{n+1})$$

$$+ (1 - \alpha_{m}) d(T(t_{m})x_{n+1}, x_{n+1}) d(z_{m}, x_{n+1})$$

$$\leq \alpha_{m} \alpha d(z_{m}, \widetilde{x}) M + \alpha_{m} \langle \overrightarrow{f(\widetilde{x})} \overset{\circ}{x}, \overrightarrow{z_{m}x_{n+1}} \rangle + \alpha_{m} d(\widetilde{x}, z_{m}) M + \alpha_{m} d^{2}(z_{m}, x_{n+1})$$

$$+ (1 - \alpha_{m}) d^{2}(z_{m}, x_{n+1}) + (1 - \alpha_{m}) d(T(t_{m})x_{n+1}, x_{n+1}) M$$

$$\leq d^{2}(z_{m}, x_{n+1}) + \alpha_{m} \alpha d(z_{m}, \widetilde{x}) M + \alpha_{m} d(\widetilde{x}, z_{m}) M + d(T(t_{m})x_{n+1}, x_{n+1}) M$$

$$+ \alpha_{m} \langle \overrightarrow{f(\widetilde{x})} \overset{\circ}{x}, \overrightarrow{z_{m}x_{n+1}} \rangle,$$

where  $M \ge \sup_{m,n\ge 1} \{d(z_m, x_n)\}$ . This implies that

$$\left| \overline{f(\tilde{x})} \overset{\rightarrow}{x}, \overline{x_{n+1}} \overset{\rightarrow}{z_m} \right| \le (1+\alpha) d(z_m, \tilde{x}) M + \frac{d(T(t_m)x_{n+1}, x_{n+1})}{\alpha_m} M.$$
(3.12)

Taking the upper limit as  $n \to \infty$  first, and then  $m \to \infty$ , inequality (3.12) yields that

$$\limsup_{m \to \infty} \limsup_{n \to \infty} \langle \overline{f(\tilde{x})} \hat{x}, \overline{x_{n+1}} z_m \rangle \le 0.$$
(3.13)

Since

$$\begin{split} \langle \overrightarrow{f(\widetilde{x})} \overset{\sim}{\widetilde{x}}, \overrightarrow{x_{n+1}} \overset{\sim}{\widetilde{x}} \rangle &= \langle \overrightarrow{f(\widetilde{x})} \overset{\sim}{\widetilde{x}}, \overrightarrow{x_{n+1}} \overrightarrow{z_m} \rangle + \langle \overrightarrow{f(\widetilde{x})} \overset{\sim}{\widetilde{x}}, \overrightarrow{z_m} \overset{\sim}{\widetilde{x}} \rangle \\ &\leq \langle \overrightarrow{f(\widetilde{x})} \overset{\sim}{\widetilde{x}}, \overrightarrow{x_{n+1}} \overrightarrow{z_m} \rangle + d(f(\widetilde{x}), \widetilde{x}) d(z_m, \widetilde{x}). \end{split}$$

Thus, by taking the upper limit as  $n \to \infty$  first, and then  $m \to \infty$  the last inequality, it follows from  $z_m \to \tilde{x}$  and (3.13) that

$$\limsup_{n\to\infty}\langle \overrightarrow{f(\tilde{x})}\widetilde{\tilde{x}}, \overrightarrow{x_{n+1}}\widetilde{\tilde{x}}\rangle \leq 0.$$

