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Some generalizations for $(\alpha - \psi, \phi)$ -contractions in b -metric-like spaces and an application

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Abstract

In this paper, we introduce a new class of α_{qsp} -admissible mappings and provide some fixed point theorems involving this class of mappings satisfying some new conditions of contractivity in the setting of b -metric-like spaces. Our results extend, unify, and generalize classical and recent fixed point results for contractive mappings.

MSC: 47H10; 54H25

Keywords: α_{qsp} -admissible mappings; $(\alpha_{qsp} - \psi, \phi)$ contractive mapping; b -metric-like space; fixed point

1 Introduction

In the past years extensions of a metric fixed point theory to generalized structures have received much attention. Also in these structures the concepts of fixed point theorems and contractions have appeared with a remarkable influence on applications in the theory of differential and integral equations, and giving appropriate mathematical models for solving a variety of applied problems in the mathematical sciences and engineering. Some generalizations are b -metric spaces introduced by Bakhtin [1] (and later extensively used by Czerwik [2]), partial metric spaces by Matthews [3], b -partial metric spaces by Shukla [4], metric-like spaces by Harandi [5], and b -metric-like spaces by Alghmandi et al. [6]. Later, Hussain [7] discussed the topological structure of b -metric-like spaces.

Also these generalizations have been associated with new and generalized classes of contractive mappings. In this direction, Samet et al. [8] introduced the concept of α -admissible, α -contractive, and $\alpha - \psi$ -contractive mappings, further extended to the (α, β) -contractive mappings. Many papers dealing with these notions have been considered to prove fixed point results (for example, see [8–23]).

In this paper, working in this direction, we introduce the concept of an α_{qsp} -admissible mapping and provide some fixed point results involving $\alpha_{qsp} - \lambda$ contractions and generalized $(\alpha_{qsp} - \psi, \phi)$ contractive mappings in the larger framework of b -spaces, precisely, in the setting of b -metric-like spaces. The presented theorems improve, extend, generalize, and unify a number of existing results in the literature.

2 Preliminaries

Definition 2.1 ([2]) Let X be a nonempty set. A mapping $d : X \times X \rightarrow [0, \infty)$ is called a b -metric if the following conditions hold for all $x, y, z \in X$ and for some $s \geq 1$:

$$d(x, y) = 0 \quad \text{if and only if} \quad x = y;$$

$$d(x, y) = d(y, x);$$

$$d(x, y) \leq s[d(x, z) + d(z, y)].$$

The pair (X, d) is called a b -metric space with parameter s .

Definition 2.2 ([3]) Let X be a nonempty set. A mapping $p : X \times X \rightarrow [0, \infty)$ is called a partial metric if the following conditions hold for all $x, y, z \in X$ and $s \geq 1$: $x = y \Leftrightarrow p(x, x) = p(x, y) = p(y, y)$;

$$p(x, x) \leq p(x, y);$$

$$p(x, y) = p(y, x);$$

$$p(x, y) \leq p(x, z) + p(z, y) - p(z, z).$$

The pair (X, p) is called a partial metric space.

Definition 2.3 ([4]) Let X be a nonempty set. A mapping $p_b : X \times X \rightarrow [0, \infty)$ is called a partial b -metric if, for any real number $s \geq 1$ and for all $x, y, z \in X$:

$$x = y \quad \Leftrightarrow \quad p_b(x, x) = p_b(x, y) = p_b(y, y);$$

$$p_b(x, x) \leq p_b(x, y);$$

$$p_b(x, y) = p_b(y, x);$$

$$p_b(x, y) \leq s[p_b(x, z) + p_b(z, y)] - p_b(z, z).$$

The pair (X, p_b) is called a partial b -metric space.

Definition 2.4 ([5]) Let X be a nonempty set. A mapping $\sigma : X \times X \rightarrow [0, \infty)$ is called metric-like if the following conditions hold for all $x, y, z \in X$:

$$\sigma(x, y) = 0 \quad \text{implies} \quad x = y;$$

$$\sigma(x, y) = \sigma(y, x);$$

$$\sigma(x, y) \leq \sigma(x, z) + \sigma(z, y).$$

The pair (X, σ) is called a metric-like space.

Definition 2.5 ([6]) Let X be a nonempty set. A mapping $\sigma_b : X \times X \rightarrow [0, \infty)$ is called b -metric-like if the following conditions hold for all $x, y, z \in X$ and for some $s \geq 1$:

$$\begin{aligned} \sigma_b(x, y) = 0 & \text{ implies } x = y; \\ \sigma_b(x, y) &= \sigma_b(y, x); \\ \sigma_b(x, y) &\leq s[\sigma_b(x, z) + \sigma_b(z, y)]. \end{aligned}$$

The pair (X, σ_b) is called a b -metric-like space.

In a b -metric-like space (X, σ_b) , if $x, y \in X$ and $\sigma_b(x, y) = 0$, then $x = y$, but the converse need not be true, and $\sigma_b(x, x)$ may be positive for $x \in X$.

Remark 2.6 The class of b -metric-like spaces is larger than either metric-like spaces or b -metric-spaces, since a b -metric-like space is a metric-like space when $s = 1$ and since every b -metric space is a b -metric-like space with the same parameter s . However, the converse implications do not hold.

Example 2.7 ([6]) Let $X = \mathbb{R}^+ \cup \{0\}$. Define the function $\sigma_b : X^2 \rightarrow [0, \infty)$ by $\sigma_b(x, y) = (x + y)^2$ for all $x, y \in X$. Then (X, σ_b) is a b -metric-like space with parameter $s = 2$.

Example 2.8 ([24]) Let $X = \mathbb{R}^+ \cup \{0\}$. Define the function $\sigma_b : X^2 \rightarrow [0, \infty)$ by $\sigma_b(x, y) = (\max\{x, y\})^2$ for all $x, y \in X$. Then (X, σ_b) is a b -metric-like space with parameter $s = 2$. Clearly, (X, σ_b) is not a b -metric or metric-like space.

Definition 2.9 ([6]) Let (X, σ_b) be a b -metric-like space with parameter s , let $\{x_n\}$ be any sequence in X , and let $x \in X$. Then

- (a) The sequence $\{x_n\}$ is said to converge to x if $\lim_{n \rightarrow \infty} \sigma_b(x_n, x) = \sigma_b(x, x)$;
- (b) The sequence $\{x_n\}$ is said to be a Cauchy sequence in (X, σ_b) if $\lim_{n, m \rightarrow \infty} \sigma_b(x_n, x_m)$ exists and is finite;
- (c) (X, σ_b) is said to be a complete b -metric-like space if, for every Cauchy sequence $\{x_n\}$ in X , there exists $x \in X$ such that $\lim_{n, m \rightarrow \infty} \sigma_b(x_n, x_m) = \lim_{n \rightarrow \infty} \sigma_b(x_n, x) = \sigma_b(x, x)$.

The limit of a sequence in a b -metric-like space need not be unique.

Proposition 2.10 ([6]) Let (X, σ_b) be a b -metric-like space with parameter s , and let $\{x_n\}$ be any sequence in X with $x \in X$ such that $\lim_{n \rightarrow \infty} \sigma_b(x_n, x) = 0$. Then

- (a) x is unique,
- (b) $\sigma_b(x, y)/s \leq \lim_{n \rightarrow \infty} \sigma_b(x_n, y) \leq s\sigma_b(x, y)$ for all $y \in X$.

In 2012, Samet et al. [8] introduced the class of α -admissible mappings.

Definition 2.11 Let X be a nonempty set, $f : X \rightarrow X$, and $\alpha : X \times X \rightarrow \mathbb{R}^+$. We say that f is an α -admissible mapping if $\alpha(x, y) \geq 1$ implies that $\alpha(fx, fy) \geq 1$ for all $x, y \in X$.

Since, in general, a b -metric-like space is not continuous, we quote the following lemmas about the convergence of sequences.

