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Some convergence results for multivalued quasi-nonexpansive mappings in $CAT(\kappa)$ spaces

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Abstract

In this paper, we prove some strong and Δ -convergence theorems for a finite family of multivalued quasi-nonexpansive mappings satisfying condition (E) in $CAT(\kappa)$ spaces. Our results extend the corresponding results of Abkar and Eslamian (Nonlinear Anal. 75:1895-1903, 2012), Panyanak (Fixed Point Theory Appl. 2014:1, 2014), Shahzad and Zegeye (Nonlinear Anal. 71:838-844, 2009) and many others.

MSC: 47H10; 47J25

Keywords: fixed points; $CAT(\kappa)$ spaces; multivalued quasi-nonexpansive mappings

1 Introduction

Fixed point theory for multivalued contractions and nonexpansive mappings using the Hausdorff metric was first studied by Markin [1] and Nadler [2]. Since then different iterative processes have been used to approximate fixed points of multivalued nonexpansive mappings. Sastry and Babu [3] defined Mann and Ishikawa iterates for a multivalued map T in a Hilbert space. Panyanak [4] and Song and Wang [5] generalized the results of Sastry and Babu [3] to uniformly convex Banach spaces. Later, Shahzad and Zegeye [6] defined two types of Ishikawa iteration processes and extended the results of [3–5]. The reader may consult [7] for more detail. Recently, Abkar and Eslamian [8] established strong and Δ -convergence theorems for the following iterative process for a finite family of multivalued quasi-nonexpansive mappings satisfying condition (E) in $CAT(0)$ spaces:

$$\begin{cases} y_{n,1} = (1 - \alpha_{n,1})x_n \oplus \alpha_{n,1}z_{n,1}, \\ y_{n,2} = (1 - \alpha_{n,2})x_n \oplus \alpha_{n,2}z_{n,2}, \\ \dots \\ y_{n,m-1} = (1 - \alpha_{n,m-1})x_n \oplus \alpha_{n,m-1}z_{n,m-1}, \\ x_{n+1} = (1 - \alpha_{n,m})x_n \oplus \alpha_{n,m}z_{n,m}, \quad n \geq 1, \end{cases} \quad (1)$$

where $z_{n,1} \in T_1(x_n)$ and $z_{n,k} \in T_k(y_{n,k-1})$ for $k = 2, \dots, m$. It is easy to see that if $m = 2$ and $T_1 = T_2 = T$, then the sequence $\{x_n\}$ defined by (1) is the Ishikawa iteration:

$$\begin{cases} y_n = (1 - \alpha_{n,1})x_n \oplus \alpha_{n,1}z_n, \\ x_{n+1} = (1 - \alpha_{n,2})x_n \oplus \alpha_{n,2}z'_n, \quad n \geq 1, \end{cases}$$

where $z_n \in Tx_n$ and $z'_n \in Ty_n$.

The purpose of the paper is to extend and improve the corresponding results of Abkar and Eslamian [8] to the general setting of $CAT(\kappa)$ spaces, which are geodesic spaces of bounded curvature, where $\kappa \in \mathbb{R}$ is the curvature bound. For example, the n -dimensional hyperbolic space \mathbb{H}^n is a $CAT(-1)$ space and the n -dimensional unit sphere S^n is a $CAT(1)$ space (see Section 2 for details). It is worth mentioning that any $CAT(\kappa)$ space is a $CAT(\kappa')$ space for $\kappa' \geq \kappa$. Thus all results for $CAT(\kappa)$ spaces with $\kappa > 0$ immediately apply to any $CAT(0)$ space.

Let D be a subset of a metric space (X, d) . Recall that an element $p \in D$ is called a *fixed point* of a single-valued mapping T if $p = Tp$ and of a multivalued mapping T if $p \in Tp$. The set of fixed points of T is denoted by $F(T)$. D is said to be *proximal* if, for each $x \in X$, there exists an element $x^* \in D$ such that

$$d(x, D) = \inf\{d(x, y) : y \in D\} = d(x, x^*).$$

It is evident that every proximal set is closed and every compact set is proximal (see [9]).

Let 2^D be a family of nonempty subsets of D . We denote by $\mathcal{C}(D)$, $\mathcal{P}(D)$ and $\mathcal{K}(D)$ the families of nonempty closed subsets, nonempty proximal subsets and nonempty compact subsets of D , respectively. The *Hausdorff metric* on $\mathcal{K}(D)$ is defined by

$$H(A, B) = \max\left\{\sup_{x \in A} d(x, B), \sup_{y \in B} d(y, A)\right\}$$

for all $A, B \in \mathcal{K}(D)$, where $d(x, B) = \inf\{d(x, z) : z \in B\}$.