Finally, we prove that  $x_n \to \tilde{x}$  as  $n \to \infty$ . For any  $n \in \mathbb{N}$ , we set  $y_n = \alpha_n \tilde{x} \oplus (1 - \alpha_n) T(t_n) x_n$ . It follows from Lemma 3.1 and Lemma 3.2(i), (ii) that

$$\begin{aligned} d^{2}(x_{n+1},\tilde{x}) &\leq d^{2}(y_{n},\tilde{x}) + 2\langle \overrightarrow{x_{n+1}y_{n}}, \overrightarrow{x_{n+1}\tilde{x}} \rangle \\ &\leq \left(\alpha_{n}d(\tilde{x},\tilde{x}) + (1-\alpha_{n})d\left(T(t_{n})x_{n},\tilde{x}\right)\right)^{2} \\ &\quad + 2\left[\alpha_{n}\langle \overrightarrow{f(x_{n})y_{n}}, \overrightarrow{x_{n+1}\tilde{x}} \rangle + (1-\alpha_{n})\langle \overrightarrow{T(t_{n})x_{n}y_{n}}, \overrightarrow{x_{n+1}\tilde{x}} \rangle\right] \\ &\leq (1-\alpha_{n})^{2}d^{2}(x_{n},\tilde{x}) + 2\left[\alpha_{n}\alpha_{n}\langle \overrightarrow{f(x_{n})\tilde{x}}, \overrightarrow{x_{n+1}\tilde{x}} \rangle + \alpha_{n}(1-\alpha_{n})\langle \overrightarrow{f(x_{n})T(t_{n})x_{n}}, \overrightarrow{x_{n+1}\tilde{x}} \rangle\right] \\ &\quad + (1-\alpha_{n})\alpha_{n}\langle \overrightarrow{T(t_{n})x_{n}\tilde{x}}, \overrightarrow{x_{n+1}\tilde{x}} \rangle + (1-\alpha_{n})(1-\alpha_{n})\langle \overrightarrow{T(t_{n})x_{n}T(t_{n})x_{n}}, \overrightarrow{x_{n+1}\tilde{x}} \rangle\right] \\ &\leq (1-\alpha_{n})^{2}d^{2}(x_{n},\tilde{x}) + 2\left[\alpha_{n}\alpha_{n}\langle \overrightarrow{f(x_{n})\tilde{x}}, \overrightarrow{x_{n+1}\tilde{x}} \rangle + \alpha_{n}(1-\alpha_{n})\langle \overrightarrow{f(x_{n})T(t_{n})x_{n}}, \overrightarrow{x_{n+1}\tilde{x}} \rangle \\ &\quad + (1-\alpha_{n})\alpha_{n}\langle \overrightarrow{T(t_{n})x_{n}\tilde{x}}, \overrightarrow{x_{n+1}\tilde{x}} \rangle + (1-\alpha_{n})^{2}d\left(T(t_{n})x_{n}, T(t_{n})x_{n}\right)d(x_{n+1}\tilde{x})\right] \end{aligned}$$

$$= (1 - \alpha_n)^2 d^2(x_n, \tilde{x}) + 2\left[\alpha_n^2 \langle \overline{f(x_n)} \overset{\rightarrow}{x}, \overline{x_{n+1}} \overset{\rightarrow}{x} \rangle + \alpha_n (1 - \alpha_n) \langle \overline{f(x_n)} \overset{\rightarrow}{x}, \overline{x_{n+1}} \overset{\rightarrow}{x} \rangle \right]$$

$$= (1 - \alpha_n)^2 d^2(x_n, \tilde{x}) + 2\alpha_n \langle \overline{f(x_n)} \overset{\rightarrow}{x}, \overline{x_{n+1}} \overset{\rightarrow}{x} \rangle$$

$$= (1 - \alpha_n)^2 d^2(x_n, \tilde{x}) + 2\alpha_n \langle \overline{f(x_n)} \overset{\rightarrow}{f(x)}, \overline{x_{n+1}} \overset{\rightarrow}{x} \rangle + 2\alpha_n \langle \overline{f(x)} \overset{\rightarrow}{x}, \overline{x_{n+1}} \overset{\rightarrow}{x} \rangle$$

$$\leq (1 - \alpha_n)^2 d^2(x_n, \tilde{x}) + 2\alpha_n \alpha d(x_n, \tilde{x}) d(x_{n+1}, \tilde{x}) + 2\alpha_n \langle \overline{f(x)} \overset{\rightarrow}{x}, \overline{x_{n+1}} \overset{\rightarrow}{x} \rangle$$