Lemma 2.12 ([7]) *Let (X, σ_b) be a b -metric-like space with parameter $s \geq 1$, and suppose that $\{x_n\}$ and $\{y_n\}$ are σ_b -convergent to x and y , respectively. Then we have*

$$\begin{aligned} \frac{1}{s^2} \sigma_b(x, y) - \frac{1}{s} \sigma_b(x, x) - \sigma_b(y, y) &\leq \liminf_{n \rightarrow \infty} \sigma_b(x_n, y_n) \\ &\leq \limsup_{n \rightarrow \infty} \sigma_b(x_n, y_n) \leq s \sigma_b(x, x) + s^2 \sigma_b(y, y) + s^2 \sigma_b(x, y). \end{aligned}$$

In particular, if $\sigma_b(x, y) = 0$, then we have $\lim_{n \rightarrow \infty} \sigma_b(x_n, y_n) = 0$.

Moreover, for each $z \in X$, we have

$$\begin{aligned} \frac{1}{s} \sigma_b(x, z) - \sigma_b(x, x) &\leq \liminf_{n \rightarrow \infty} \sigma_b(x_n, z) \\ &\leq \limsup_{n \rightarrow \infty} \sigma_b(x_n, z) \leq s \sigma_b(x, z) + s \sigma_b(x, x). \end{aligned}$$

In particular, if $\sigma_b(x, x) = 0$, then

$$\begin{aligned} \frac{1}{s} \sigma_b(x, z) &\leq \liminf_{n \rightarrow \infty} \sigma_b(x_n, z) \\ &\leq \limsup_{n \rightarrow \infty} \sigma_b(x_n, z) \leq s \sigma_b(x, z). \end{aligned}$$

The following result is useful.

Lemma 2.13 *Let (X, σ_b) be a b -metric-like space with parameter $s \geq 1$. Then*

- (a) *If $\sigma_b(x, y) = 0$, then $\sigma_b(x, x) = \sigma_b(y, y) = 0$;*
- (b) *If $\{x_n\}$ is a sequence such that $\lim_{n \rightarrow \infty} \sigma_b(x_n, x_{n+1}) = 0$, then we have*

$$\lim_{n \rightarrow \infty} \sigma_b(x_n, x_n) = \lim_{n \rightarrow \infty} \sigma_b(x_{n+1}, x_{n+1}) = 0;$$

- (c) *If $x \neq y$, then $\sigma_b(x, y) > 0$.*

Proof The proof is obvious. □

Lemma 2.14 *Let (X, σ_b) be a complete b -metric-like space with parameter $s \geq 1$, and let $\{x_n\}$ be a sequence such that*

$$\lim_{n \rightarrow \infty} \sigma_b(x_n, x_{n+1}) = 0. \tag{2.1}$$

If $\{x_n\}$ is not Cauchy, then there exist $\varepsilon > 0$ and two subsequences $\{x_{m_k}\}$ and $\{x_{n_k}\}$ of $\{x_n\}$ with $n_k > m_k > k$ (positive integers) such that $\sigma_b(x_{m_k}, x_{n_k}) \geq \varepsilon$, $\sigma_b(x_{m_k}, x_{n_k-1}) < \varepsilon$, $\varepsilon/s^2 \leq \limsup_{k \rightarrow \infty} \sigma_b(x_{m_k-1}, x_{n_k-1}) \leq \varepsilon s$, $\varepsilon/s \leq \limsup_{k \rightarrow \infty} \sigma_b(x_{n_k-1}, x_{m_k}) \leq \varepsilon s^2$, and $\varepsilon/s \leq \limsup_{k \rightarrow \infty} \sigma_b(x_{m_k-1}, x_{n_k}) \leq \varepsilon s^2$.

Proof If $\{x_n\}$ is not a σ_b -Cauchy sequence, then there exists $\varepsilon > 0$ for which we can find two subsequences $\{x_{m_k}\}$ and $\{x_{n_k}\}$ of $\{x_n\}$ such that n_k is the smallest index for which

$$n_k > m_k > k, \quad \sigma_b(x_{m_k}, x_{n_k}) \geq \varepsilon. \tag{2.2}$$

This means that

$$\sigma_b(x_{m_k}, x_{n_{k-1}}) < \varepsilon. \tag{2.3}$$

From (2.2) and property (c) of Definition 2.4 we have

$$\begin{aligned} \varepsilon &\leq \sigma_b(x_{m_k}, x_{n_k}) \leq s\sigma_b(x_{m_k}, x_{m_{k-1}}) + s\sigma_b(x_{m_{k-1}}, x_{n_k}) \\ &\leq s\sigma_b(x_{m_k}, x_{m_{k-1}}) + s^2\sigma_b(x_{m_{k-1}}, x_{n_{k-1}}) + s^2\sigma_b(x_{n_{k-1}}, x_{n_k}). \end{aligned} \tag{2.4}$$

Taking the upper limit as $k \rightarrow \infty$ in (2.4) and using (2.1), (2.2), and (2.3), we get

$$\frac{\varepsilon}{s^2} \leq \limsup_{k \rightarrow \infty} \sigma_b(x_{m_{k-1}}, x_{n_{k-1}}). \tag{2.5}$$

By the triangle inequality we have

$$\sigma_b(x_{m_{k-1}}, x_{n_{k-1}}) \leq s\sigma_b(x_{m_{k-1}}, x_{m_k}) + s\sigma_b(x_{m_k}, x_{n_{k-1}}),$$

so, taking the upper limit as $k \rightarrow \infty$ and using (2.1), we get

$$\limsup_{k \rightarrow \infty} \sigma_b(x_{m_{k-1}}, x_{n_{k-1}}) \leq \varepsilon s. \tag{2.6}$$

By (2.5) and (2.6) we have

$$\frac{\varepsilon}{s^2} \leq \limsup_{k \rightarrow \infty} \sigma_b(x_{m_{k-1}}, x_{n_{k-1}}) \leq \varepsilon s. \tag{2.7}$$

Also, we have

$$\varepsilon \leq \sigma_b(x_{m_k}, x_{n_k}) \leq s\sigma_b(x_{m_k}, x_{m_{k-1}}) + s\sigma_b(x_{m_{k-1}}, x_{n_k}),$$

and, taking the upper limit as $k \rightarrow \infty$, we get

$$\frac{\varepsilon}{s} \leq \limsup_{k \rightarrow \infty} \sigma_b(x_{m_{k-1}}, x_{n_k}). \tag{2.8}$$

Again

$$\varepsilon \leq \sigma_b(x_{m_k}, x_{n_k}) \leq s\sigma_b(x_{m_k}, x_{n_{k-1}}) + s\sigma_b(x_{n_{k-1}}, x_{n_k}).$$

Taking the upper limit as $k \rightarrow \infty$ and using (2.1), we get

$$\frac{\varepsilon}{s} \leq \limsup_{k \rightarrow \infty} \sigma_b(x_{n_{k-1}}, x_{m_k}). \tag{2.9}$$

Since $\sigma_b(x_{n_{k-1}}, x_{m_k}) \leq s\sigma_b(x_{n_{k-1}}, x_{m_{k-1}}) + s\sigma_b(x_{m_{k-1}}, x_{m_k})$, from (2.1) and (2.7) we have

$$\limsup_{k \rightarrow \infty} \sigma_b(x_{n_{k-1}}, x_{m_k}) \leq s \limsup_{k \rightarrow \infty} \sigma_b(x_{n_{k-1}}, x_{m_{k-1}}) \leq \varepsilon s^2. \tag{2.10}$$

Consequently,

$$\frac{\varepsilon}{s} \leq \limsup_{k \rightarrow \infty} \sigma_b(x_{n_k-1}, x_{m_k}) \leq \varepsilon s^2. \tag{2.11}$$

Also,

$$\sigma_b(x_{m_k-1}, x_{n_k}) \leq s\sigma_b(x_{m_k-1}, x_{n_k-1}) + s\sigma_b(x_{n_k-1}, x_{n_k}).$$

Then from (2.7), (2.8), and (2.1) we have

$$\limsup_{k \rightarrow \infty} \sigma_b(x_{m_k-1}, x_{n_k}) \leq s \limsup_{k \rightarrow \infty} \sigma_b(x_{m_k-1}, x_{n_k-1}) \leq \varepsilon s^2.$$

Consequently,

$$\frac{\varepsilon}{s} \leq \limsup_{k \rightarrow \infty} \sigma_b(x_{m_k-1}, x_{n_k}) \leq \varepsilon s^2. \tag{2.12}$$

This completes proof. □

3 Main results

We begin this section with the following definition.