Definition 1 A multivalued mapping $T : D \rightarrow 2^D$ is said to

- (i) be *nonexpansive* if, for all $x, y \in D$,

$$H(Tx, Ty) \leq d(x, y);$$

- (ii) be *quasi-nonexpansive* if $F(T) \neq \emptyset$ and

$$H(Tx, Tp) \leq d(x, p), \quad \forall p \in F(T), x \in D;$$

- (iii) satisfy *condition* (E_μ) provided that

$$d(x, Ty) \leq \mu d(x, Tx) + d(x, y), \quad x, y \in D \text{ and } \mu \geq 1.$$

We say that T satisfies *condition* (E) whenever T satisfies (E_μ) for some $\mu \geq 1$.

Remark 1 There exist multivalued quasi-nonexpansive mappings satisfying condition (E) . For example, define a mapping $T : [0, 5] \rightarrow [0, 5]$ by

$$Tx = \begin{cases} [0, \frac{x}{5}], & x \neq 5, \\ \{1\}, & x = 5. \end{cases}$$

Let $x, y \in [0, 5)$, then we get

$$H(Tx, Ty) = \left| \frac{x-y}{5} \right| \leq d(x, y).$$

If $x \in [0, 4]$ and $y = 5$, then

$$H(Tx, Ty) = 1 \leq 5 - x = d(x, y).$$

If $x \in (4, 5)$ and $y = 5$, we have

$$d(x, Tx) = \frac{4x}{5}, \quad d(x, y) = 5 - x, \quad H(Tx, Ty) = 1 \quad \text{and} \quad d(x, Ty) = x - 1.$$

Then it is easy to prove that T has the required properties.

In 1991, Xu [10] introduced the best approximation operator P_T to find fixed points of $*$ -nonexpansive multivalued mappings. In 2013, Dehghan [11] obtained the demiclosed principle of such mappings and approximated their fixed points using P_T . Let $P_T : D \rightarrow 2^D$ be a multivalued mapping defined by

$$P_T(x) = \{u \in Tx : d(x, u) = d(x, Tx)\}.$$

By [12] we have the following lemma.

Lemma 1 [12] *Let D be a nonempty subset of a metric space (X, d) and $T : D \rightarrow \mathcal{P}(D)$ be a multivalued mapping. Then*

- (i) $d(x, Tx) = d(x, P_T(x))$ for all $x \in D$;
- (ii) $x \in F(T) \Leftrightarrow x \in F(P_T) \Leftrightarrow P_T(x) = \{x\}$;
- (iii) $F(T) = F(P_T)$.

2 Preliminaries

The study of fixed points in $CAT(\kappa)$ spaces was initiated by Kirk [13, 14]. A few recent new convergence results of classical iterations on $CAT(\kappa)$ spaces have been obtained (see, e.g., [15–19] and the references therein). For example, Panyanak [19] in 2014 proved the strong convergence of two types of Ishikawa iteration processes introduced in Shahzad and Zegeye [6] for some multivalued quasi-nonexpansive mappings in $CAT(1)$ spaces.

Let (X, d) be a metric space and $x, y \in X$ with $l = d(x, y)$. For $x, y \in X$, a *geodesic path* joining x to y is an isometry $c : [0, l] \rightarrow X$ such that $c(0) = x, c(l) = y$. The image of a geodesic path is called a *geodesic segment*, and we shall denote a definite choice of this geodesic segment by $[x, y]$. A metric space X is a *geodesic space* (*r-geodesic space*) if every two points of X (every two points with distance smaller than r) are joined by a geodesic segment, and X is a *uniquely geodesic space* (*r-uniquely geodesic space*) if there is exactly one geodesic segment joining x and y for any $x, y \in X$ (for any $x, y \in X$ with $d(x, y) < r$). A subset D of X is said to be *convex* if D includes every geodesic segment joining any two of its points.

The n -dimensional sphere S^n is the set $\{x = (x_1, \dots, x_{n+1}) \in \mathbb{R}^{n+1} : \langle x|x \rangle = 1\}$, where $\langle \cdot | \cdot \rangle$ is the Euclidean scalar product. It is endowed with the following metric: $d_{S^n}(x, y) = \arccos \langle x|y \rangle$, $x, y \in S^n$.

Definition 2 Given $\kappa \in \mathbb{R}$, denote by M_κ^n the following metric spaces:

- (i) if $\kappa = 0$, then M_0^n is the Euclidean space \mathbb{R}^n ;
- (ii) if $\kappa > 0$, then M_κ^n is obtained from the sphere S^n by multiplying the distance function by $1/\sqrt{\kappa}$;
- (iii) if $\kappa < 0$, then M_κ^n is obtained from the hyperbolic n -space \mathbb{H}^n by multiplying the distance function by $1/\sqrt{-\kappa}$.