$$\leq (1 - \alpha_n)^2 d^2(x_n, \tilde{x}) + \alpha_n \alpha \left( d^2(x_n, \tilde{x}) + d^2(x_{n+1}, \tilde{x}) \right) + 2\alpha_n \langle \overline{f(x)} \overset{\rightarrow}{x}, \overline{x_{n+1}} \overset{\rightarrow}{x} \rangle,$$

which implies that

$$d^{2}(x_{n+1},\tilde{x}) \leq \frac{1 - (2 - \alpha)\alpha_{n} + \alpha_{n}^{2}}{1 - \alpha\alpha_{n}} d^{2}(x_{n},\tilde{x}) + \frac{2\alpha_{n}}{1 - \alpha\alpha_{n}} \langle \overrightarrow{f(\tilde{x})} \dot{\widetilde{x}}, \overrightarrow{x_{n+1}} \dot{\widetilde{x}} \rangle$$
$$\leq \frac{1 - (2 - \alpha)\alpha_{n}}{1 - \alpha\alpha_{n}} d^{2}(x_{n},\tilde{x}) + \frac{2\alpha_{n}}{1 - \alpha\alpha_{n}} \langle \overrightarrow{f(\tilde{x})} \dot{\widetilde{x}}, \overrightarrow{x_{n+1}} \dot{\widetilde{x}} \rangle + \alpha_{n}^{2} M,$$

where  $M \ge \sup_{n \ge 0} \{ d^2(x_n, \tilde{x}) \}$ . It then follows that

$$d^2(x_{n+1},\tilde{x}) \leq (1-\alpha'_n)d^2(x_n,\tilde{x}) + \alpha'_n\beta'_n,$$

where

$$\alpha'_n = \frac{2(1-\alpha)\alpha_n}{1-\alpha\alpha_n} \quad \text{and} \quad \beta'_n = \frac{(1-\alpha\alpha_n)\alpha_n}{2(1-\alpha)}M + \frac{1}{(1-\alpha)} \langle \overrightarrow{f(\tilde{x})} \overset{\rightarrow}{\tilde{x}}, \overrightarrow{x_{n+1}} \overset{\rightarrow}{\tilde{x}} \rangle.$$

Applying Lemma 2.8, we can conclude that  $x_n \rightarrow \tilde{x}$ . This completes the proof.

If  $f \equiv u$ , then the following corollary can be obtained directly from Theorem 3.5.

**Corollary 3.6** Let C be a closed convex subset of a complete CAT(0) space X, and let  $\{T(t)\}$  be a one-parameter continuous semigroup of nonexpansive mappings on C satisfying  $\mathcal{F} \neq \emptyset$  and uniformly asymptotically regular (in short, u.a.r.) on C, that is, for all  $h \ge 0$  and any bounded subset B of C,

$$\lim_{t\to\infty}\sup_{x\in B}d\big(T(h)\big(T(t)x\big),T(t)x\big)=0.$$

Suppose that  $t_n \in [0, \infty)$ ,  $\alpha_n \in (0, 1)$ ,  $x_0 \in C$  and  $\{x_n\}$  is given by

$$x_{n+1} = \alpha_n u \oplus (1 - \alpha_n) T(t_n) x_n, \quad \forall n \ge 0,$$
(3.14)

where  $\{\alpha_n\} \subset (0,1)$  satisfies the following conditions:

- (i)  $\lim_{n\to\infty} \alpha_n = 0$ ;
- (ii)  $\sum_{n=0}^{\infty} \alpha_n = \infty$  and
- (iii)  $\lim_{n\to\infty} t_n = \infty$ .

Then  $\{x_n\}$  converges strongly as  $n \to \infty$  to  $\tilde{x}$  such that  $\tilde{x} = P_F \tilde{x}$ , which is equivalent to the variational inequality (3.9).

### **Competing interests**

The authors declare that they have no competing interests.

### Authors' contributions

Both authors read and approved the final manuscript.

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