Definition 3.1 Let (X, σ_b) be a b -metric-like space with parameter $s \geq 1$, let $\alpha : X \times X \rightarrow [0, \infty)$ be a function, and let $q \geq 1$ and $p \geq 2$ be arbitrary constants. A mapping $f : X \rightarrow X$ is α_{qs^p} -admissible if $\alpha(x, y) \geq qs^p$ implies $\alpha(fx, fy) \geq qs^p$ for all $x, y \in X$.

Remark 3.2

- (i) Taking $q = 1$ in this definition, we obtain an α_{s^p} -admissible mapping defined in a b -metric-like space or in a b -metric space.
- (ii) Note that, for $s = 1$, the definition reduces to an α_q -admissible mapping defined in a metric space or in a metric-like space.
- (iii) For $s = 1$ and $q = 1$, the definition reduces to the definition of an α -admissible mapping in a metric space [8].
- (iv) The class of α_{qs^p} -admissible mappings is strictly larger, and, more generally, because the constant $p \geq 2$, it is not restricted to some certain values.

We further consider the following properties.

Let (X, σ_b) be a complete b -metric-like space with parameter $s \geq 1$, and let $\alpha : X \times X \rightarrow [0, \infty)$ be a function. Then:

- (H_{qs^p}) If $\{x_n\}$ is a sequence in X such that $x_n \rightarrow x \in X$ as $n \rightarrow \infty$ and $\alpha(x_n, x_{n+1}) \geq qs^p$, then there exists a subsequence $\{x_{n_k}\}$ of $\{x_n\}$ such that $\alpha(x_{n_k}, x) \geq qs^p$ for all $k \in N$.
- (U_{qs^p}) For all $x, y \in \text{Fix}(f)$, we have $\alpha(x, y) \geq qs^p$, where $\text{Fix}(f)$ denotes the set of fixed points of f .

Example 3.3 Let $X = (0, +\infty)$. Define $f : X \rightarrow X$ and $\alpha : X \times X \rightarrow [0, +\infty)$ by $fx = \ln x$ for all $x \in X$, and let

$$\alpha(x, y) = \begin{cases} 2s^2, & x \neq y, \\ 0, & x = y \end{cases} \text{ for any } s \geq 1.$$

Then, f is α_{qs^p} -admissible.

Example 3.4 Let $X = (0, +\infty)$. Define $f : X \rightarrow X$ and $\alpha : X \times X \rightarrow [0, \infty)$ by $fx = 3x$ for all $x \in X$ and

$$\alpha(x, y) = \begin{cases} 2, & x \neq y, \\ 0, & x = y \end{cases} \text{ for all } x, y \in X.$$

Then f is α_{qs^p} -admissible.

Based on the definition of quasi-contraction from Ćirić, we introduce the following definition in the setting of a b -metric-like space.

Definition 3.5 Let (X, σ_b) be a complete b -metric-like space with parameter $s \geq 1$, and let $f : X \rightarrow X$ be a given mapping. We say that f is a generalized $\alpha_{qs^p} - \lambda$ -quasi-contraction if f is an α_{qs^p} -admissible mapping such that

$$\alpha(x, y)\sigma_b(fx, fy) \leq \lambda \max \left\{ \begin{array}{l} \sigma_b(x, y), \sigma_b(x, fx), \sigma_b(y, fy), \sigma_b(x, fy), \\ \sigma_b(y, fx), \sigma_b(x, x), \sigma_b(y, y) \end{array} \right\} \tag{3.1}$$

for all $x, y \in X$ and $\lambda \in [0, 1/2)$.

Remark 3.6 If we take $\alpha(x, y) = s^2$ ($p = 2$ and $q = 1$), then the definition reduces to the definition of an $s - \lambda$ quasi-contraction, and if we take $s = 1$, then the definition reduces to the λ -quasi-contraction in the setting of metric spaces.

Theorem 3.7 Let (X, σ_b) be a complete b -metric-like space with parameter $s \geq 1$, let $f : X \rightarrow X$ be a self-mapping, and let $\alpha : X \times X \rightarrow \mathbb{R}^+$ be a given function. Suppose that the following conditions are satisfied:

- (i) f is an α_{qs^p} -admissible mapping;
- (ii) f is an $\alpha_{qs^p} - \lambda$ contractive mapping;
- (iii) there exists $x_0 \in X$ such that $\alpha(x_0, fx_0) \geq qs^p$;
- (iv) either f is continuous, or property H_{qs^p} is satisfied.

Then f has a fixed point. Moreover, f has a unique fixed point if property U_{qs^p} is satisfied.

Proof By hypothesis (iii) there exists $x_0 \in X$ such that $\alpha(x_0, fx_0) \geq qs^p$. We define the sequence $\{x_n\}$ in X by $x_n = fx_{n-1}$ for all $n \in \mathbb{N}$. If $x_n = x_{n+1}$ for some $n \in \mathbb{N}$, then $u = x_n$ is a fixed point for f . Consequently, we suppose that $x_n \neq x_{n+1}$ ($\sigma_b(x_n, x_{n+1}) > 0$) for all $n \in \mathbb{N}$.

Since f is an α_{qs^p} -admissible mapping, we have

$$\begin{aligned} \alpha(x_0, x_1) &= \alpha(x_0, fx_0) \geq qs^p, & \alpha(fx_0, fx_1) &= \alpha(x_1, x_2) \geq qs, & \text{and} \\ \alpha(fx_1, fx_2) &= \alpha(x_2, x_3) \geq qs^p. \end{aligned}$$

Hence, by induction we get

$$\alpha(x_n, x_{n+1}) \geq qs^p \quad \text{for all } n \in N.$$

By condition (3.1) we have:

$$\begin{aligned} &qs^p \sigma_b(x_n, x_{n+1}) \\ &= qs^p \sigma_b(fx_{n-1}, fx_n) \leq \alpha(x_{n-1}, x_n) \sigma_b(fx_{n-1}, fx_n) \\ &\leq \lambda \max \left\{ \begin{array}{l} \sigma_b(x_{n-1}, x_n), \sigma_b(x_{n-1}, fx_{n-1}), \sigma_b(x_n, fx_n), \sigma_b(x_{n-1}, fx_n), \\ \sigma_b(x_n, fx_{n-1}), \sigma_b(x_{n-1}, x_{n-1}), \sigma_b(x_n, x_n) \end{array} \right\} \\ &= \lambda \max \left\{ \begin{array}{l} \sigma_b(x_{n-1}, x_n), \sigma_b(x_{n-1}, x_n), \sigma_b(x_n, x_{n+1}), \sigma_b(x_{n-1}, x_{n+1}), \\ \sigma_b(x_n, x_n), \sigma_b(x_{n-1}, x_{n-1}), \sigma_b(x_n, x_n) \end{array} \right\} \\ &\leq \lambda \max \left\{ \begin{array}{l} \sigma_b(x_{n-1}, x_n), \sigma_b(x_{n-1}, x_n), \sigma_b(x_n, x_{n+1}), s[\sigma_b(x_{n-1}, x_n) + \sigma_b(x_n, x_{n+1})], \\ 2s\sigma_b(x_n, x_{n-1}), 2s\sigma_b(x_{n-1}, x_n), 2s\sigma_b(x_n, x_{n-1}) \end{array} \right\} \\ &= \lambda \max \left\{ \begin{array}{l} \sigma_b(x_{n-1}, x_n), \sigma_b(x_{n-1}, x_n), \sigma_b(x_n, x_{n+1}), s[\sigma_b(x_{n-1}, x_n) + \sigma_b(x_n, x_{n+1})], \\ 2s\sigma_b(x_n, x_{n-1}) \end{array} \right\}. \end{aligned} \tag{3.2}$$

If $\sigma_b(x_{n-1}, x_n) < \sigma_b(x_n, x_{n+1})$ for some $n \in N$, then from inequality (3.2) we have $\sigma_b(x_n, x_{n+1}) \leq 2\lambda/qs^{p-1} \sigma_b(x_n, x_{n+1})$, a contradiction since $2\lambda/qs^{p-1} < 1$.