A *geodesic triangle* $\Delta(x, y, z)$ in a geodesic space (X, d) consists of three points x, y, z of X and three geodesic segments joining each pair of vertices. A *comparison triangle* of a geodesic triangle $\Delta(x, y, z)$ is the triangle $\bar{\Delta}(\bar{x}, \bar{y}, \bar{z})$ in M_κ^2 such that

$$d(x, y) = d_{M_\kappa^2}(\bar{x}, \bar{y}), \quad d(y, z) = d_{M_\kappa^2}(\bar{y}, \bar{z}), \quad d(z, x) = d_{M_\kappa^2}(\bar{z}, \bar{x}).$$

If $\kappa > 0$, then such a triangle $\bar{\Delta}$ always exists whenever $d(x, y) + d(y, z) + d(z, x)$ is less than $2D_\kappa$, where $D_\kappa = \pi/\sqrt{\kappa}$. A point $\bar{p} \in [\bar{x}, \bar{y}]$ is called a *comparison point* for $p \in [x, y]$ if $d(x, p) = d_{M_\kappa^2}(\bar{x}, \bar{p})$. A geodesic triangle in X is said to satisfy the *CAT(κ) inequality* if for any $p, q \in \Delta(x, y, z)$ and for their comparison points $\bar{p}, \bar{q} \in \bar{\Delta}(\bar{x}, \bar{y}, \bar{z})$, we have

$$d(p, q) \leq d_{M_\kappa^2}(\bar{p}, \bar{q}).$$

Definition 3 Given $\kappa > 0$, a metric space X is a *CAT(κ) space* if X is D_κ -geodesic and any geodesic triangle $\Delta(x, y, z)$ in X with $d(x, y) + d(y, z) + d(z, x) < 2D_\kappa$ satisfies the CAT(κ) inequality.

In 1976, Lim [20] introduced the concept of Δ -convergence in a general metric space. Let $\{x_n\}$ be a bounded sequence in a CAT(κ) space X . For $x \in X$, we define

$$r(x, \{x_n\}) = \limsup_{n \rightarrow \infty} d(x, x_n).$$

The *asymptotic radius* $r(\{x_n\})$ of $\{x_n\}$ is given by

$$r(\{x_n\}) = \inf\{r(x, \{x_n\}) : x \in X\}.$$

The *asymptotic center* $A(\{x_n\})$ of $\{x_n\}$ is the set

$$A(\{x_n\}) = \{x \in X : r(x, \{x_n\}) = r(\{x_n\})\}.$$

A sequence $\{x_n\}$ in a CAT(κ) space X is said to Δ -converge to $x \in X$ if x is the unique asymptotic center of $\{u_n\}$ for every subsequence $\{u_n\}$ of $\{x_n\}$.

It follows from [21] that CAT(κ) spaces are uniquely geodesic spaces. In this paper, we mainly focus on CAT(κ) spaces with $\kappa > 0$, and we now collect some elementary facts about them.

Lemma 2 [15] *Let $\kappa > 0$ and (X, d) be a $CAT(\kappa)$ space with $\text{diam}(X) =: \sup\{d(u, v) : u, v \in X\} < \frac{\pi}{2\sqrt{\kappa}}$. Then $A(\{x_n\})$ consists of exactly one point.*

Lemma 3 [15] *Let $\kappa > 0$ and (X, d) be a complete $CAT(\kappa)$ space with $\text{diam}(X) \leq \frac{\pi/2-\varepsilon}{\sqrt{\kappa}}$ for some $\varepsilon \in (0, \pi/2)$. Then every sequence in X has a Δ -convergent subsequence.*

Lemma 4 [15] *Let $\kappa > 0$ and (X, d) be a complete $CAT(\kappa)$ space with $\text{diam}(X) \leq \frac{\pi/2-\varepsilon}{\sqrt{\kappa}}$ for some $\varepsilon \in (0, \pi/2)$. D is a closed convex subset of X . If $\{x_n\} \subseteq D$ and $\Delta\text{-}\lim_{n \rightarrow \infty} x_n = x$, then $x \in D$.*

Since the asymptotic center is unique by Lemma 2, we can obtain the following lemma.

Lemma 5 [22] *Let $\kappa > 0$ and (X, d) be a complete $CAT(\kappa)$ space with $\text{diam}(X) \leq \frac{\pi/2-\varepsilon}{\sqrt{\kappa}}$ for some $\varepsilon \in (0, \pi/2)$. Let $\{x_n\}$ be a sequence in X with $A(\{x_n\}) = \{x\}$. If $\{u_n\}$ is a subsequence of $\{x_n\}$ with $A(\{u_n\}) = \{u\}$ and $\{d(x_n, u)\}$ converges, then $x = u$.*

Lemma 6 [21] *Let $\kappa > 0$ and (X, d) be a complete $CAT(\kappa)$ space with $\text{diam}(X) \leq \frac{\pi/2-\varepsilon}{\sqrt{\kappa}}$ for some $\varepsilon \in (0, \pi/2)$. Then, for any $x, y, z \in X$ and $t \in [0, 1]$, we have*

$$d((1-t)x \oplus ty, z) \leq (1-t)d(x, z) + td(y, z).$$

Lemma 7 [23] *Let $\kappa > 0$ and (X, d) be a $CAT(\kappa)$ space with $\text{diam}(X) \leq \frac{\pi/2-\varepsilon}{\sqrt{\kappa}}$ for some $\varepsilon \in (0, \pi/2)$. Then, for any $x, y, z \in X$ and $t \in [0, 1]$, we have*

$$d^2((1-t)x \oplus ty, z) \leq (1-t)d^2(x, z) + td^2(y, z) - \frac{R}{2}t(1-t)d^2(x, y),$$

where $R = (\pi - 2\varepsilon) \tan(\varepsilon)$.

3 Main results

In this section, we prove our main theorems.

Theorem 1 (Demiclosed principle) *Let $\kappa > 0$ and (X, d) be a complete $CAT(\kappa)$ space with $\text{diam}(X) \leq \frac{\pi/2-\varepsilon}{\sqrt{\kappa}}$ for some $\varepsilon \in (0, \pi/2)$. Let D be a nonempty closed convex subset of X , and let $T : D \rightarrow \mathcal{K}(D)$ be a multivalued mapping satisfying condition (E). If $\{x_n\}$ is a sequence in D such that $\lim_{n \rightarrow \infty} d(x_n, Tx_n) = 0$ and $\Delta\text{-}\lim_{n \rightarrow \infty} x_n = x$, then $x \in Tx$, from which we may formally say that $I - T$ is demiclosed at zero.*

Proof Since $\Delta\text{-}\lim_{n \rightarrow \infty} x_n = x$, by Lemma 4 we have $x \in D$. For each $n \geq 1$, we choose $z_n \in Tx$ such that

$$d(x_n, z_n) = d(x_n, Tx).$$

By the compactness of Tx , there is a subsequence $\{z_{n_k}\}$ of $\{z_n\}$ such that $\lim_{k \rightarrow \infty} z_{n_k} = w \in Tx$. It follows from condition (E) that

$$d(x_{n_k}, z_{n_k}) = d(x_{n_k}, Tx) \leq \mu d(x_{n_k}, Tx_{n_k}) + d(x_{n_k}, x)$$

for some $\mu \geq 1$. Note that

$$d(x_{n_k}, w) \leq d(x_{n_k}, z_{n_k}) + d(z_{n_k}, w) \leq \mu d(x_{n_k}, Tx_{n_k}) + d(x_{n_k}, x) + d(z_{n_k}, w).$$

Thus

$$\limsup_{k \rightarrow \infty} d(x_{n_k}, w) \leq \limsup_{k \rightarrow \infty} d(x_{n_k}, x).$$

By the uniqueness of asymptotic centers, we obtain $x = w \in Tx$. The proof is completed. \square

Theorem 2 *Let $\kappa > 0$ and (X, d) be a complete $CAT(\kappa)$ space with $\text{diam}(X) \leq \frac{\pi/2-\varepsilon}{\sqrt{\kappa}}$ for some $\varepsilon \in (0, \pi/2)$. Let D be a nonempty closed convex subset of X , and let $T_i : D \rightarrow \mathcal{K}(D)$ ($i = 1, \dots, m$) be a family of multivalued quasi-nonexpansive mappings satisfying condition (E). Suppose that $\mathcal{F} = \bigcap_{i=1}^m F(T_i) \neq \emptyset$ and $T_i(p) = \{p\}$ for each $p \in \mathcal{F}$. Let $\alpha_{n,i} \in [a, b] \subset (0, 1)$ ($i = 1, \dots, m$). Then $\{x_n\}$ defined by (1) Δ -converges to some point in \mathcal{F} .*

Proof We divide our proof into several steps.