Hence, for all $n \in N$, $\sigma_b(x_n, x_{n+1}) \leq \sigma_b(x_{n-1}, x_n)$, and also by inequality (3.2) we get

$$\sigma_b(x_n, x_{n+1}) \leq \frac{2\lambda}{qs^{p-1}} \sigma_b(x_{n-1}, x_n). \tag{3.3}$$

Similarly, by the contractive condition of theorem we have:

$$\sigma_b(x_{n-1}, x_n) \leq \frac{2\lambda}{qs^{p-1}} \sigma_b(x_{n-2}, x_{n-1}). \tag{3.4}$$

Generally, from (3.3) and (3.4) we have, for all n ,

$$\sigma_b(x_n, x_{n+1}) \leq c \sigma_b(x_{n-1}, x_n) \leq \dots \leq c^n \sigma_b(x_0, x_1), \tag{3.5}$$

where $0 \leq c = 2\lambda/qs^{p-1} < 1$. Taking limit as $n \rightarrow \infty$ in (3.5), we have

$$\sigma_b(x_n, x_{n+1}) \rightarrow 0. \tag{3.6}$$

Now we prove that $\{x_n\}$ is a Cauchy sequence. To do this, let $m, n > 0$ be such that $m > n$.

Using Definition 2.4(c), we have

$$\begin{aligned} \sigma_b(x_n, x_m) &\leq s[\sigma_b(x_n, x_{n+1}) + \sigma_b(x_{n+1}, x_m)] \\ &\leq s\sigma_b(x_n, x_{n+1}) + s^2\sigma_b(x_{n+1}, x_{n+2}) + s^3\sigma_b(x_{n+2}, x_{n+3}) + \dots \\ &\leq sc^n\sigma_b(x_0, x_1) + s^2c^{n+1}\sigma_b(x_0, x_1) + s^3c^{n+2}\sigma_b(x_0, x_1) + \dots \\ &= sc^n\sigma_b(x_0, x_1)[1 + sc + (sc)^2 + (sc)^3 + \dots] \\ &\leq \frac{sc^n}{1 - sc}\sigma_b(x_0, x_1). \end{aligned}$$

Taking the limit as $n, m \rightarrow \infty$, we have $\sigma_b(x_n, x_m) \rightarrow 0$, since $0 \leq cs = 2\lambda s/q s^{p-1} = 2\lambda/q s^{p-2} < 1$. Therefore $\{x_n\}$ is a Cauchy sequence in the complete b -metric-like space (X, σ_b) . Thus there is some $u \in X$ such that $\{x_n\}$ converges to u .

If f is a continuous mapping, then we get:

$$f(u) = f\left(\lim_{n \rightarrow \infty} x_n\right) = \lim_{n \rightarrow \infty} f(x_n) = \lim_{n \rightarrow \infty} (x_{n+1}) = u.$$

Thus u is a fixed point of f .

On the other hand, if f is not a continuous function and property H_{qs^p} holds, then there exists a subsequence $\{x_{n_k}\}$ of $\{x_n\}$ such that $\alpha(x_{n_k}, u) \geq qs^p$ for all $k \in N$.

Since $\alpha(x_{n_k}, u) \geq qs^p$, applying condition (3.1) with $x = x_{n_k}$ and $y = u$, we obtain

$$\begin{aligned} qs^p\sigma_b(x_{n_k+1}, fu) &= qs^p\sigma_b(fx_{n_k}, fu) \leq \alpha(x_{n_k}, u)\sigma_b(fx_{n_k}, fu) \\ &\leq \lambda \max \left\{ \begin{array}{l} \sigma_b(x_{n_k}, u), \sigma_b(x_{n_k}, fx_{n_k}), \sigma_b(u, fu), \sigma_b(x_{n_k}, fu), \\ \sigma_b(u, fx_{n_k}), \sigma_b(x_{n_k}, x_{n_k}), \sigma_b(u, u) \end{array} \right\} \\ &= \lambda \max \left\{ \begin{array}{l} \sigma_b(x_{n_k}, u), \sigma_b(x_{n_k}, x_{n_k+1}), \sigma_b(u, fu), \\ \sigma_b(x_{n_k}, fu), \sigma_b(u, x_{n_k+1}), \sigma_b(x_{n_k}, x_{n_k}), \sigma_b(u, u) \end{array} \right\}. \end{aligned} \tag{3.7}$$

Taking the upper limit as $k \rightarrow \infty$ in (3.7) and using (3.6), and Lemmas 2.12 and 2.13, we have

$$qs^{p-1}\sigma_b(u, fu) = qs^p \frac{1}{s}\sigma_b(u, fu) \leq 2\lambda s\sigma_b(u, fu). \tag{3.8}$$

From (3.8) we get $\sigma_b(u, fu) = 0$, which implies that $fu = u$. Hence u is a fixed point of f .

Further, suppose that u and v are two fixed points of f , where $fu = u$ and $fv = v$ for some $u \neq v$. Since property U_{qs^p} is satisfied, we have $\alpha(u, v) \geq qs^p$. Hence, from (3.1) we have

$$\begin{aligned} qs^p\sigma_b(u, v) &= qs^p\sigma_b(fu, fv) \leq \alpha(u, v)\sigma_b(fu, fv) \\ &\leq \lambda \max \left\{ \begin{array}{l} \sigma_b(u, v), \sigma_b(u, fu), \sigma_b(v, fv), \sigma_b(u, fv), \\ \sigma_b(v, fu), \sigma_b(u, u), \sigma_b(v, v) \end{array} \right\} \\ &= \lambda \max \left\{ \begin{array}{l} \sigma_b(u, v), \sigma_b(u, u), \sigma_b(v, v), \sigma_b(u, v), \\ \sigma_b(v, u), \sigma_b(u, u), \sigma_b(v, v) \end{array} \right\} \\ &\leq 2\lambda s\sigma_b(u, v). \end{aligned} \tag{3.9}$$

So $\sigma_b(u, v) = 0$, and since $0 \leq c = 2\lambda/qs^{p-1} < 1$, we get $\sigma_b(u, v) = 0$. Hence the fixed point is unique. □

The following theorem is a version of the Hardy-Rogers result.

Theorem 3.8 *Let (X, σ_b) be a complete b -metric-like space with parameter $s \geq 1$, and let $f : X \rightarrow X$ be a given self-mapping. Suppose that there exists a function $\alpha : X \times X \rightarrow [0, \infty)$ such that*

$$\alpha(x, y)\sigma_b(fx, fy) \leq \alpha_1\sigma_b(x, y) + \alpha_2\sigma_b(x, fx) + \alpha_3\sigma_b(y, fy) + \alpha_4\sigma_b(x, fy) + \alpha_5\sigma_b(y, fx),$$

for all $x, y \in X$ and the constants $a_i \geq 0, i = 1, \dots, 5$, where $a_1 + a_2 + a_3 + a_4 + a_5 < 1/2$. Assume also that:

- (i) f is an α_{qs^p} -admissible mapping;
- (ii) there exists $x_0 \in X$ such that $\alpha(x_0, fx_0) \geq qs^p$;
- (iii) either f is continuous, or property H_{qs^p} is satisfied.

Then f has a fixed point. Moreover, f has a unique fixed point if property U_{qs^p} is satisfied.