Step 1. In the sequel, we shall show that $\lim_{n \rightarrow \infty} d(x_n, p)$ exists for any $p \in \mathcal{F}$. Since T_1 is quasi-nonexpansive, by Lemma 6 we have

$$\begin{aligned} d(y_{n,1}, p) &= d((1 - \alpha_{n,1})x_n \oplus \alpha_{n,1}z_{n,1}, p) \\ &\leq (1 - \alpha_{n,1})d(x_n, p) + \alpha_{n,1}d(z_{n,1}, p) \\ &= (1 - \alpha_{n,1})d(x_n, p) + \alpha_{n,1}d(z_{n,1}, T_1(p)) \\ &\leq (1 - \alpha_{n,1})d(x_n, p) + \alpha_{n,1}H(T_1(x_n), T_1(p)) \\ &\leq (1 - \alpha_{n,1})d(x_n, p) + \alpha_{n,1}d(x_n, p) \\ &= d(x_n, p) \end{aligned}$$

and

$$\begin{aligned} d(y_{n,2}, p) &= d((1 - \alpha_{n,2})x_n \oplus \alpha_{n,2}z_{n,2}, p) \\ &\leq (1 - \alpha_{n,2})d(x_n, p) + \alpha_{n,2}d(z_{n,2}, p) \\ &= (1 - \alpha_{n,2})d(x_n, p) + \alpha_{n,2}d(z_{n,2}, T_2(p)) \\ &\leq (1 - \alpha_{n,2})d(x_n, p) + \alpha_{n,2}H(T_2(y_{n,1}), T_2(p)) \\ &\leq (1 - \alpha_{n,2})d(x_n, p) + \alpha_{n,2}d(y_{n,1}, p) \\ &\leq d(x_n, p). \end{aligned}$$

By continuing this process we have

$$d(x_{n+1}, p) \leq d(x_n, p).$$

It implies that $d(x_n, p)$ is decreasing and bounded below, thus $\lim_{n \rightarrow \infty} d(x_n, p)$ exists for any $p \in \mathcal{F}$.

Step 2. We shall show that $\lim_{n \rightarrow \infty} d(x_n, T_i(x_n)) = 0$ for $i = 1, \dots, m$. In fact, by Lemma 7 we obtain

$$\begin{aligned} d^2(y_{n,1}, p) &= d^2((1 - \alpha_{n,1})x_n \oplus \alpha_{n,1}z_{n,1}, p) \\ &\leq (1 - \alpha_{n,1})d^2(x_n, p) + \alpha_{n,1}d^2(z_{n,1}, p) - \frac{R}{2}\alpha_{n,1}(1 - \alpha_{n,1})d^2(x_n, z_{n,1}) \\ &= (1 - \alpha_{n,1})d^2(x_n, p) + \alpha_{n,1}d^2(z_{n,1}, T_1(p)) - \frac{R}{2}\alpha_{n,1}(1 - \alpha_{n,1})d^2(x_n, z_{n,1}) \\ &\leq (1 - \alpha_{n,1})d^2(x_n, p) + \alpha_{n,1}H^2(T_1(x_n), T_1(p)) - \frac{R}{2}\alpha_{n,1}(1 - \alpha_{n,1})d^2(x_n, z_{n,1}) \\ &\leq (1 - \alpha_{n,1})d^2(x_n, p) + \alpha_{n,1}d^2(x_n, p) - \frac{R}{2}\alpha_{n,1}(1 - \alpha_{n,1})d^2(x_n, z_{n,1}) \\ &= d^2(x_n, p) - \frac{R}{2}\alpha_{n,1}(1 - \alpha_{n,1})d^2(x_n, z_{n,1}) \end{aligned}$$

and

$$\begin{aligned} d^2(y_{n,2}, p) &= d^2((1 - \alpha_{n,2})x_n \oplus \alpha_{n,2}z_{n,2}, p) \\ &\leq (1 - \alpha_{n,2})d^2(x_n, p) + \alpha_{n,2}d^2(z_{n,2}, p) - \frac{R}{2}\alpha_{n,2}(1 - \alpha_{n,2})d^2(x_n, z_{n,2}) \\ &= (1 - \alpha_{n,2})d^2(x_n, p) + \alpha_{n,2}d^2(z_{n,2}, T_2(p)) - \frac{R}{2}\alpha_{n,2}(1 - \alpha_{n,2})d^2(x_n, z_{n,2}) \\ &\leq (1 - \alpha_{n,2})d^2(x_n, p) + \alpha_{n,2}H^2(T_2(y_{n,1}), T_2(p)) - \frac{R}{2}\alpha_{n,2}(1 - \alpha_{n,2})d^2(x_n, z_{n,2}) \\ &\leq (1 - \alpha_{n,2})d^2(x_n, p) + \alpha_{n,2}d^2(y_{n,1}, p) - \frac{R}{2}\alpha_{n,2}(1 - \alpha_{n,2})d^2(x_n, z_{n,2}) \\ &\leq d^2(x_n, p) - \frac{R}{2}\alpha_{n,2}\alpha_{n,1}(1 - \alpha_{n,1})d^2(x_n, z_{n,1}) - \frac{R}{2}\alpha_{n,2}(1 - \alpha_{n,2})d^2(x_n, z_{n,2}). \end{aligned}$$

Similarly, we get

$$\begin{aligned} d^2(x_{n+1}, p) &= d^2((1 - \alpha_{n,m})x_n \oplus \alpha_{n,m}z_{n,m}, p) \\ &\leq (1 - \alpha_{n,m})d^2(x_n, p) + \alpha_{n,m}d^2(z_{n,m}, p) - \frac{R}{2}\alpha_{n,m}(1 - \alpha_{n,m})d^2(x_n, z_{n,m}) \\ &= (1 - \alpha_{n,m})d^2(x_n, p) + \alpha_{n,m}d^2(z_{n,m}, T_2(p)) - \frac{R}{2}\alpha_{n,m}(1 - \alpha_{n,m})d^2(x_n, z_{n,m}) \\ &\leq (1 - \alpha_{n,m})d^2(x_n, p) + \alpha_{n,m}H^2(T_m(y_{n,m-1}), T_m(p)) \\ &\quad - \frac{R}{2}\alpha_{n,m}(1 - \alpha_{n,m})d^2(x_n, z_{n,m}) \\ &\leq (1 - \alpha_{n,m})d^2(x_n, p) + \alpha_{n,m}d^2(y_{n,m-1}, p) - \frac{R}{2}\alpha_{n,m}(1 - \alpha_{n,m})d^2(x_n, z_{n,m}) \\ &\leq d^2(x_n, p) - \frac{R}{2}\alpha_{n,m}(1 - \alpha_{n,m})d^2(x_n, z_{n,m}) \\ &\quad - \frac{R}{2}\alpha_{n,m}\alpha_{n,m-1}(1 - \alpha_{n,m-1})d^2(x_n, z_{n,m-1}) - \dots \\ &\quad - \frac{R}{2}\alpha_{n,m}\alpha_{n,m-1} \dots \alpha_{n,1}(1 - \alpha_{n,1})d^2(x_n, z_{n,1}). \end{aligned}$$

Then we have

$$\begin{aligned} \frac{R}{2} a^m (1-b) d^2(x_n, z_{n,1}) &\leq \frac{R}{2} \alpha_{n,m} \alpha_{n,m-1} \cdots \alpha_{n,1} (1-\alpha_{n,1}) d^2(x_n, z_{n,1}) \\ &\leq d^2(x_n, p) - d^2(x_{n+1}, p), \end{aligned}$$

which yields that

$$\sum_{n=1}^{\infty} \frac{R}{2} a^m (1-b) d^2(x_n, z_{n,1}) \leq d^2(x_1, p) < \infty,$$

and hence

$$\lim_{n \rightarrow \infty} d(x_n, z_{n,1}) = 0.$$

Similarly, we can also have

$$\lim_{n \rightarrow \infty} d(x_n, z_{n,k}) = 0 \quad (k = 2, \dots, m).$$

Thus we obtain

$$\lim_{n \rightarrow \infty} d(x_n, T_1(x_n)) \leq \lim_{n \rightarrow \infty} d(x_n, z_{n,1}) = 0, \tag{2}$$

$$\lim_{n \rightarrow \infty} d(x_n, T_k(y_{n,k-1})) \leq \lim_{n \rightarrow \infty} d(x_n, z_{n,k}) = 0 \tag{3}$$

and

$$\lim_{n \rightarrow \infty} d(x_n, y_{n,k-1}) = \alpha_{n,k-1} \lim_{n \rightarrow \infty} d(x_n, z_{n,k-1}) = 0 \tag{4}$$

for $k = 2, \dots, m$. Now, by condition (E), (3) and (4), we have, for some $\mu \geq 1$,

$$\begin{aligned} d(x_n, T_k(x_n)) &\leq d(x_n, y_{n,k-1}) + d(y_{n,k-1}, T_k(x_n)) \\ &\leq d(x_n, y_{n,k-1}) + \mu d(y_{n,k-1}, T_k(y_{n,k-1})) + d(x_n, y_{n,k-1}) \\ &\leq d(x_n, y_{n,k-1}) + \mu d(y_{n,k-1}, x_n) + \mu d(x_n, T_k(y_{n,k-1})) \\ &\quad + d(x_n, y_{n,k-1}) \rightarrow 0 \end{aligned} \tag{5}$$

as $n \rightarrow \infty$ (for $k = 2, \dots, m$). By (2) and (5) we have

$$\lim_{n \rightarrow \infty} d(x_n, T_i(x_n)) = 0$$

for $i = 1, \dots, m$.