Proof This theorem can be considered as a corollary of Theorem 3.7, since, for all $x, y \in X$, we have

$$\begin{aligned} &\alpha_1\sigma_b(x, y) + \alpha_2\sigma_b(x, fx) + \alpha_3\sigma_b(y, fy) + \alpha_4\sigma_b(x, fy) + \alpha_5\sigma_b(y, fx) \\ &\leq (\alpha_1 + \alpha_2 + \alpha_3 + \alpha_4 + \alpha_5) \max\{\sigma_b(x, y), \sigma_b(x, fx), \sigma_b(y, fy), \sigma_b(x, fy), \sigma_b(y, fx)\} \\ &= k \max\{\sigma_b(x, y), \sigma_b(x, fx), \sigma_b(y, fy), \sigma_b(x, fy), \sigma_b(y, fx)\}, \end{aligned}$$

where $0 < k = a_1 + a_2 + a_3 + a_4 + a_5 < 1/2$. □

Corollary 3.9 *Let (X, σ_b) be complete b -metric-like space with parameter $s \geq 1$. If $f : X \rightarrow X$ is a self-mapping and there exist constants $a_i \geq 0, i = 1, \dots, 5$, with $a_1 + a_2 + a_3 + a_4 + a_5 < 1/2$ such that*

$$qs^p\sigma_b(fx, fy) \leq \alpha_1\sigma_b(x, y) + \alpha_2\sigma_b(x, fx) + \alpha_3\sigma_b(y, fy) + \alpha_4\sigma_b(x, fy) + \alpha_5\sigma_b(y, fx),$$

for all $x, y \in X$ and a constant $p \geq 2$, then f has a unique fixed point in X .

Proof In Theorem 3.8, take the function $\alpha(x, y) = qs^p$. □

Remark 3.10 Theorem 3.7 generalizes Theorem 18 in [7]. For $\alpha(x, y) = s^2$ and for all $x, y \in X$, Theorems 3.7 and 3.8 reduce to Theorems 3.2 and 3.13 of [19]. In Theorem 3.7 and Corollary 3.9, by choosing the constants a_i in certain manner, we obtain, as particular cases, certain classes of α_{qs^p} -types of Kannan, Chatterjea, Reich, and Zamfirescu contractions.

The notion of $\alpha - \psi$ contractive mappings is defined in a complete metric space in [8]. Thereafter, many authors provided various fixed point theorems for such a class of mappings. In the following definition, we extend and generalize the notions of $\alpha - \psi$ and $(\psi - \phi)$ -contractive mappings in the context of larger spaces, such as b -metric-like spaces.

The aim of this section is to extend and generalize the main classical result and other existing results in the literature on b -metric and metric-like spaces.

Let (X, σ_b) be a b -metric-like space with parameter $s \geq 1$. For a self-mapping $f : X \rightarrow X$, we define $N(x, y)$ by

$$N(x, y) = \max \left\{ \sigma_b(x, y), \sigma_b(x, fx), \sigma_b(y, fy), \frac{\sigma_b(x, fy) + \sigma_b(y, fx)}{4s} \right\} \tag{3.10}$$

for all $x, y \in X$.

The families Ψ, Φ with altering distance functions are defined as follows:

- $\psi : [0, \infty) \rightarrow [0, \infty)$ an increasing and continuous function;
- $\phi : [0, \infty) \rightarrow [0, \infty)$ is continuous, and $\phi(t) < \psi(t)$ for all $t > 0$.

Let \mathbb{S} be the set of all mappings $\beta : [0, \infty) \rightarrow [0, 1)$ satisfying the condition

$$\beta(t_n) \rightarrow 1 \text{ as } n \rightarrow \infty \text{ implies that } t_n \rightarrow 0 \text{ as } n \rightarrow \infty.$$

Definition 3.11 Let (X, σ_b) be a b -metric-like space with parameter $s \geq 1$, and let $f : X \rightarrow X$ be a self-mapping. Also, let $\alpha : X \times X \rightarrow [0, \infty)$ and $q \geq 1, p \geq 2$. We say that f is an $(\alpha_{qs^p} - \psi, \phi)$ generalized contractive mapping if there exist $\psi \in \Psi, \phi \in \Phi$ such that

$$\psi(\alpha(x, y)\sigma_b(fx, fy)) \leq \phi(N(x, y)) \tag{3.11}$$

for all $x, y \in X$ with $\alpha(x, y) \geq qs^p$, where $N(x, y)$ is defined by (3.10).

Remark 3.12

- (i) Taking $q = 1$ in the definition, we obtain $\alpha_s - (\psi, \phi)$ admissible mappings defined in a b -metric-like space or in a b -metric space.
- (ii) Note that, for $\alpha(x, y) = q$, the definition reduces to an α_q -admissible mapping defined in a metric space or in a metric-like space.
- (iii) For $s = 1$ and $q = 1$, the definition reduces to the definition of an α -admissible mapping in a metric space.
- (iv) The definition reduces to a (ψ, ϕ) -contractive mapping if we take $\alpha(x, y) = 1$.
- (v) The definition reduces to an $\alpha_{qs^p} - \phi$ contractive mapping if we take $\psi(t) = t$.
- (vi) The definition reduces to an $\alpha_{qs^p} - \lambda$ contractive mapping if we take $\psi(t) = t$ and $\phi(t) = \lambda t$ for $\lambda \in (0, 1)$.

We now present the following theorem.

Theorem 3.13 Let (X, σ_b) be a complete b -metric-like space with parameter $s \geq 1$, and let $f : X \rightarrow X$ be an $(\alpha_{qs^p} - \psi, \phi)$ generalized contractive mapping. Suppose that the following conditions are satisfied:

- (i) f is an α_{qs^p} -admissible mapping;
- (ii) there exists $x_0 \in X$ such that $\alpha(x_0, fx_0) \geq qs^p$;
- (iii) either f is continuous, or property H_{qs^p} is satisfied.

Then f has a fixed point $x \in X$. Moreover, f has a unique fixed point if property U_{qs^p} is satisfied.

Proof By assumption (ii) there exists a point $x_0 \in X$ such that $\alpha(x_0, fx_0) \geq qs^p$. We construct a sequence $\{x_n\}$ in X by $x_n = f^n x_0 = f(x_{n-1})$ for all $n \in N$. If we suppose that $\sigma_b(x_n, x_{n+1}) = 0$ for some n , then $x_{n+1} = x_n$, and the proof is completed, since $u = x_n = x_{n+1} = f(x_n) = fu$. Consequently, throughout the proof, we assume that

$$\sigma_b(x_n, x_{n+1}) > 0 \quad \text{for all } n \in N. \tag{3.12}$$

Since f is an α_{qs^p} -admissible mapping, we observe that

$$\begin{aligned} \alpha(x_0, x_1) = \alpha(x_0, fx_0) &\geq qs^p, & \alpha(fx_0, fx_1) = \alpha(x_1, x_2) &\geq qs & \text{ and} \\ \alpha(fx_1, fx_2) = \alpha(x_2, x_3) &\geq qs^p. \end{aligned}$$

In general, by induction we derive that

$$\alpha(x_n, x_{n+1}) \geq qs^p \quad \text{for all } n \in N. \tag{3.13}$$

By (3.13) and condition (3.11) we have:

$$\begin{aligned} \psi(\sigma_b(x_n, x_{n+1})) &\leq \psi(qs^p \sigma_b(x_n, x_{n+1})) = \psi(qs^p \sigma_b(fx_{n-1}, fx_n)) \\ &\leq \psi(\alpha(x_{n-1}, x_n) \sigma_b(fx_{n-1}, fx_n)) \\ &\leq \phi(N(x_{n-1}, x_n)) < \psi(N(x_{n-1}, x_n)), \end{aligned} \tag{3.14}$$

where

$$\begin{aligned} N(x_{n-1}, x_n) &= \max \left\{ \sigma_b(x_{n-1}, x_n), \sigma_b(x_{n-1}, fx_{n-1}), \sigma_b(x_n, fx_n), \right. \\ &\quad \left. \frac{\sigma_b(x_{n-1}, fx_n) + \sigma_b(x_n, fx_{n-1})}{4s} \right\} \\ &= \max \left\{ \sigma_b(x_{n-1}, x_n), \sigma_b(x_{n-1}, x_n), \sigma_b(x_n, x_{n+1}), \right. \\ &\quad \left. \frac{\sigma_b(x_{n-1}, x_{n+1}) + \sigma_b(x_n, x_n)}{4s} \right\} \\ &\leq \max \left\{ \sigma_b(x_{n-1}, x_n), \sigma_b(x_{n-1}, x_n), \sigma_b(x_n, x_{n+1}), \right. \\ &\quad \left. \frac{s[\sigma_b(x_{n-1}, x_n) + \sigma_b(x_n, x_{n+1})] + 2s\sigma_b(x_{n-1}, x_n)}{4s} \right\}. \end{aligned} \tag{3.15}$$

If we assume that, for some $n \in N$,

$$\sigma_b(x_{n-1}, x_n) < \sigma_b(x_n, x_{n+1}),$$

then from inequality (3.15) we get

$$N(x_{n-1}, x_n) \leq \sigma_b(x_n, x_{n+1}). \tag{3.16}$$

Again, by (3.13) and condition (3.11) we have:

$$\begin{aligned} \psi(\sigma_b(x_n, x_{n+1})) &\leq \psi(qs^p \sigma_b(x_n, x_{n+1})) = \psi(qs^p \sigma_b(fx_{n-1}, fx_n)) \\ &\leq \psi(\alpha(x_{n-1}, x_n) \sigma_b(fx_{n-1}, fx_n)) \\ &\leq \phi(N(x_{n-1}, x_n)) < \psi(N(x_{n-1}, x_n)). \end{aligned} \tag{3.17}$$

By the property ψ inequality (3.17) implies that

$$\sigma_b(x_n, x_{n+1}) \leq N(x_{n-1}, x_n). \tag{3.18}$$

From (3.16) and (3.18) we have

$$N(x_{n-1}, x_n) = \sigma_b(x_n, x_{n+1}). \tag{3.19}$$

From (3.17), using (3.19), we obtain

$$\begin{aligned} \psi(\sigma_b(x_n, x_{n+1})) &\leq \psi(qs^p \sigma_b(x_n, x_{n+1})) = \psi(qs^p \sigma_b(fx_{n-1}, fx_n)) \\ &\leq \psi(\alpha(x_{n-1}, x_n) \sigma_b(fx_{n-1}, fx_n)) \\ &\leq \phi(N(x_{n-1}, x_n)) = \phi(\sigma_b(x_n, x_{n+1})) \\ &< \psi(\sigma_b(x_n, x_{n+1})), \end{aligned} \tag{3.20}$$

which gives a contradiction, since we have assumed that $\sigma_b(x_n, x_{n+1}) > 0$ and $\phi(t) < \psi(t)$ for all $t > 0$. Hence, for all $n \in N$, $\sigma_b(x_n, x_{n+1}) \leq \sigma_b(x_{n-1}, x_n)$, and the sequence $\{\sigma_b(x_n, x_{n+1})\}$ is decreasing and bounded below. Hence there exists $l \geq 0$ such that $\sigma_b(x_n, x_{n+1}) \rightarrow l$. Also,

$$\lim_{n \rightarrow \infty} \sigma_b(x_n, x_{n+1}) = \lim_{n \rightarrow \infty} N(x_{n-1}, x_n) = l.$$

We shall prove that $l = 0$.

Consider

$$\begin{aligned} \psi(\sigma_b(x_n, x_{n+1})) &\leq \psi(qs^p \sigma_b(x_n, x_{n+1})) = \psi(qs^p \sigma_b(fx_{n-1}, fx_n)) \\ &\leq \psi(\alpha(x_{n-1}, x_n) \sigma_b(fx_{n-1}, fx_n)) \\ &\leq \phi(N(x_{n-1}, x_n)) = \phi(\sigma_b(x_n, x_{n+1})). \end{aligned} \tag{3.21}$$

If we assume that $l > 0$, taking the limit in (3.21), we have

$$\psi(l) \leq \phi(l),$$

which is a contradiction since $\psi(t) > \phi(t)$ for $t > 0$. Hence $l = 0$, and

$$\lim_{n \rightarrow \infty} \sigma_b(x_n, x_{n+1}) = \lim_{n \rightarrow \infty} N(x_{n-1}, x_n) = 0. \tag{3.22}$$

Next, we shall show that $\{x_n\}$ is a Cauchy sequence in X . Suppose, on the contrary, that $\{x_n\}$ is not a Cauchy sequence. Then by Lemma 2.14 there exist $\varepsilon > 0$ and two subsequences

$\{x_{m_k}\}$ and $\{x_{n_k}\}$ of $\{x_n\}$, with $n_k > m_k > k$, such that

$$\begin{aligned} \sigma_b(x_{m_k}, x_{n_k}) &\geq \varepsilon, & \sigma_b(x_{m_k}, x_{n_k-1}) &< \varepsilon, \\ \frac{\varepsilon}{s^2} &\leq \limsup_{k \rightarrow \infty} \sigma_b(x_{m_k-1}, x_{n_k-1}) \leq \varepsilon s, \\ \frac{\varepsilon}{s} &\leq \limsup_{k \rightarrow \infty} \sigma_b(x_{n_k-1}, x_{m_k}) \leq \varepsilon s^2, & \text{and} \\ \frac{\varepsilon}{s} &\leq \limsup_{k \rightarrow \infty} \sigma_b(x_{m_k-1}, x_{n_k}) \leq \varepsilon s^2. \end{aligned} \tag{3.23}$$

From the definition of $N(x, y)$ we have

$$\begin{aligned} N(x_{m_k-1}, x_{n_k-1}) &= \max \left\{ \sigma_b(x_{m_k-1}, x_{n_k-1}), \sigma_b(x_{m_k-1}, fx_{m_k-1}), \sigma_b(x_{n_k-1}, fx_{n_k-1}), \right. \\ &\quad \left. \frac{\sigma_b(x_{m_k-1}, fx_{n_k-1}) + \sigma_b(x_{n_k-1}, fx_{m_k-1})}{4s} \right\} \\ &= \max \left\{ \sigma_b(x_{m_k-1}, x_{n_k-1}), \sigma_b(x_{m_k-1}, x_{m_k}), \sigma_b(x_{n_k-1}, x_{n_k}), \right. \\ &\quad \left. \frac{\sigma_b(x_{m_k-1}, x_{n_k}) + \sigma_b(x_{n_k-1}, x_{m_k})}{4s} \right\}. \end{aligned} \tag{3.24}$$

Taking the upper limit as $k \rightarrow \infty$ in (3.24) and using (3.22), (3.23), we get

$$\begin{aligned} \limsup_{k \rightarrow \infty} N(x_{m_k-1}, x_{n_k-1}) &= \limsup_{k \rightarrow \infty} \max \left\{ \sigma_b(x_{m_k-1}, x_{n_k-1}), \sigma_b(x_{m_k-1}, x_{m_k}), \sigma_b(x_{n_k-1}, x_{n_k}), \right. \\ &\quad \left. \frac{\sigma_b(x_{m_k-1}, x_{n_k}) + \sigma_b(x_{n_k-1}, x_{m_k})}{4s} \right\} \\ &\leq \max \left\{ \varepsilon s, 0, 0, \frac{\varepsilon s}{2} \right\} \leq \varepsilon s. \end{aligned} \tag{3.25}$$

Using the α_{qs^p} -weak contractive condition, we have

$$\begin{aligned} \psi(qs^p \sigma_b(x_{m_k}, x_{n_k})) &\leq \psi(qs^p \sigma_b(fx_{m_k-1}, fx_{n_k-1})) \\ &\leq \psi(\alpha(x_{m_k-1}, x_{n_k-1}) \sigma_b(fx_{m_k-1}, fx_{n_k-1})) \\ &\leq \phi(N(x_{m_k-1}, x_{n_k-1})). \end{aligned} \tag{3.26}$$