Step 3. Now we are in a position to prove the Δ -convergence of $\{x_n\}$. In fact, let $W_\omega(x_n) := \cup A(\{u_n\})$ for all subsequences $\{u_n\}$ of $\{x_n\}$. We claim that $W_\omega(x_n) \subset \mathcal{F}$. Let $u \in W_\omega(x_n)$, then there exists a subsequence $\{u_n\}$ of $\{x_n\}$ such that $A(\{u_n\}) = \{u\}$. By Lemma 3 and Lemma 4, there exists a subsequence $\{v_n\}$ of $\{u_n\}$ such that $\Delta\text{-}\lim_{n \rightarrow \infty} v_n = v \in D$. Since $\lim_{n \rightarrow \infty} d(v_n, T_i v_n) = 0$ ($i = 1, \dots, m$), it follows from Theorem 1 that $v \in \mathcal{F}$

and thus $\lim_{n \rightarrow \infty} d(x_n, v)$ exists by Step 1. By Lemma 5, $u = v \in \mathcal{F}$, which implies that $W_\omega(x_n) \subset \mathcal{F}$. Let $\{u_n\}$ be a subsequence of $\{x_n\}$ with $A(\{u_n\}) = \{u\}$, and let $A(\{x_n\}) = \{x\}$. Since $u \in W_\omega(x_n) \subset \mathcal{F}$ and $\lim_{n \rightarrow \infty} d(x_n, u)$ converges, we get $x = u$ by Lemma 5. It implies that $W_\omega(x_n)$ consists of exactly one point. The proof is completed. \square

Remark 2 Theorem 2 improves and extends the corresponding results in Abkar and Eslamian [8, Theorem 3.6].

In the sequel, we make use of *condition (A)* introduced by Senter and Dotson [24]. A mapping $T : D \rightarrow D$, where D is a subset of a normed space E , is said to satisfy condition (A) if there exists a nondecreasing function $f : [0, \infty) \rightarrow [0, \infty)$ with $f(0) = 0, f(r) > 0$ for all $r > 0$ such that

$$\|x - Tx\| \geq f(d(x, F(T))) \quad \text{for all } x \in D.$$

Theorem 3 Let $\kappa > 0$ and (X, d) be a complete $CAT(\kappa)$ space with $\text{diam}(X) \leq \frac{\pi/2 - \varepsilon}{\sqrt{\kappa}}$ for some $\varepsilon \in (0, \pi/2)$. Let D be a nonempty closed convex subset of X , and let $T_i : D \rightarrow \mathcal{C}(D)$ ($i = 1, \dots, m$) be a family of multivalued quasi-nonexpansive mappings satisfying condition (E). Suppose that $\mathcal{F} = \bigcap_{i=1}^m F(T_i) \neq \emptyset$ and $T_i p = \{p\}$ for each $p \in \mathcal{F}$. Let $\alpha_{n,i} \in [a, b] \subset (0, 1)$ ($i = 1, \dots, m$). Assume that there is a nondecreasing function $f : [0, \infty) \rightarrow [0, \infty)$ with $f(0) = 0, f(r) > 0$ for all $r > 0$ such that for some $i = 1, \dots, m$,

$$d(x_n, T_i(x_n)) \geq f(d(x_n, \mathcal{F})). \tag{6}$$

Then $\{x_n\}$ defined by (1) converges strongly to some point in \mathcal{F} .

Proof As in the proof of Theorem 2, for $i = 1, \dots, m$, we have $\lim_{n \rightarrow \infty} d(x_n, T_i(x_n)) = 0$. Hence by assumption (6) we obtain $\lim_{n \rightarrow \infty} d(x_n, \mathcal{F}) = 0$. Now we can choose a subsequence $\{x_{n_k}\} \subset \{x_n\}$ and a subsequence $\{p_k\} \subset \mathcal{F}$ such that for all positive integer $k \geq 1$,

$$d(x_{n_k}, p_k) < \frac{1}{2^k}.$$

Since for each $p \in \mathcal{F}$ the sequence $\{d(x_n, p)\}$ is decreasing, we get

$$d(x_{n_{k+1}}, p_k) \leq d(x_{n_k}, p_k) < \frac{1}{2^k}.$$

Hence

$$d(p_{k+1}, p_k) \leq d(x_{n_{k+1}}, p_{k+1}) + d(x_{n_{k+1}}, p_k) < \frac{1}{2^{k+1}} + \frac{1}{2^k} < \frac{1}{2^{k-1}}.$$