Taking the upper limit in (3.26), using (3.23) and (3.25), we obtain

$$\begin{aligned} \psi(\varepsilon s) &\leq \psi(q\varepsilon s^{p-1}) = \psi\left(qs^p \frac{\varepsilon}{s}\right) \leq \psi\left(\limsup_{k \rightarrow \infty} \sigma_b(x_{m_k}, x_{n_k})\right) \\ &\leq \phi\left(\limsup_{k \rightarrow \infty} (N(x_{m_k-1}, x_{n_k-1}))\right) \leq \phi(\varepsilon s) \\ &< \psi(\varepsilon s), \end{aligned}$$

which is a contradiction, since $\varepsilon > 0$. Therefore $\{x_n\}$ is a Cauchy sequence in the complete b -metric-like space (X, σ_b) . Thus, there is some $u \in X$ such that $\{x_n\}$ converges to u . If f is a continuous mapping, we get:

$$f(u) = f\left(\lim_{n \rightarrow \infty} x_n\right) = \lim_{n \rightarrow \infty} f(x_n) = \lim_{n \rightarrow \infty} (x_{n+1}) = u,$$

and u is a fixed point of f .

If the self-map f is not continuous, then from (3.13) and condition H_{qs^p} , there exists a subsequence $\{x_{n_k}\}$ of $\{x_n\}$ such that $\alpha(x_{n_k}, u) \geq qs^p$ for all $k \in N$. Since $\alpha(x_{n_k}, u) \geq qs^p$, applying contractive condition (3.11), with $x = x_{n_k}$ and $y = u$, we obtain

$$\begin{aligned} \psi(qs^p \sigma_b(x_{n_k+1}, fu)) &= \psi(qs^p \sigma_b(fx_{n_k}, fu)) \\ &\leq \psi(\alpha(x_{n_k}, u) \sigma_b(fx_{n_k}, fu)) \\ &\leq \phi(N(x_{n_k}, u)), \end{aligned} \tag{3.27}$$

where

$$\begin{aligned} N(x_{n_k}, u) &= \max \left\{ \sigma_b(x_{n_k}, u), \sigma_b(x_{n_k}, fx_{n_k}), \sigma_b(u, fu), \right. \\ &\quad \left. \frac{\sigma_b(x_{n_k}, fu) + \sigma_b(u, fx_{n_k})}{4s} \right\} \\ &= \max \left\{ \sigma_b(x_{n_k}, u), \sigma_b(x_{n_k}, x_{n_k+1}), \sigma_b(u, fu), \right. \\ &\quad \left. \frac{\sigma_b(x_{n_k}, fu) + \sigma_b(u, x_{n_k+1})}{4s} \right\}. \end{aligned} \tag{3.28}$$

Taking the upper limit in (3.28) and using Lemma 2.13 and result (3.22), we obtain

$$\limsup_{n \rightarrow \infty} N(x_{n_k}, u) \leq \max \left\{ 0, 0, \sigma_b(u, fu), \frac{s\sigma_b(u, fu)}{4s} \right\} = \sigma_b(u, fu). \tag{3.29}$$

Taking the upper limit as $k \rightarrow \infty$ in (3.27) and using (3.29) and Lemma 2.13, we obtain

$$\begin{aligned} \psi(qs^{p-1} \sigma_b(u, fu)) &= \psi \left(qs^p \frac{1}{s} \sigma_b(u, fu) \right) \leq \psi \left(qs^p \limsup_{k \rightarrow \infty} \sigma_b(x_{n_k}, fu) \right) \\ &\leq \phi \left(\limsup_{k \rightarrow \infty} N(x_{n_k}, u) \right) < \psi \left(\limsup_{k \rightarrow \infty} N(x_{n_k}, u) \right) \\ &\leq \psi(\sigma_b(u, fu)). \end{aligned} \tag{3.30}$$

From (3.30) we get $\sigma_b(u, fu) = 0$, which implies that $fu = u$. Hence u is a fixed point of f .

Suppose that u and v are two fixed points of f , where $fu = u$ and $fv = v$ are such that $u \neq v$. Then, by hypothesis U_{qs^p} , $\alpha(u, v) \geq qs^p$, and applying (3.11), we have

$$\begin{aligned} \psi(qs^p \sigma_b(u, u)) &= \psi(qs^p \sigma_b(fu, fu)) \leq \psi(\alpha(u, u) \sigma_b(fu, fu)) \\ &\leq \phi(N(u, u)) \leq \phi(\sigma_b(u, u)), \end{aligned} \tag{3.31}$$

where

$$N(u, u) = \max \left\{ \sigma_b(u, u), \sigma_b(u, u), \sigma_b(u, u), \frac{\sigma_b(u, u) + \sigma_b(u, u)}{4s} \right\} = \sigma_b(u, u).$$

From inequality (3.31) it follows that $\sigma_b(u, u) = 0$ (also $\sigma_b(v, v) = 0$).

Again we have

$$\begin{aligned} \psi(qs^p \sigma_b(u, v)) &= \psi(qs^p \sigma_b(fu, fv)) \leq \psi(\alpha(u, v) \sigma_b(fu, fv)) \\ &\leq \phi(N(u, v)) \leq \phi(\sigma_b(u, v)), \end{aligned} \tag{3.32}$$

where $N(u, v) = \sigma_b(u, v)$.

Inequality (3.32) implies that $\sigma_b(u, v) = 0$. Therefore $u = v$, and the fixed point is unique. □

Remark 3.14 Our theorem extends Theorems 2.1, 2.2, and 2.7 of Aydi et al. [9].

By taking $\phi(t) = \psi(t) - \varphi(t)$, where $\varphi \in \Psi$, in Theorem 3.13 we obtain the following result.

Corollary 3.15 *Let (X, σ_b) be a complete b -metric-like space with parameter $s \geq 1$, let $f : X \rightarrow X$ be a self-mapping, and let $\alpha : X \times X \rightarrow [0, \infty)$. Suppose that the following conditions are satisfied:*

- (i) f is an α_{qs^p} -admissible mapping;
- (ii) there exist functions $\psi, \varphi \in \Psi$ such that

$$\psi(\alpha(x, y)\sigma_b(fx, fy)) \leq \psi(N(x, y)) - \varphi(N(x, y));$$

- (iii) there exists $x_0 \in X$ such that $\alpha(x_0, fx_0) \geq qs^p$;
- (iv) either f is continuous, or property H_{qs^p} is satisfied.

Then f has a fixed point $x \in X$. Moreover, f has a unique fixed point if property U_{qs^p} is satisfied.

Remark 3.16 This corollary extends Theorems 3 and 4 of Roshan et al. [25].

By taking $\psi(t) = t$ and $\phi(t) = \beta(t)t$ where $\beta \in \mathbb{S}$ is as in Theorem 3.13, we obtain the following result.

Corollary 3.17 *Let (X, σ_b) be a complete b -metric-like space with parameter $s \geq 1$, let $f : X \rightarrow X$ be a self-mapping, and let $\alpha : X \times X \rightarrow [0, \infty)$. Suppose that the following conditions are satisfied:*

- (i) f is an α_{qs^p} -admissible mapping;
- (ii) there exist functions $\psi, \varphi \in \Psi$ such that

$$\psi(\alpha(x, y)\sigma_b(fx, fy)) \leq \beta(N(x, y))(N(x, y));$$

- (iii) there exists $x_0 \in X$ such that $\alpha(x_0, fx_0) \geq qs^p$;
- (iv) either f is continuous, or property H_{qs^p} is satisfied.

Then f has a fixed point $x \in X$. Moreover, f has a unique fixed point if property U_{qs^p} is satisfied.

If we take $\psi(t) = t$ in Theorem 3.13, then we get the following result.

Corollary 3.18 *Let (X, σ_b) be a complete b -metric-like space with parameter $s \geq 1$, let $f : X \rightarrow X$ be a self-mapping, and let $\alpha : X \times X \rightarrow [0, \infty)$. Suppose that the following conditions are satisfied:*

- (i) f is an α_{qs^p} -admissible mapping;
- (ii) there exist functions $\varphi \in \Psi$ such that

$$\alpha(x, y)\sigma_b(fx, fy) \leq \varphi(N(x, y));$$

- (iii) there exists $x_0 \in X$ such that $\alpha(x_0,fx_0) \geq qs^p$;
- (iv) either f is continuous, or property H_{qs^p} is satisfied.

Then f has a fixed point $x \in X$. If property U_{qs^p} is satisfied, then f has a unique fixed point.

Remark 3.19 Corollary 3.18 generalizes and extends Theorem 2.7 of Samet et al. [8].

Corollary 3.20 Let (X, σ_b) be a complete b -metric-like space with parameter $s \geq 1$, let $f : X \rightarrow X$ be a self-mapping, and let $\alpha : X \times X \rightarrow [0, \infty)$. Suppose that the following conditions are satisfied:

- (i) f is an α_{qs^p} -admissible mapping;
- (ii) there exists a function $\varphi \in \Psi$ such that

$$\alpha(x, y)\sigma_b(fx, fy) \leq N(x, y) - \varphi(N(x, y));$$

- (iii) there exists $x_0 \in X$ such that $\alpha(x_0,fx_0) \geq qs^p$;
- (iv) either f is continuous, or property H_{qs^p} is satisfied.

Then f has a fixed point $x \in X$. Moreover, f has a unique fixed point if property U_{qs^p} is satisfied.

Proof It follows from Corollary 3.15 by taking $\psi(t) = t$. □

Remark 3.21 Corollary 3.20 generalizes Theorem 2.7 of Harandi [5].

Corollary 3.22 Let (X, σ_b) be a complete b -metric like space with parameter $s \geq 1$, and let f, g be two selfmaps of X with $\psi \in \Psi, \varphi \in \Phi$ satisfying the condition

$$\psi(\alpha_{qs^p}\sigma_b(fx, fy)) \leq \lambda\psi(M(x, y))$$

for all $x, y \in X$, where $M(x, y)$ is defined in (3.15), and $q > 1$. Then f and g have a unique common fixed point in X .

Proof In Theorem 3.13, take $\varphi(t) = \lambda\psi(t)$ where $0 < \lambda < 1$. □

Corollary 3.23 Let (X, σ_b) be a complete b -metric-like space with parameter $s \geq 1$, and let $f : X \rightarrow X$ be a self-mapping such that, for all $x, y \in X$ and any arbitrary coefficient $p \geq 1$,

$$qs^p\sigma_b(fx, fy) \leq k \max \left\{ \sigma_b(x, y), \sigma_b(x, fx), \sigma_b(y, fy), \frac{\sigma_b(x, fy) + \sigma_b(y, fx)}{4s} \right\},$$

where $k \in (0, 1)$. Then f has a unique fixed point.

Proof It follows from Corollary 3.15 by taking $\alpha(x, y) = qs^p, \psi(t) = t$, and $\varphi(t) = (1 - k)t$ for all $t \in [0, \infty)$ and $k \in (0, 1)$. □

Remark 3.24 It is clear that we can derive several corresponding results by replacing the b -metric-like space with some other spaces such as a b -metric space, a metric space, a metric-like space, and a partial metric space. Conditions (3.1) and (3.12) are more general

than the analogues in the previous literature, and theorems related to those conditions have a more general character because of the parameter s and arbitrary coefficients q, p .

3.1 Application

In this section, we will use Corollary 3.23 to show that there is a solution to the following integral equation:

$$x(t) = \int_0^T G(t, r, x(r)) \, dr. \tag{3.33}$$

Let $X = C([0, T])$ be the set of real continuous functions defined on $[0, T]$ for $T > 0$.

We endow X with

$$\sigma_b(x, y) = \max_{t \in [0, 1]} (|x(t)| + |y(t)|)^m \quad \text{for all } x, y \in X.$$

It is evident that (X, σ_b) is a complete b -metric-like space with parameter $s = 2^{m-1}$ with $m > 1$.

Consider the mapping $f : X \rightarrow X$ defined by $fx(t) = \int_0^T G(t, r, x(r)) \, dr$.

Theorem 3.25 *Consider equation (3.33) and suppose that*

- (a) $G : [0, T] \times [0, T] \times R \rightarrow R^+ = [0, \infty)$ (that is, $G(t, r, x(r)) \geq 0$) is continuous;
- (b) there exists a continuous $\gamma : [0, T] \times [0, T] \rightarrow R$;
- (c) $\sup_{t \in [0, T]} \int_0^T \gamma(t, r) \, dr \leq 1$;
- (d) there exists a constant $L \in (0, 1)$ such that, for all $(t, r) \in [0, T]^2$ and $x, y \in R$,

$$|G(t, r, x(r)) + G(t, r, y(r))| \leq \left(\frac{L}{s^3}\right)^{\frac{1}{m}} \gamma(t, r) (|x(r)| + |y(r)|).$$

Then the integral equation (3.33) has a unique solution in $x \in X$.

Proof For $x, y \in X$, from conditions (c) and (d), for all t , we have

$$\begin{aligned} q s \sigma_b(fx(t), fy(t)) &= q s (|fx(t)| + |fy(t)|)^m \\ &= q s \left(\left| \int_0^T G(t, r, x(r)) \, dr \right| + \left| \int_0^T G(t, r, y(r)) \, dr \right| \right)^m \\ &\leq q s \left(\int_0^T |G(t, r, x(r))| \, dr + \int_0^T |G(t, r, y(r))| \, dr \right)^m \\ &\leq q s \left(\int_0^T \left(\frac{L}{s^3}\right)^{\frac{1}{m}} \gamma(t, r) ((|x(r)| + |y(r)|)^m)^{\frac{1}{m}} \, dr \right)^m \\ &\leq q s \left(\int_0^T \left(\frac{L}{s^3}\right)^{\frac{1}{m}} \gamma(t, r) \sigma_b^{\frac{1}{m}}(x(r), y(r)) \, dr \right)^m \\ &\leq q s \cdot \frac{L}{s^3} \sigma_b(x(r), y(r)) \left(\int_0^T \gamma(t, r) \, dr \right)^m \\ &= \frac{qL}{s^2} \sigma_b(x(r), y(r)) \left(\int_0^T \gamma(t, r) \, dr \right)^m \\ &\leq \frac{qL}{s^2} \sigma_b(x(r), y(r)), \end{aligned}$$

which implies that

$$\begin{aligned} s\sigma_b(fx(t), fy(t)) &\leq \frac{L}{s^2} \sigma_b(x(r), y(r)) \\ &\leq k \max \left\{ \sigma_b(x, y), \sigma_b(x, Tx), \sigma_b(y, Ty), \frac{\sigma_b(x, Ty) + \sigma_b(y, Tx)}{4s} \right\}, \end{aligned}$$

where $k = L/s^2 \in (0, 1)$.

Therefore, all of the conditions of Corollary 3.23 are satisfied, and, as a result, the mapping f has a unique fixed point in X , which is a solution of the integral equation (3.33). \square

4 Conclusions

In this paper, the class of α_{qs^p} -admissible mappings is introduced in a larger structure such as a b -metric-like space. Some fixed point results dealing with $(\alpha - \psi, \phi)$ contractions are obtained, and they cover and unify a huge number of published results in the related literature.

Acknowledgements

The authors gratefully acknowledge all the remarks and comments made by the anonymous referees.

Competing interests

The authors declare that they have no competing interests.

Authors' contributions

All authors contributed equally and significantly in writing this paper. All authors read and approved the final manuscript.

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Received: 15 August 2017 Accepted: 2 November 2017 Published online: 06 December 2017

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