Then $\{p_k\}$ is a Cauchy sequence in D . Without loss of generality, we can assume that $p_k \rightarrow p^* \in D$. Since for each $i = 1, \dots, m$

$$d(p^*, T_i(p^*)) = \lim_{n \rightarrow \infty} d(p_k, T_i(p_k)) \leq \lim_{n \rightarrow \infty} H(T_i(p_k), T_i(p^*)) \leq \lim_{k \rightarrow \infty} d(p_k, p^*) = 0,$$

then $p^* \in \mathcal{F}$ and $\{x_{n_k}\}$ converges strongly to p^* . Since $\lim_{n \rightarrow \infty} d(x_n, p^*)$ exists, it follows that $\{x_n\}$ converges strongly to p^* . The proof is completed. \square

Remark 3 Theorem 3 improves and extends the corresponding results in Abkar and Es-lamian [8, Theorem 3.9] and Panyanak [19, Theorem 3.2].

Theorem 4 Let $\kappa > 0$ and (X, d) be a complete $CAT(\kappa)$ space with $diam(X) \leq \frac{\pi/2-\varepsilon}{\sqrt{\kappa}}$ for some $\varepsilon \in (0, \pi/2)$. D is a nonempty closed convex subset of X . Let $T_i : D \rightarrow \mathcal{P}(D)$ ($i = 1, \dots, m$) be a family of multivalued mappings with $\mathcal{F} = \bigcap_{i=1}^m F(T_i) \neq \emptyset$ such that P_{T_i} is quasi-nonexpansive satisfying condition (E). For $x_1 \in D$, define the sequence $\{x_n\} \subset D$ as follows:

$$\begin{cases} y_{n,1} = (1 - \beta_{n,1})x_n \oplus \beta_{n,1}z_{n,1}, \\ y_{n,2} = (1 - \beta_{n,2})x_n \oplus \beta_{n,2}z_{n,2}, \\ \dots \\ y_{n,m-1} = (1 - \beta_{n,m-1})x_n \oplus \beta_{n,m-1}z_{n,m-1}, \\ x_{n+1} = (1 - \beta_{n,m})x_n \oplus \beta_{n,m}z_{n,m}, \quad n \geq 1, \end{cases} \tag{7}$$

where $z_{n,1} \in P_{T_1}(x_n)$, $z_{n,k} \in P_{T_k}(y_{n,k-1})$ ($k = 2, \dots, m$) and $\beta_{n,i} \in [a, b] \subset (0, 1)$ ($i = 1, \dots, m$). Assume that there is a nondecreasing function $f : [0, \infty) \rightarrow [0, \infty)$ with $f(0) = 0, f(r) > 0$ for all $r > 0$ such that for some $i = 1, \dots, m$,

$$d(x_n, T_i(x_n)) \geq f(d(x_n, \mathcal{F})). \tag{8}$$

Then $\{x_n\}$ defined by (7) converges strongly to some point in \mathcal{F} .

Proof It follows from Lemma 1 and (8) that

$$d(x_n, P_{T_i}(x_n)) = d(x_n, T_i(x_n)) \geq f(d(x_n, \mathcal{F})) = f\left(d\left(x_n, \bigcap_{i=1}^m F(P_{T_i})\right)\right)$$

for some $i = 1, \dots, m$. Next we show that $P_{T_i}(x)$ is closed for any $i = 1, \dots, m$ and $x \in D$. In fact, let $\{y_n\} \subset P_{T_i}(x)$ and $\lim_{n \rightarrow \infty} y_n = y$ for some $y \in D$. Then

$$d(x, y_n) = d(x, T_i(x)) \quad \text{and} \quad \lim_{n \rightarrow \infty} d(x, y_n) = d(x, y).$$

It follows that $d(x, y) = d(x, T_i(x))$ and hence $y \in P_{T_i}(x)$. Now applying Theorem 3 to the mappings P_{T_i} , we conclude that the sequence $\{x_n\}$ defined by (7) converges strongly to some point in \mathcal{F} . The proof is completed. □

Remark 4 Theorem 4 improves and extends the corresponding results in Abkar and Es-lamian [8, Theorem 3.12] and Panyanak [19, Theorem 3.4].

Competing interests

The author declares that they have no competing interests.

Acknowledgements

Supported by the General Project of Educational Department in Sichuan (No. 13ZB0182) and the National Natural Science Foundation of China (No. 11426190).

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